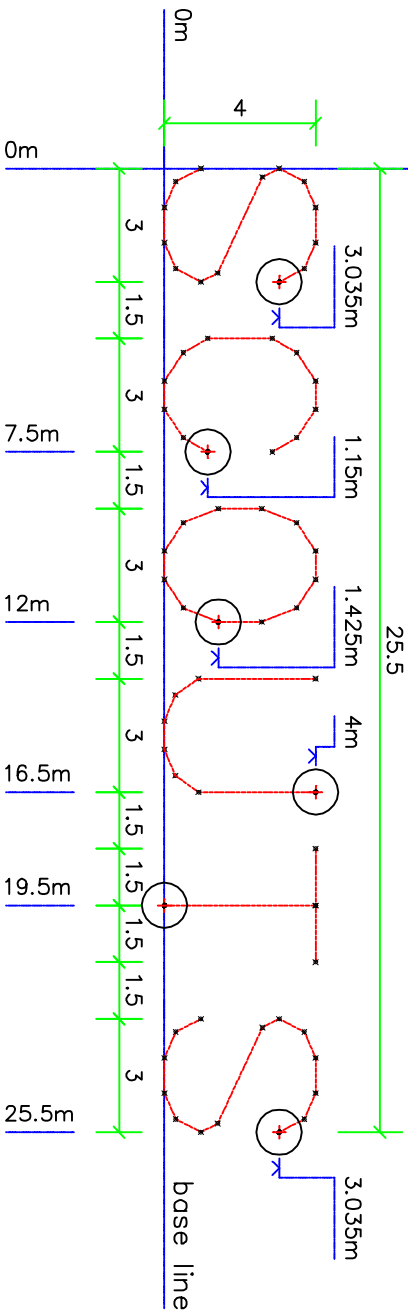




Alphabet Micro Navigation

All dimensions, setting out and bearings are based on a base line running from East to West. All dimensions shown are in metres (m), a typically capital letter is 4m high x 3m wide, a lowercase letter is 2.7m high x 2.5m wide and each letter has a 1.5m spacer between each letter. This is important if you want to set out your own words / sentences. Each letter is set out on a separate sheet so it would be easy to give a patrol a word to set out or an individual scout may be given the setting out to perform each letter.



The word "SCOUTS" 4m tall 25.5m wide, as a guide it took one leader approximately 30 minutes to set out the setting out / starting points for each letter which are ringed. So a little time will be required before you ask your scouts to perform the micro navigation.

Each letter is made up of several points which the scouts are required to mark. Markers could vary depending what you have available some ideas could be pebbles, flags, tent pegs, glow sticks (if at night) or beaver scouts but with the later there is no guarantee that the markers will stay where they been placed. To enable the scouts to visualise the letters better paracord or reflective gylines (at night) could be used to join up points (dot to dot).

Other ideas where alphabet micro navigation could be used are: –

- To write the group name.
- To write a fun message.
- As a base on a hike the scouts could micro navigate the next 6 figure grid reference.
- Scouts name.
- Words around the theme of scouting.

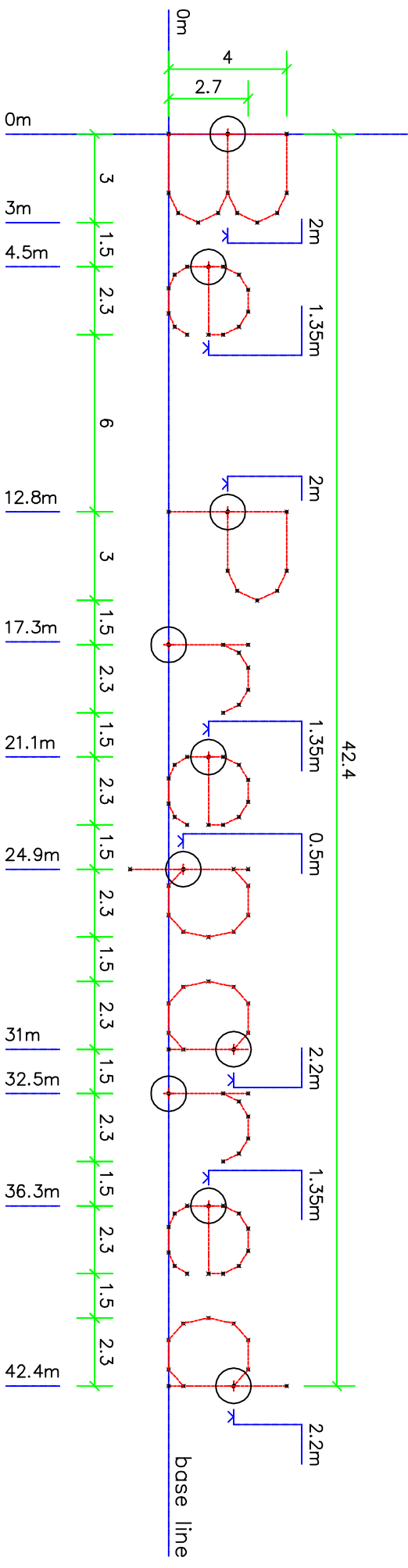
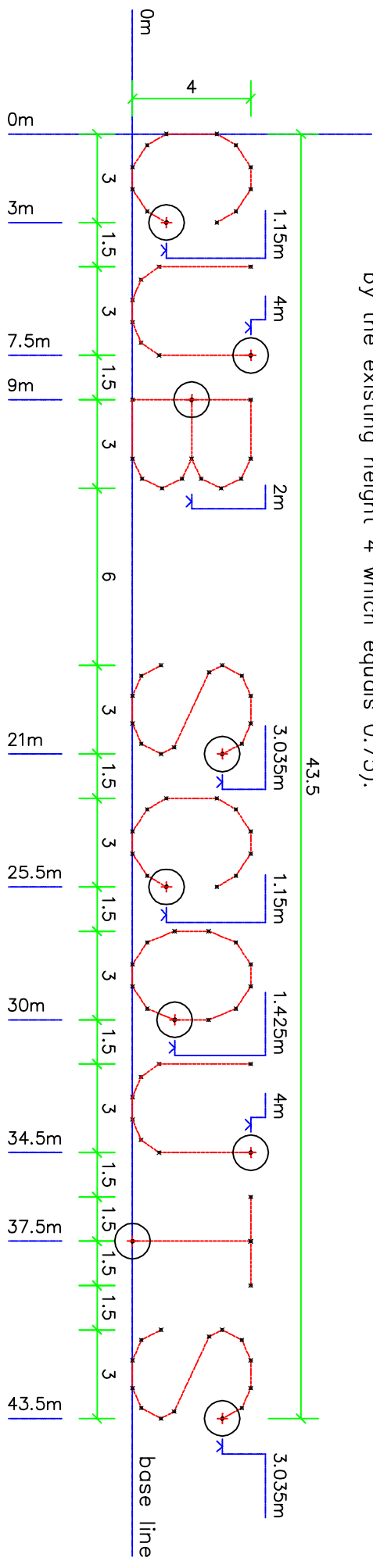
Some of these examples are shown in the following pages. The main idea of this is to have fun while teaching the scouts to be able to use a compass more confidently.

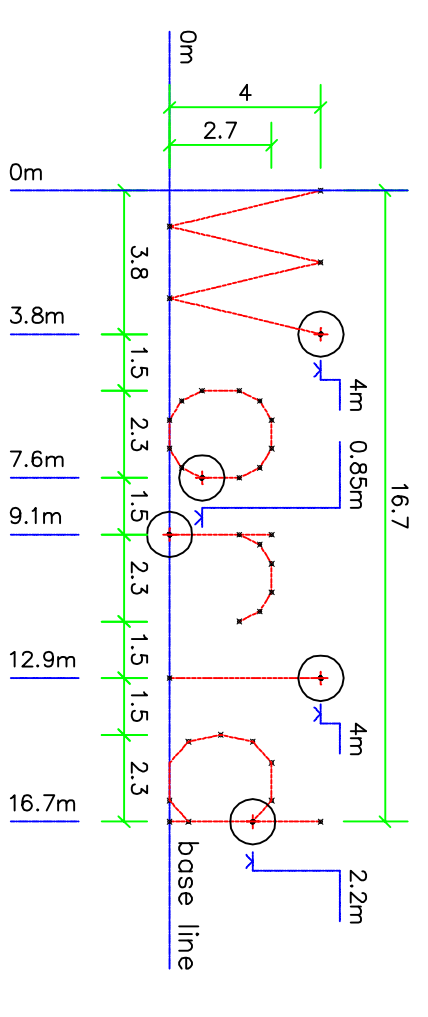
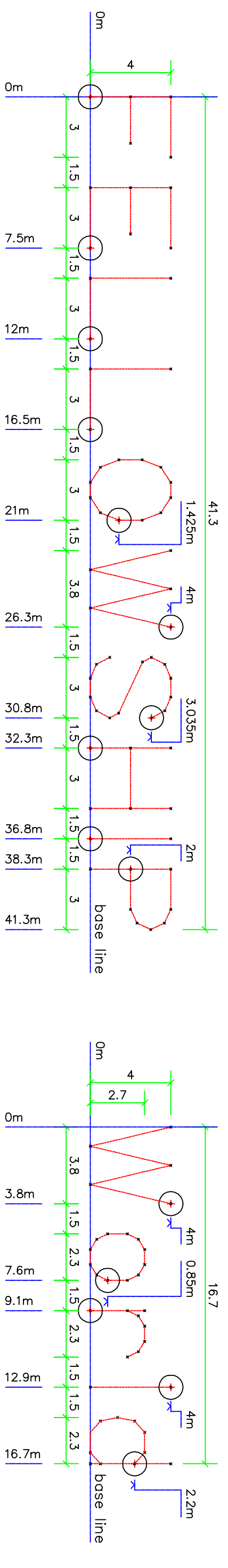
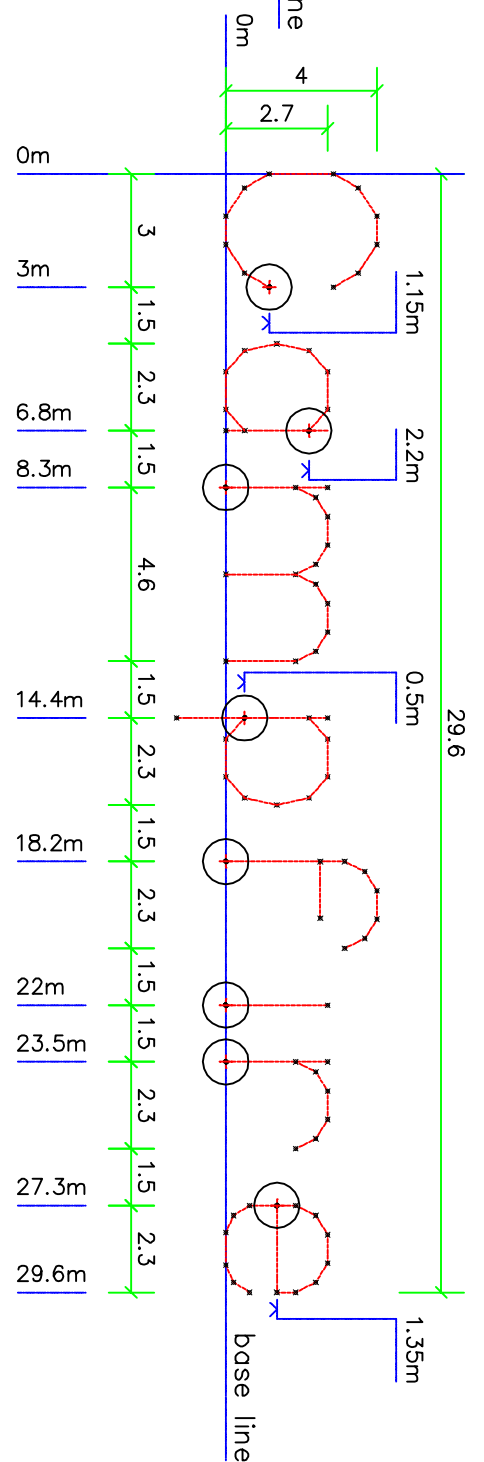
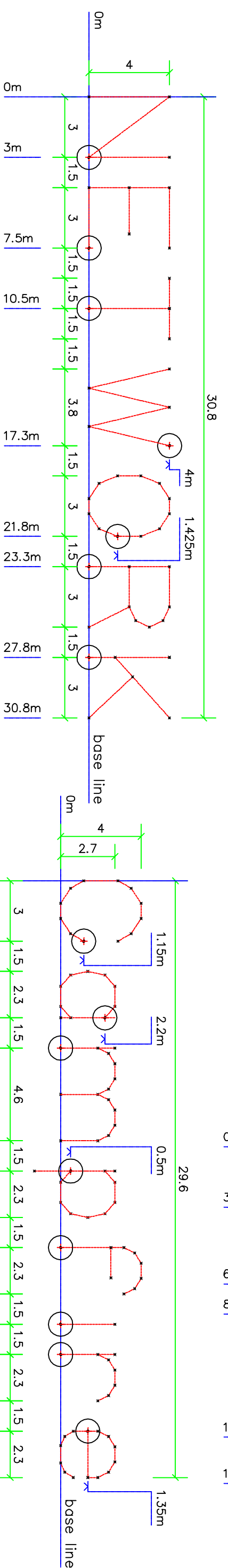
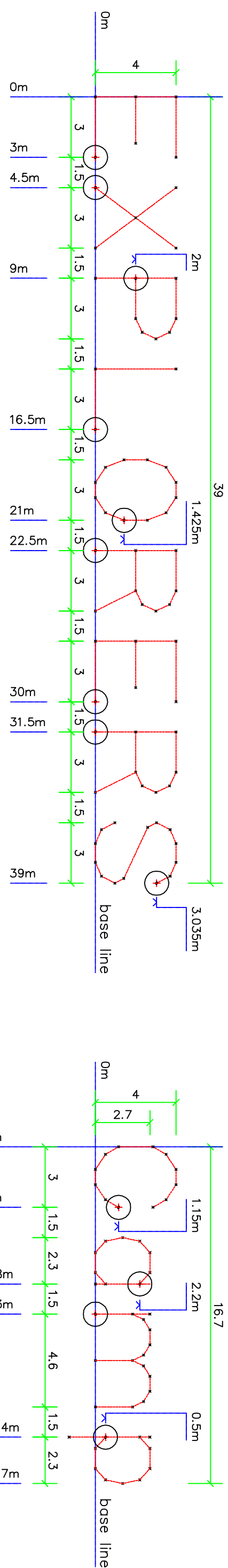
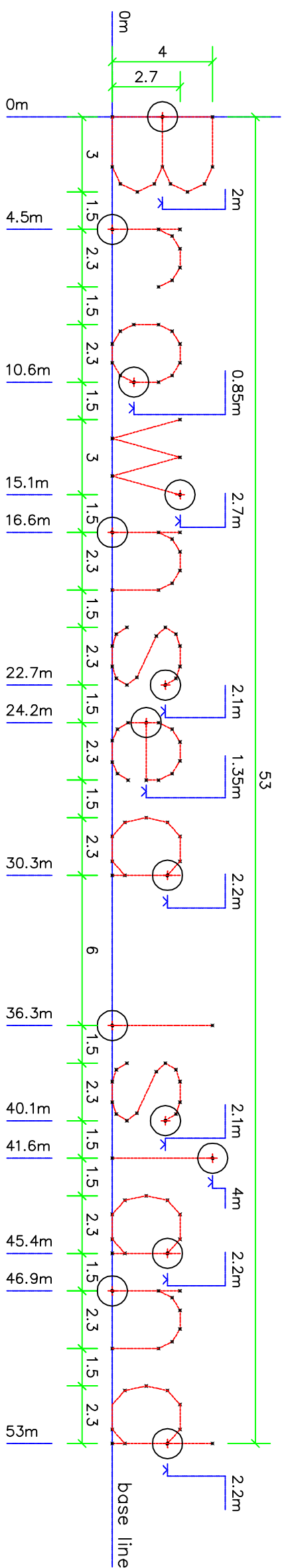
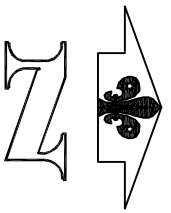
Depending on how much fun you want this to be you could either issue them a tape measure for the dimensions or not. Of course more fun when not as not many scouts know what exactly a metre looks like and therefore when you have individuals working on letters to make one word the final word can be as you would imagine a little bit untidy.

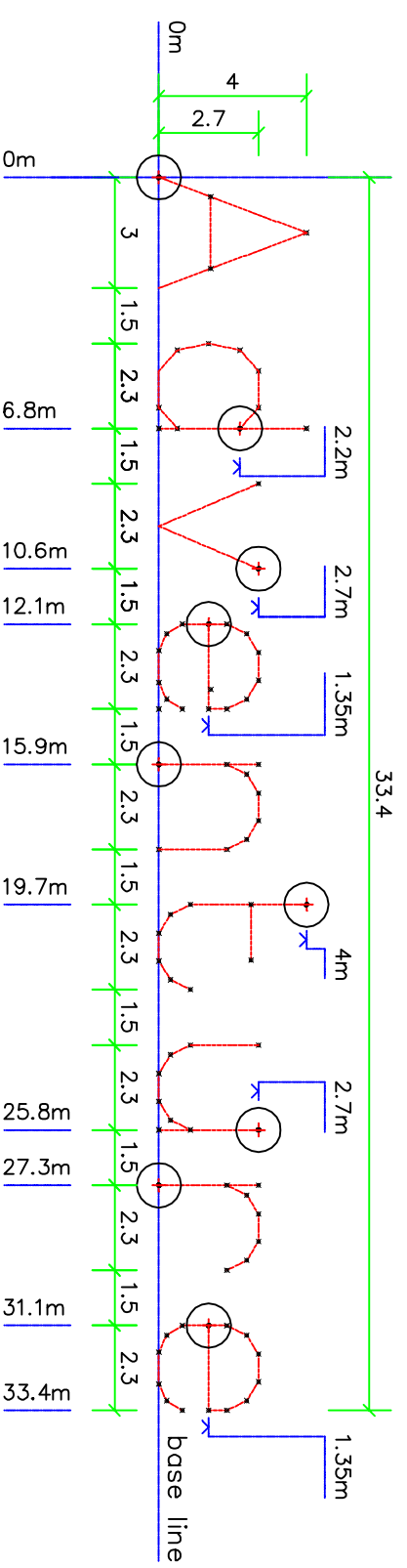
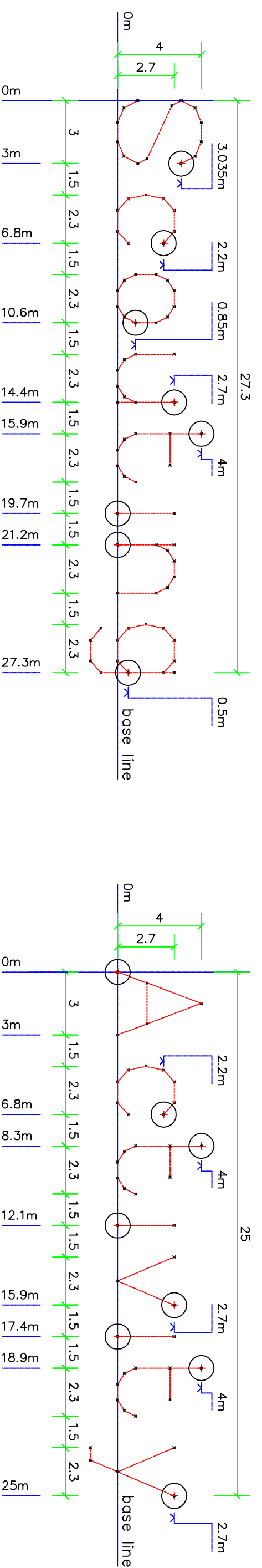
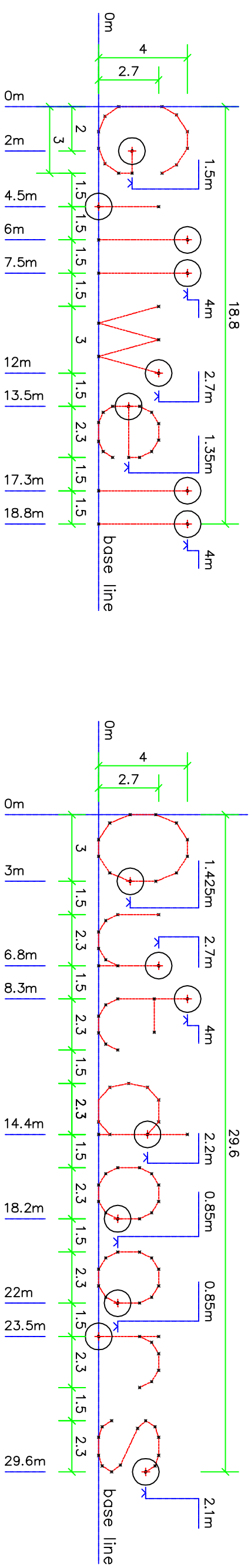
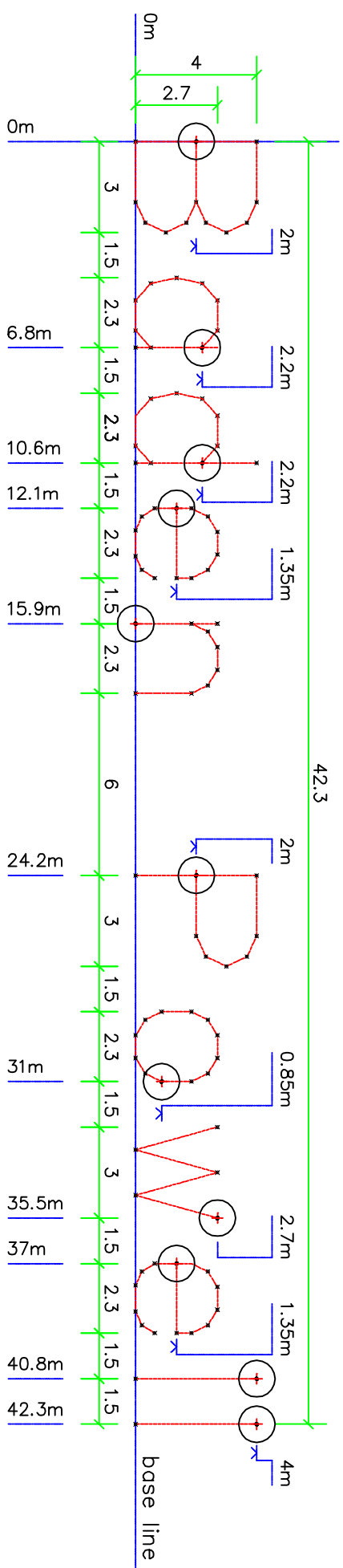
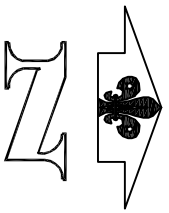


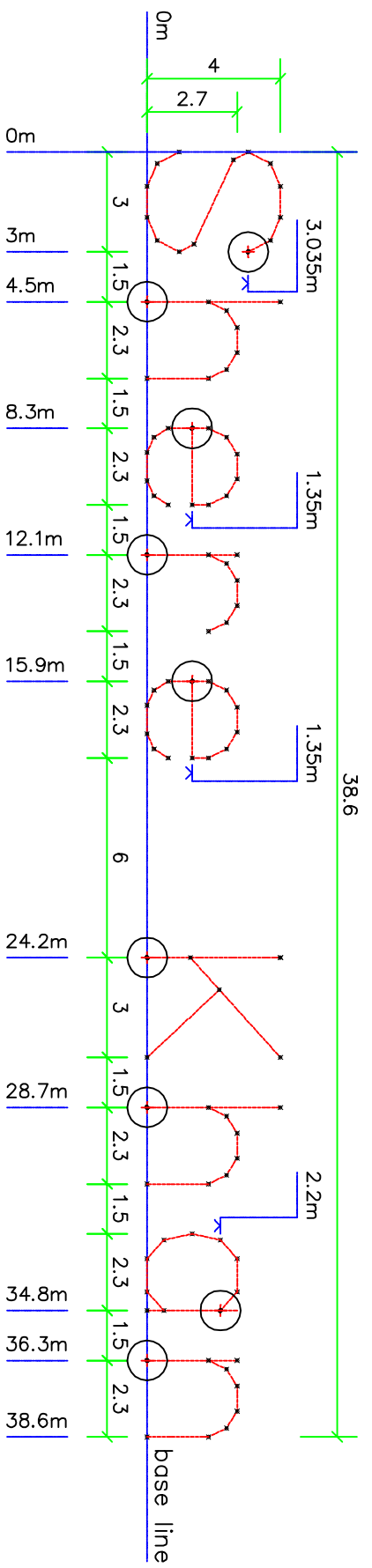
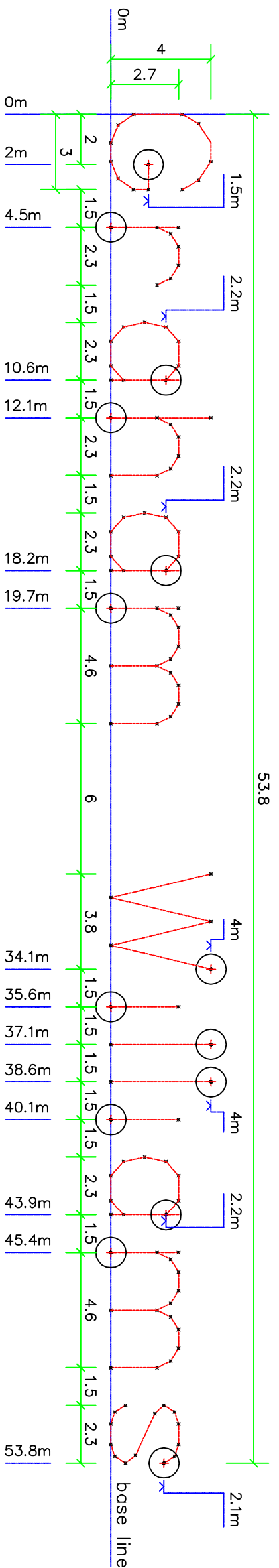
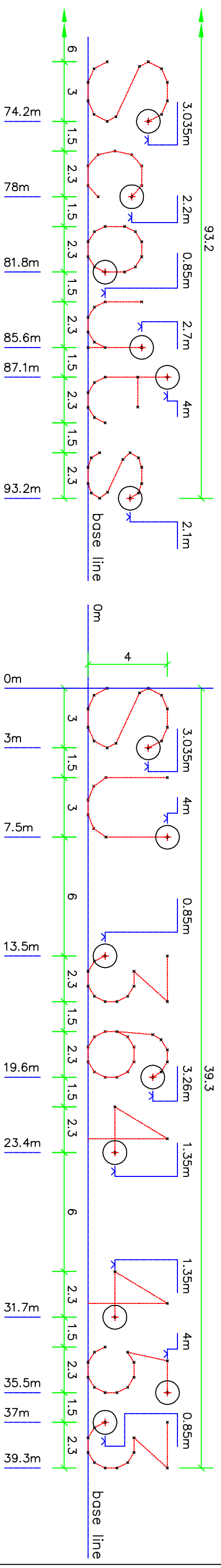
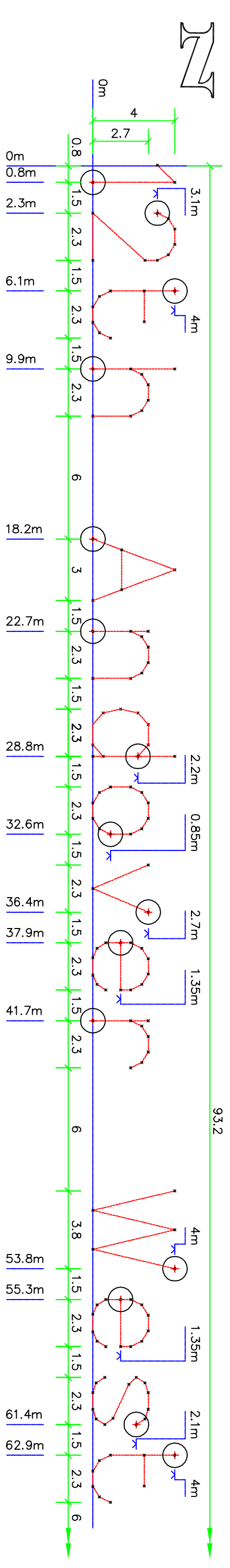
Alphabet Micro Navigation

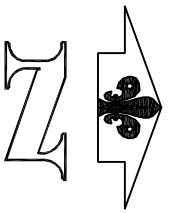
If you want to make the letter shorter or taller just scale the dimensions either up or down for example if you want 3m high letters instead of 4m then times all dimensions by 0.75 and that will scale all letters proportionally. (On a calculator always start with the new height of the lettering that you require 3 divide that by the existing height 4 which equals 0.75).



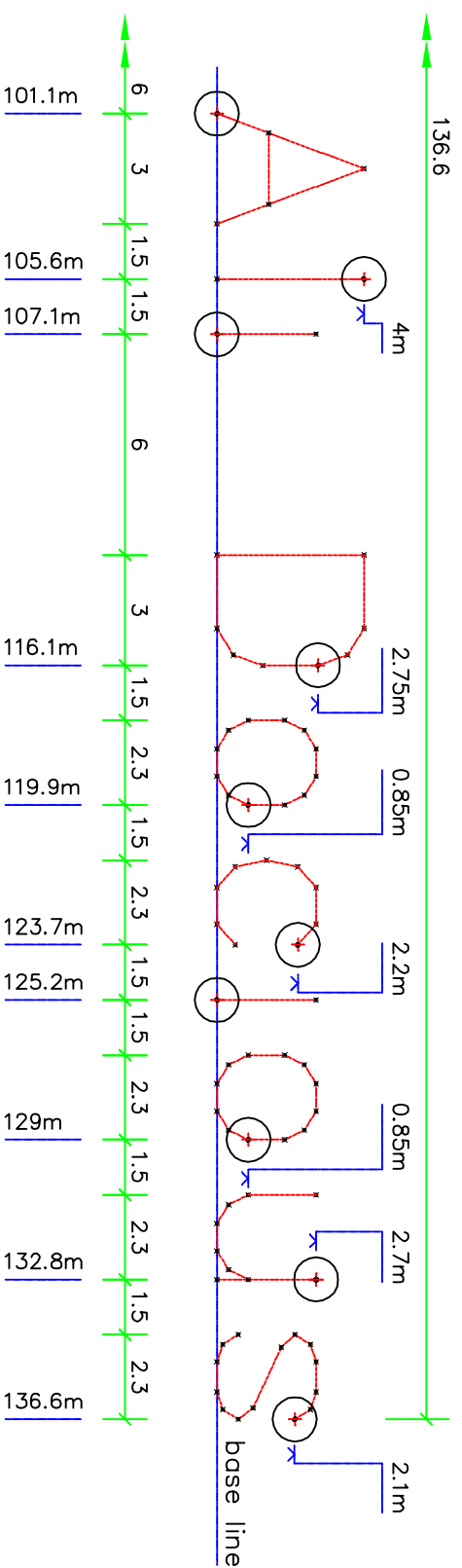
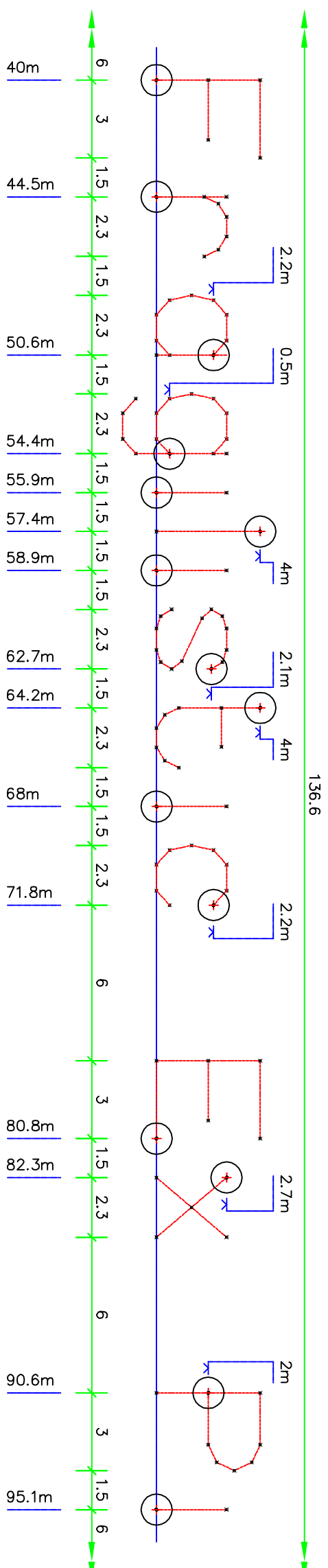
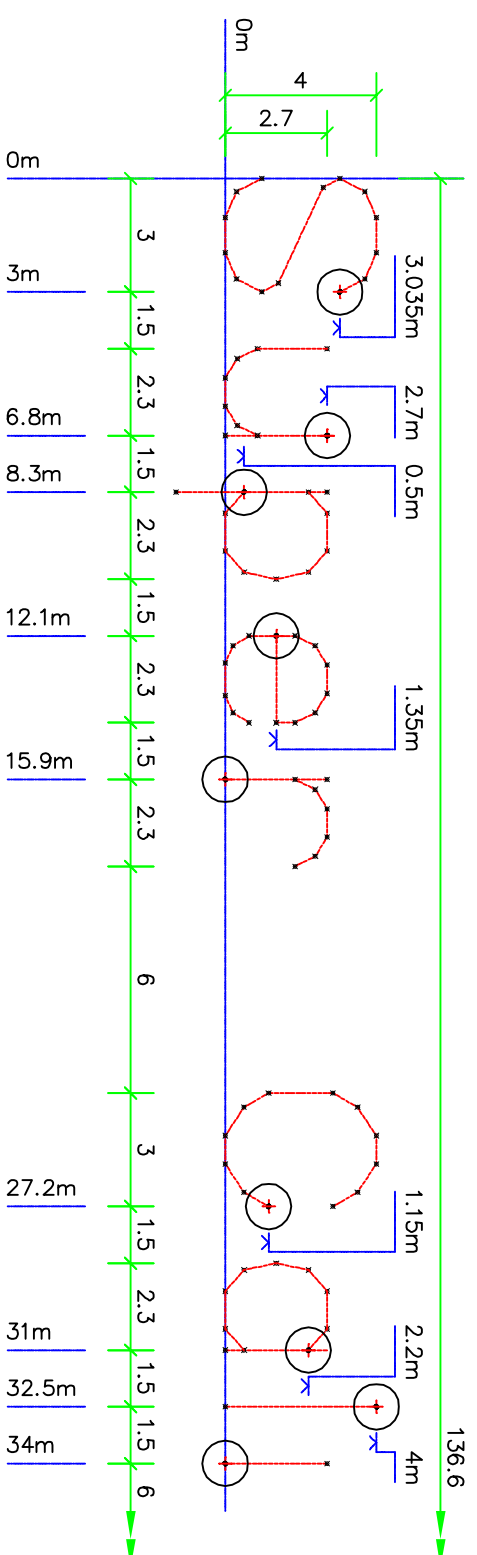


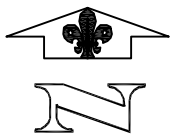






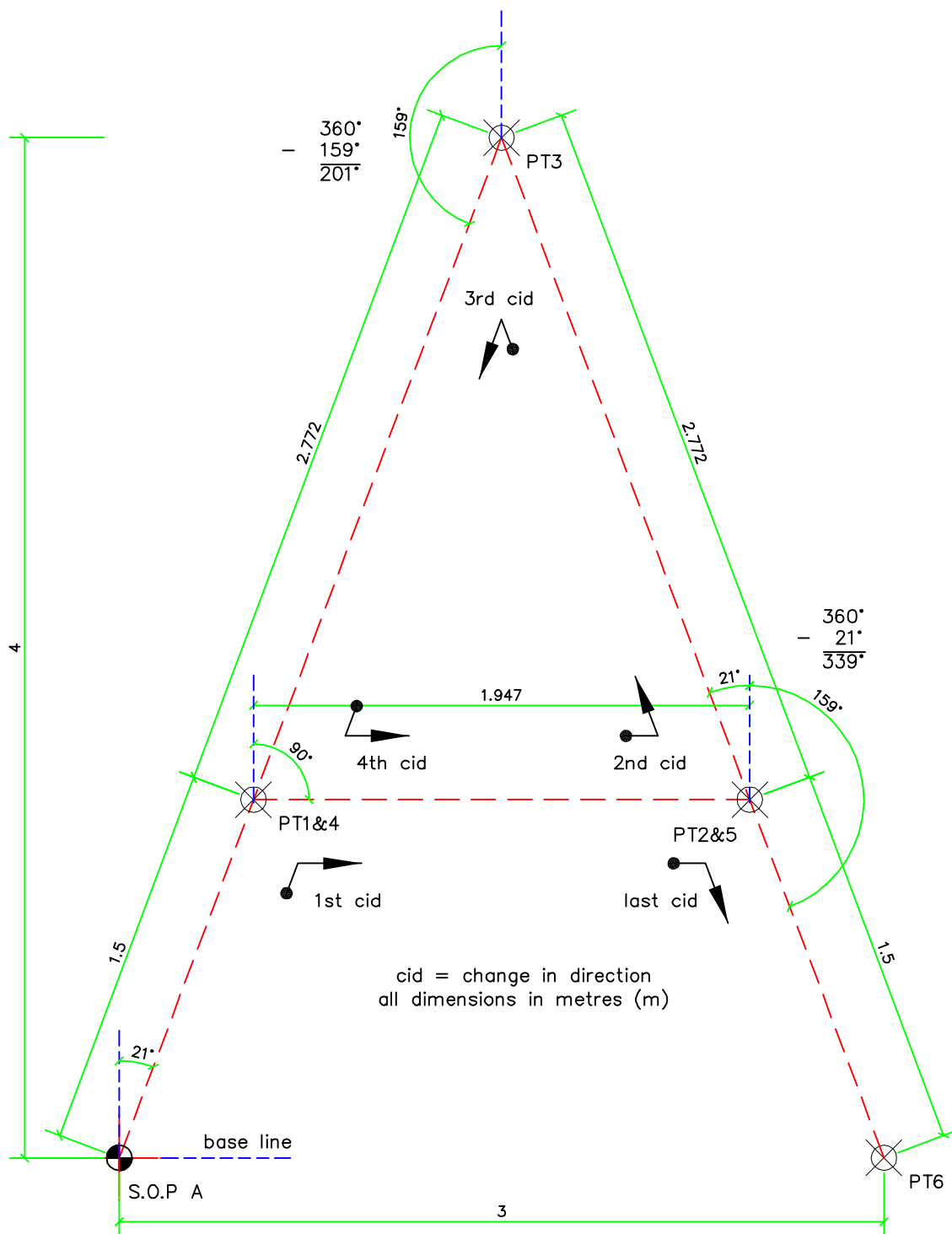
Alphabet Micro Navigation (one for the explorers)

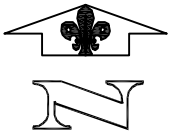




Micro navigation – letter A

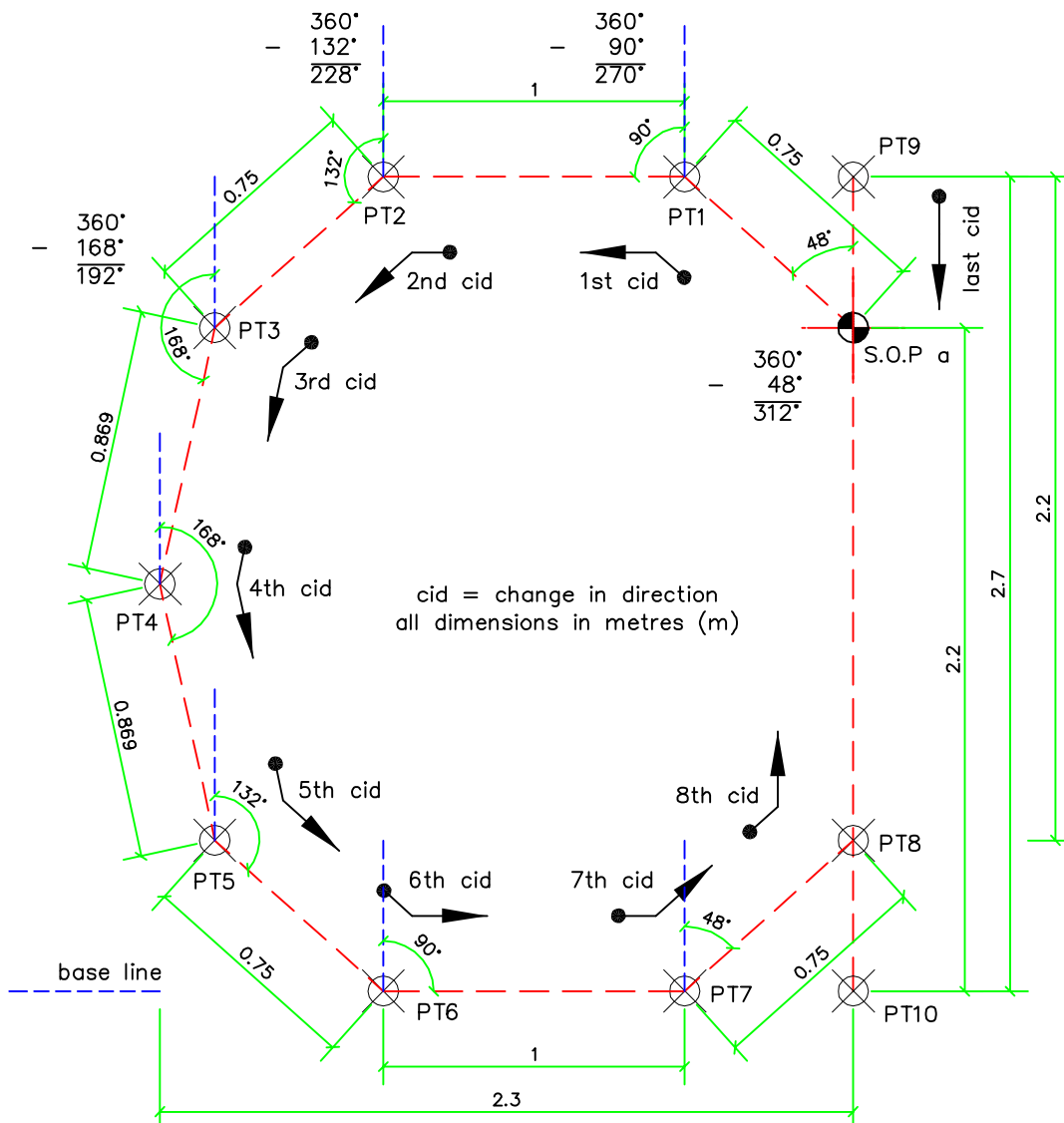
- From S.O.P A walk 1.5m on a bearing of 21° and mark the location.
- From PT1 Walk 1.9m on a bearing of 90° and mark the location.
- From PT2 Walk 2.8m on a bearing of 339° and mark the location.
- From PT3 Walk 2.8m on a bearing of 201° .
- From PT4 Walk 1.9m on a bearing of 90° .
- From PT5 Walk 1.5m on a bearing of 159° and mark the location and finish.

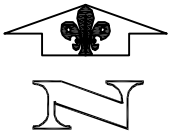




Micro navigation – letter a

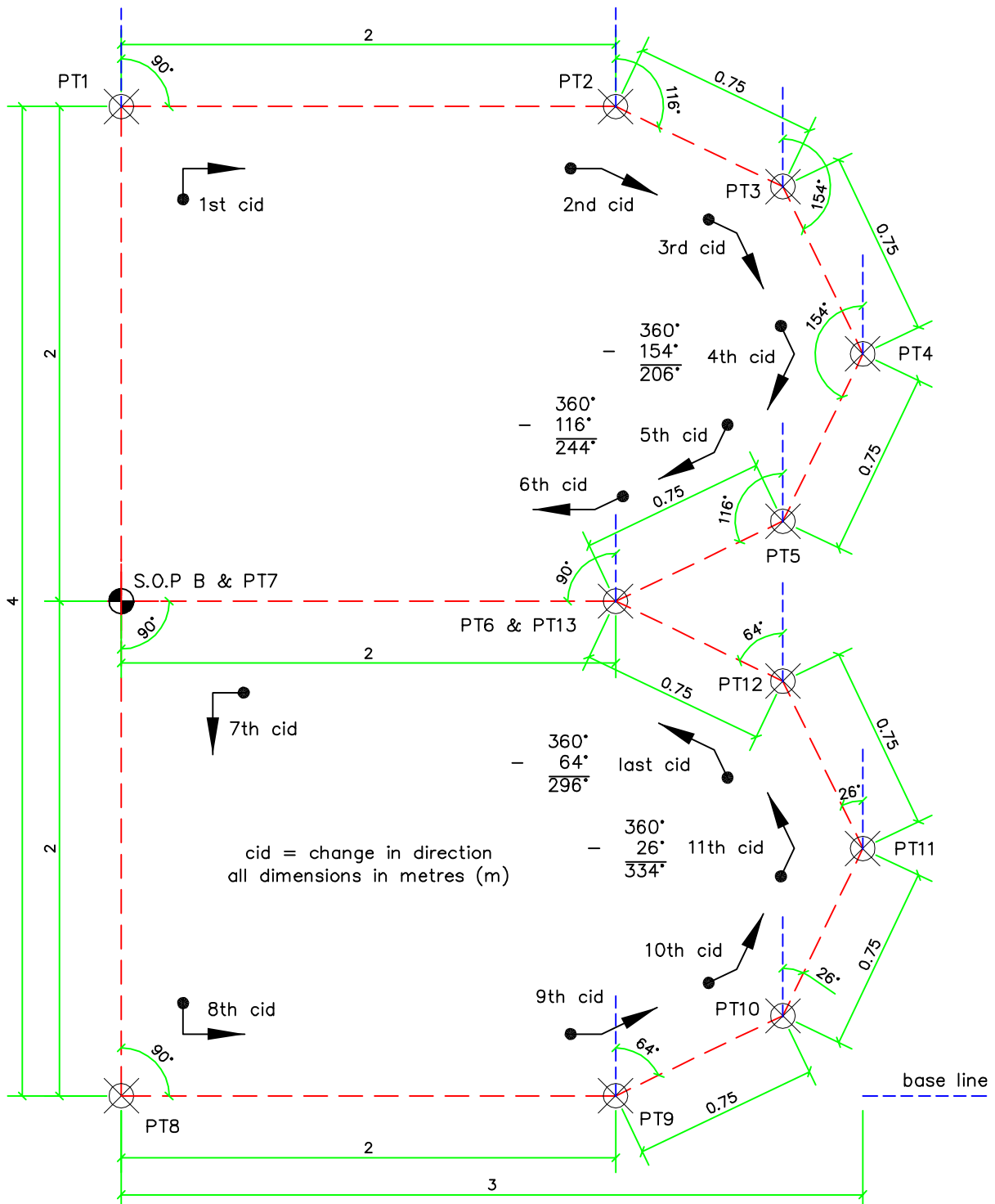
- From S.O.P a walk 0.75m on a bearing of 312° and mark the location.
- From PT1 Walk 1m on a bearing of 270° and mark the location.
- From PT2 Walk 0.75m on a bearing of 228° and mark the location.
- From PT3 Walk 0.9m on a bearing of 192° and mark the location.
- From PT4 Walk 0.9m on a bearing of 168° and mark the location.
- From PT5 Walk 0.75m on a bearing of 132° and mark the location.
- From PT6 Walk 1m on a bearing of 90° and mark the location.
- From PT7 Walk 0.75m on a bearing of 48° and mark the location.
- From PT8 Walk 2.2m on a bearing of 0° and mark the location.
- From PT9 Walk 2.7m on a bearing of 180° and mark the location and finish.

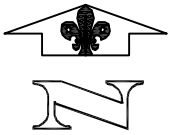




Micro navigation – letter B

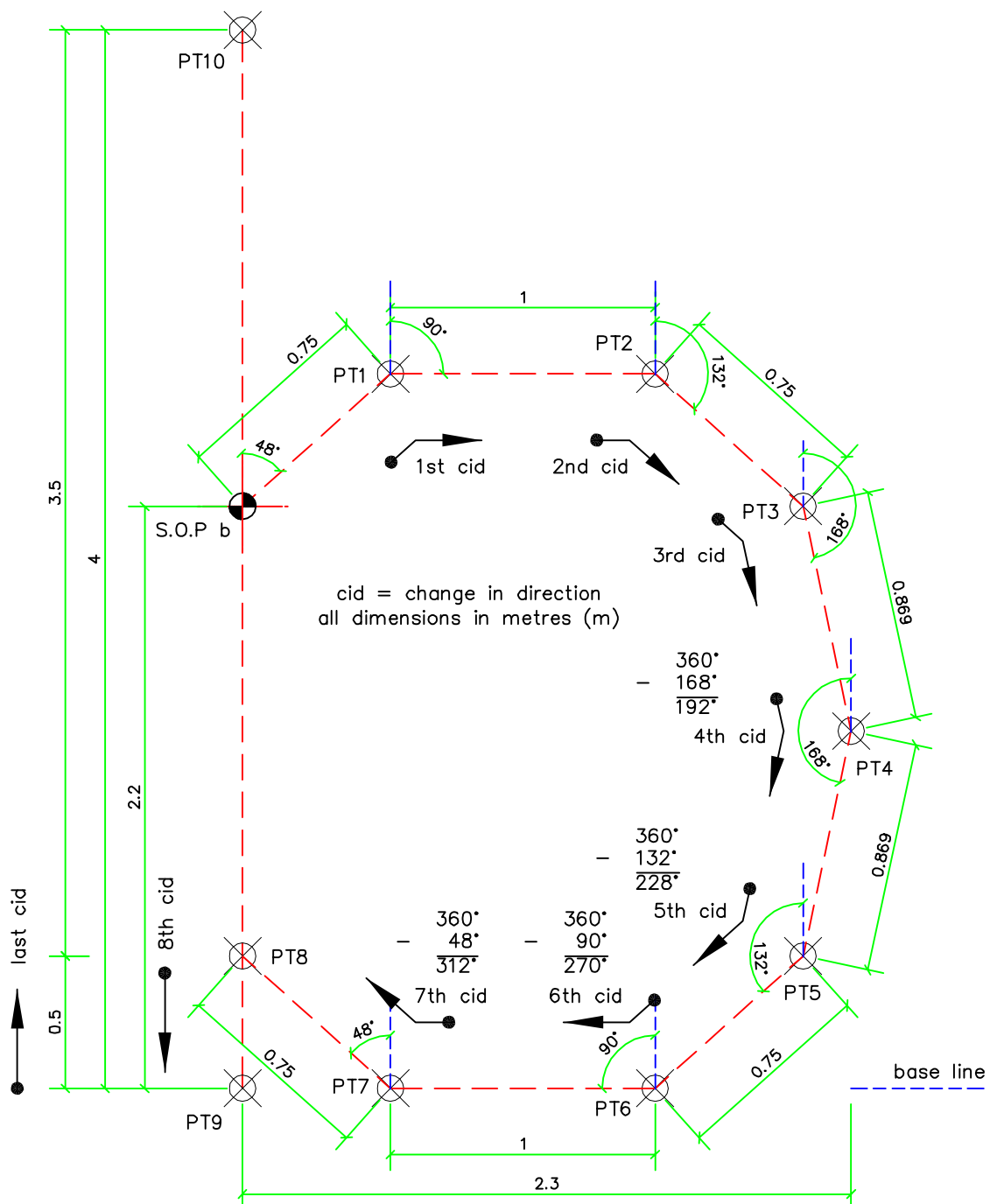
- From S.O.P B walk 2m on a bearing of 0° and mark the location.
- From PT1 Walk 2m on a bearing of 90° and mark the location.
- From PT2 Walk 0.75m on a bearing of 116° and mark the location.
- From PT3 Walk 0.75m on a bearing of 154° and mark the location.
- From PT4 Walk 0.75m on a bearing of 206° and mark the location.
- From PT5 Walk 0.75m on a bearing of 244° and mark the location.
- From PT6 Walk 2m on a bearing of 270° .
- From PT7 Walk 2m on a bearing of 180° and mark the location.
- From PT8 Walk 2m on a bearing of 90° and mark the location.
- From PT9 Walk 0.75m on a bearing of 64° and mark the location.
- From PT10 Walk 0.75m on a bearing of 26° and mark the location.
- From PT11 Walk 0.75m on a bearing of 334° and mark the location.
- From PT12 Walk 0.75m on a bearing of 296° and finish.

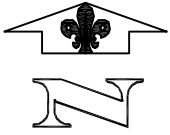




Micro navigation – letter b

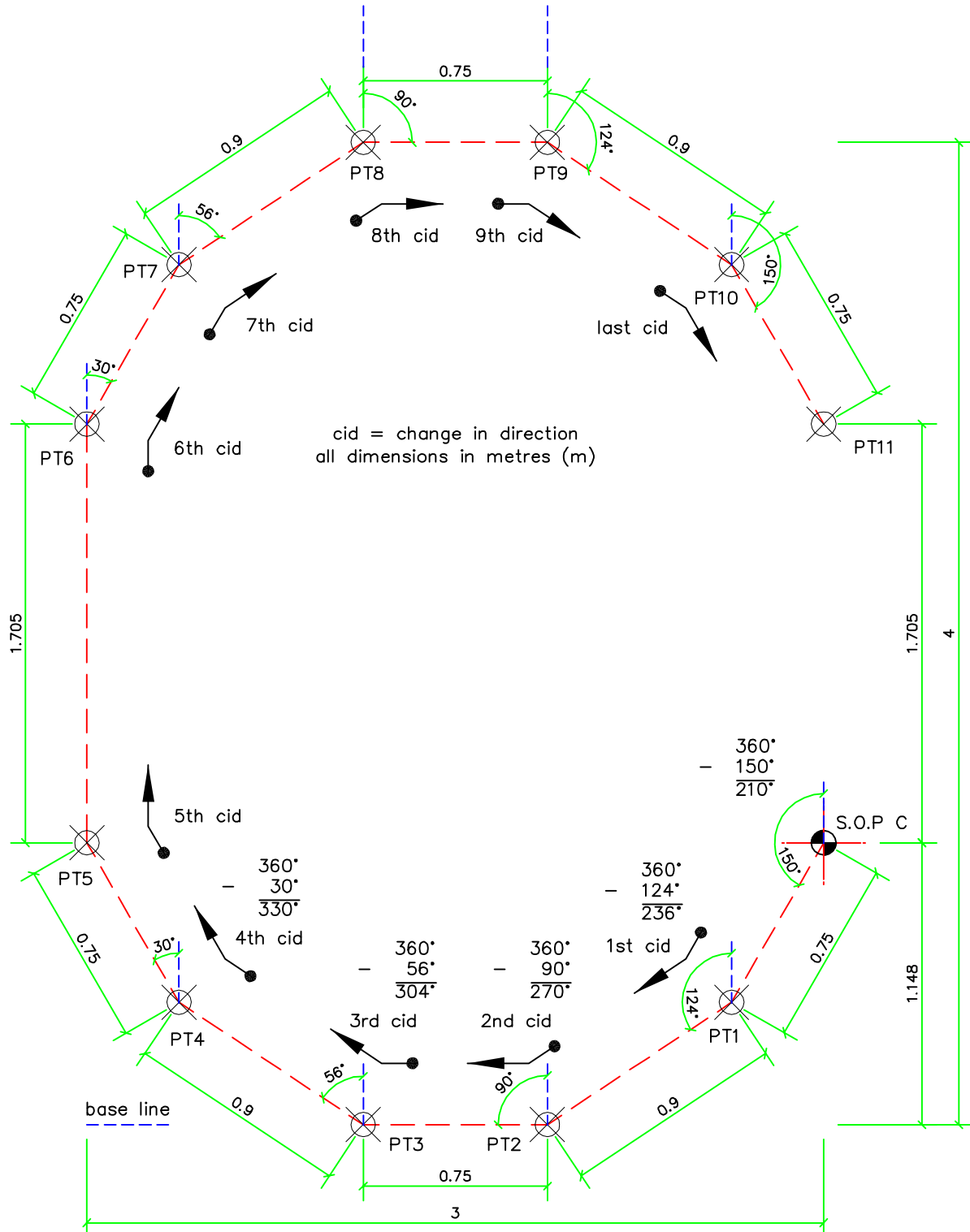
- From S.O.P b walk 0.75m on a bearing of 48° and mark the location.
- From PT1 Walk 1m on a bearing of 90° and mark the location.
- From PT2 Walk 0.75m on a bearing of 132° and mark the location.
- From PT3 Walk 0.9m on a bearing of 168° and mark the location.
- From PT4 Walk 0.9m on a bearing of 192° and mark the location.
- From PT5 Walk 0.75m on a bearing of 228° and mark the location.
- From PT6 Walk 1m on a bearing of 270° and mark the location.
- From PT7 Walk 0.75m on a bearing of 312° and mark the location.
- From PT8 Walk 0.5m on a bearing of 180° and mark the location.
- From PT9 Walk 4m on a bearing of 0° and mark the location and finish.

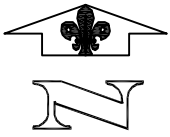




Micro navigation – letter C

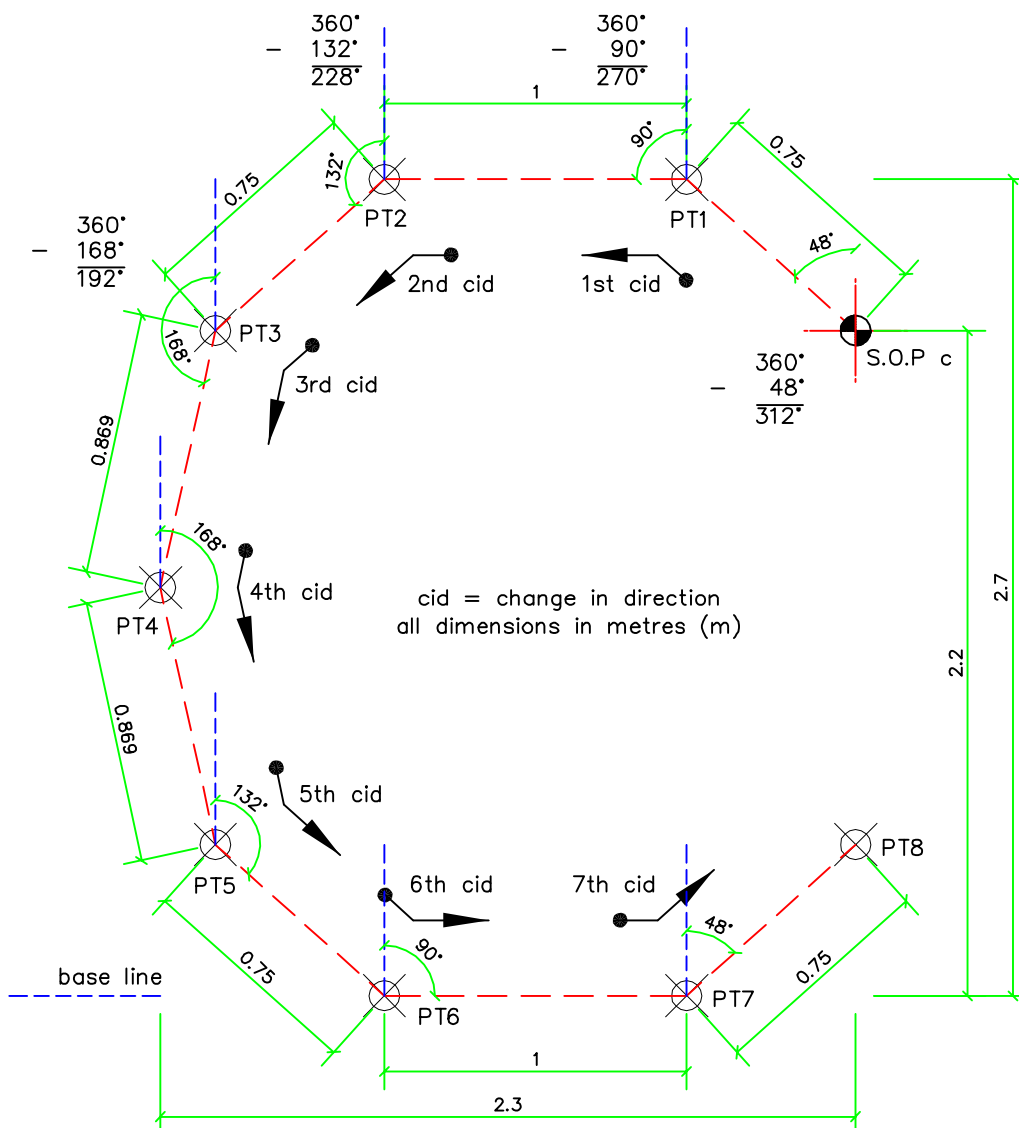
- | | | |
|---|------|------------------------|
| From S.O.P C walk 0.75m on a bearing of | 210° | and mark the location. |
| From PT1 Walk 0.9m on a bearing of | 236° | and mark the location. |
| From PT2 Walk 0.75m on a bearing of | 270° | and mark the location. |
| From PT3 Walk 0.9m on a bearing of | 304° | and mark the location. |
| From PT4 Walk 0.75m on a bearing of | 330° | and mark the location. |
| From PT5 Walk 1.7m on a bearing of | 0° | and mark the location. |
| From PT6 Walk 0.75m on a bearing of | 30° | and mark the location. |
| From PT7 Walk 0.9m on a bearing of | 56° | and mark the location. |
| From PT8 Walk 0.75m on a bearing of | 90° | and mark the location. |
| From PT9 Walk 0.9m on a bearing of | 124° | and mark the location. |
| From PT10 Walk 0.75m on a bearing of | 150° | and mark the location. |
| | | and finish. |

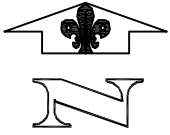




Micro navigation – letter c

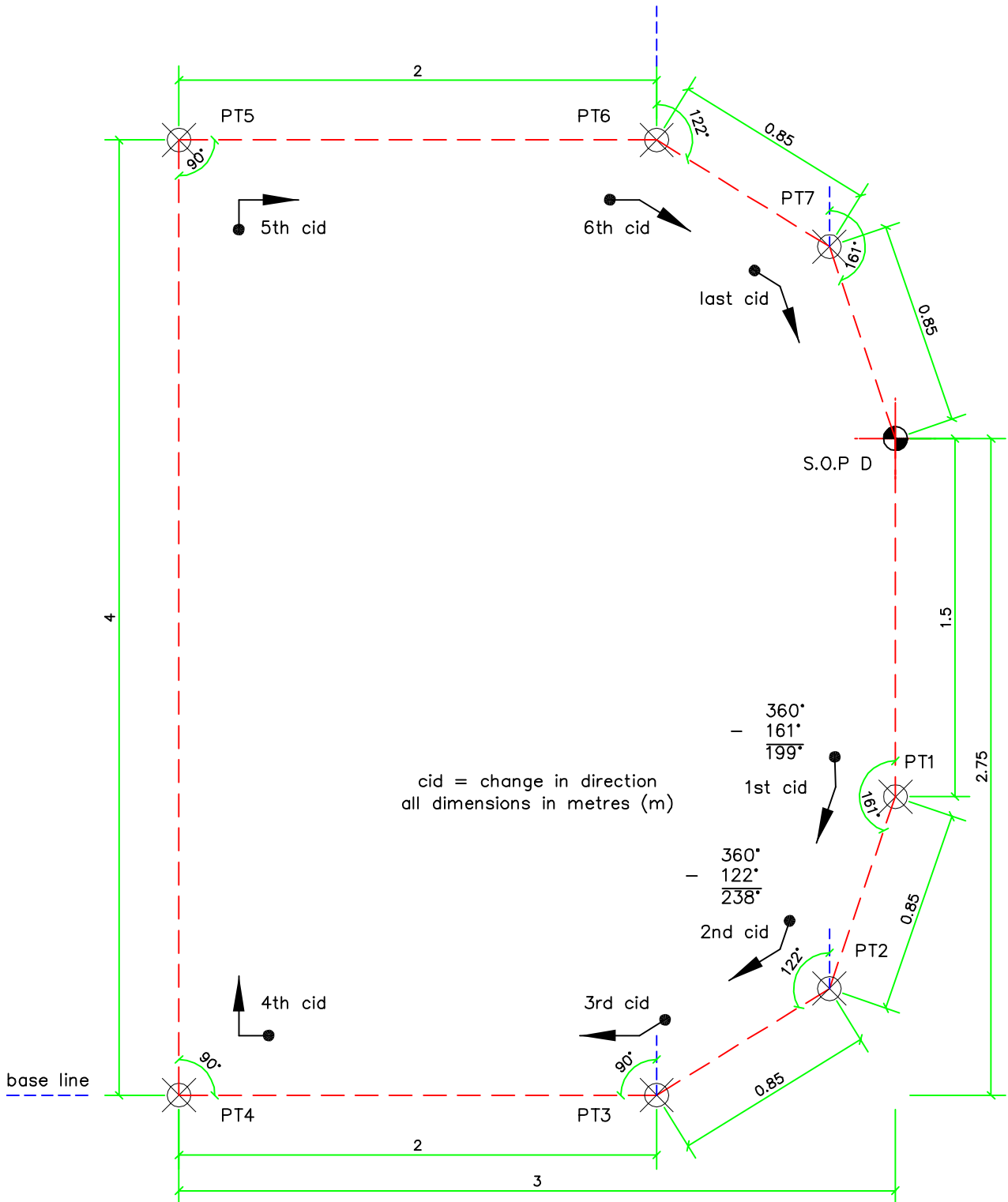
- From S.O.P c walk 0.75m on a bearing of 312° and mark the location.
- From PT1 Walk 1m on a bearing of 270° and mark the location.
- From PT2 Walk 0.75m on a bearing of 228° and mark the location.
- From PT3 Walk 0.9m on a bearing of 192° and mark the location.
- From PT4 Walk 0.9m on a bearing of 168° and mark the location.
- From PT5 Walk 0.75m on a bearing of 132° and mark the location.
- From PT6 Walk 1m on a bearing of 90° and mark the location.
- From PT7 Walk 0.75m on a bearing of 48° and mark the location and finish.

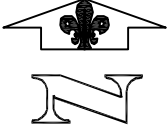




Micro navigation – letter D

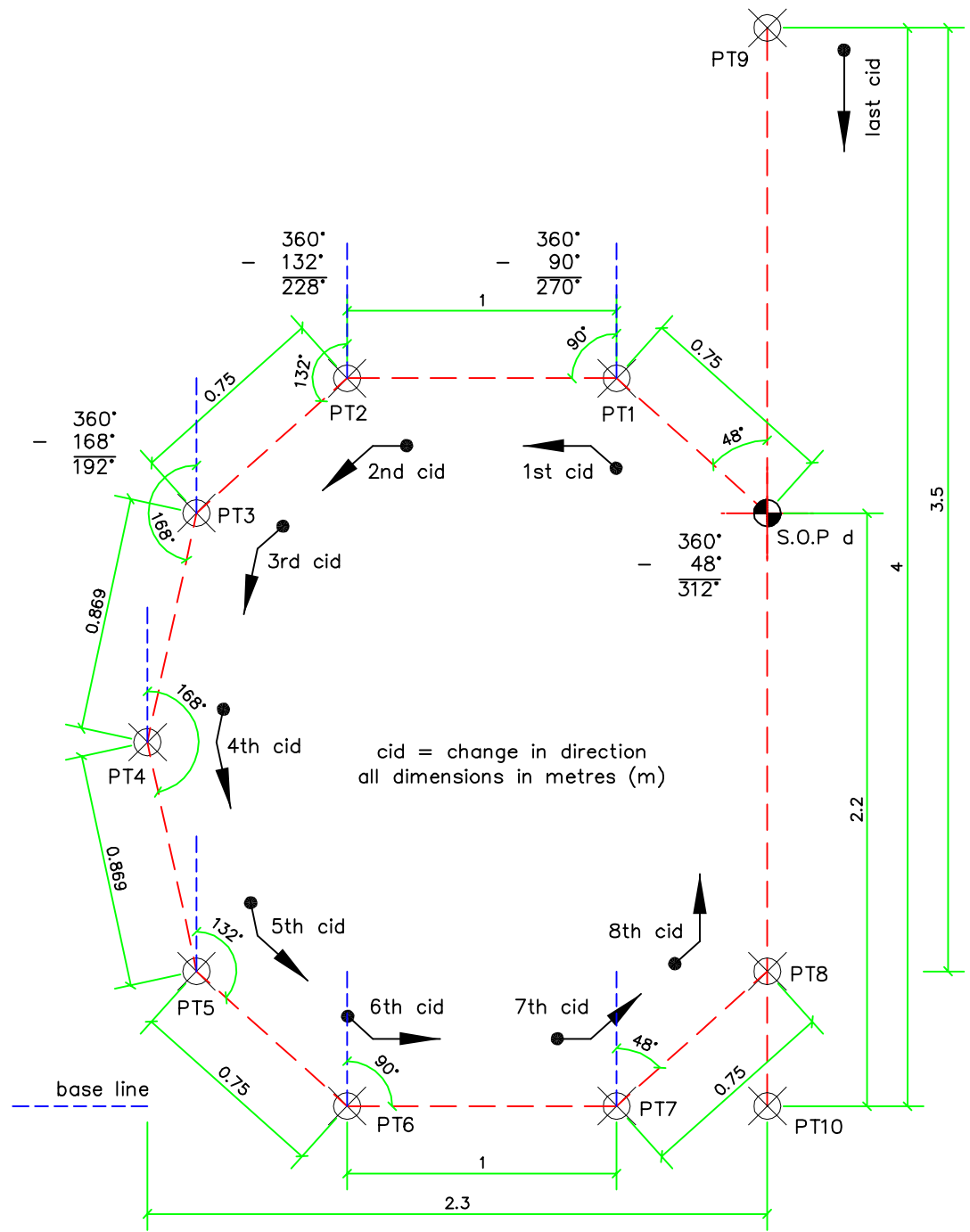
- From S.O.P D walk 1.5m on a bearing of 180° and mark the location.
- From PT1 Walk 0.85m on a bearing of 199° and mark the location.
- From PT2 Walk 0.85m on a bearing of 238° and mark the location.
- From PT3 Walk 2m on a bearing of 270° and mark the location.
- From PT4 Walk 4m on a bearing of 0° and mark the location.
- From PT5 Walk 2m on a bearing of 90° and mark the location.
- From PT6 Walk 0.85m on a bearing of 122° and mark the location.
- From PT7 Walk 0.85m on a bearing of 161° and finish.

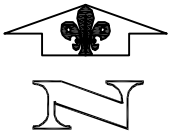




Micro navigation – letter d

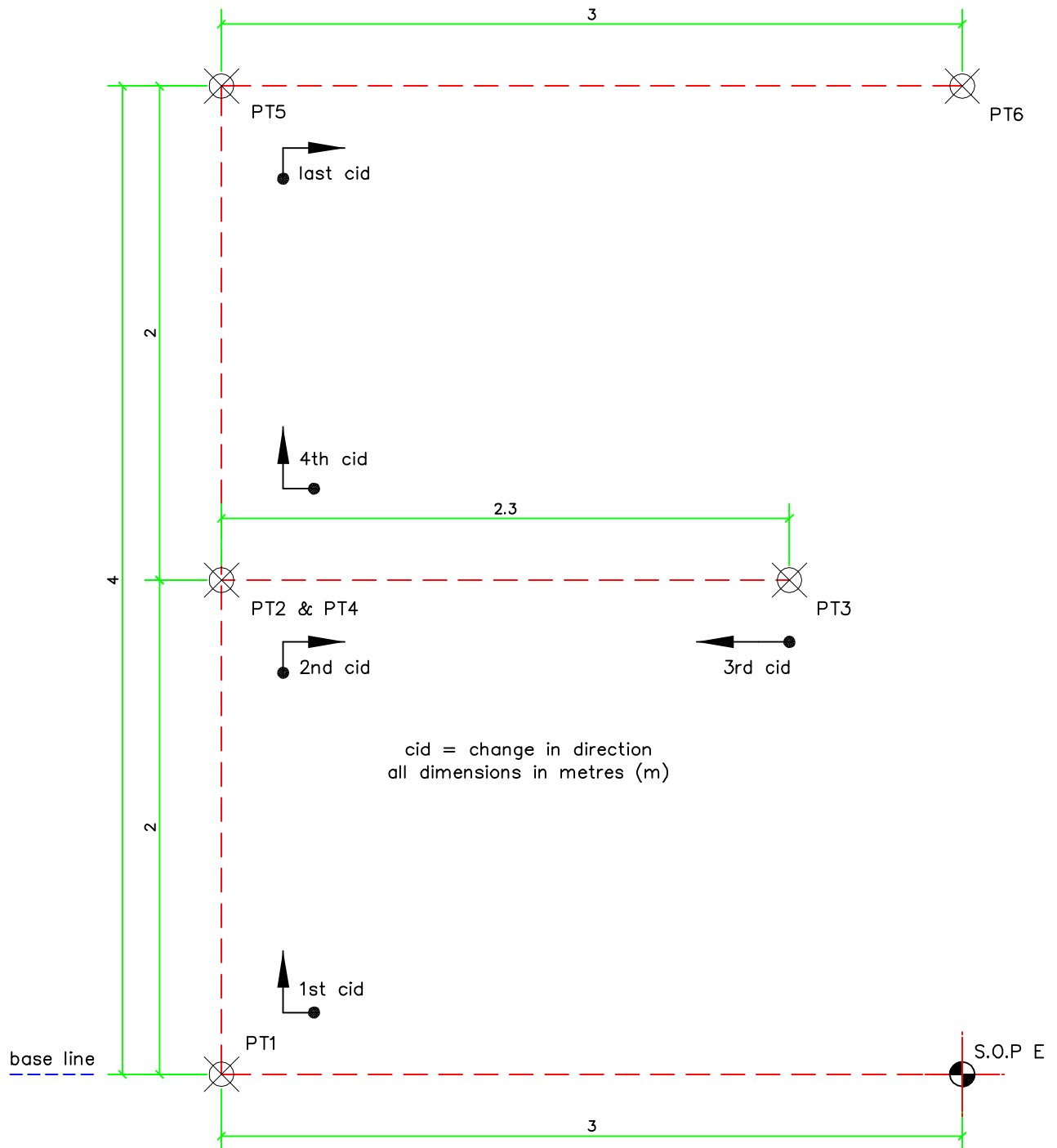
- From S.O.P d walk 0.75m on a bearing of 312° and mark the location.
- From PT1 Walk 1m on a bearing of 270° and mark the location.
- From PT2 Walk 0.75m on a bearing of 228° and mark the location.
- From PT3 Walk 0.9m on a bearing of 192° and mark the location.
- From PT4 Walk 0.9m on a bearing of 168° and mark the location.
- From PT5 Walk 0.75m on a bearing of 132° and mark the location.
- From PT6 Walk 1m on a bearing of 90° and mark the location.
- From PT7 Walk 0.75m on a bearing of 48° and mark the location.
- From PT8 Walk 3.5m on a bearing of 0° and mark the location.
- From PT9 Walk 4m on a bearing of 180° and mark the location and finish.

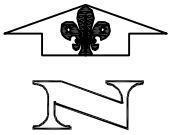




Micro navigation – letter E

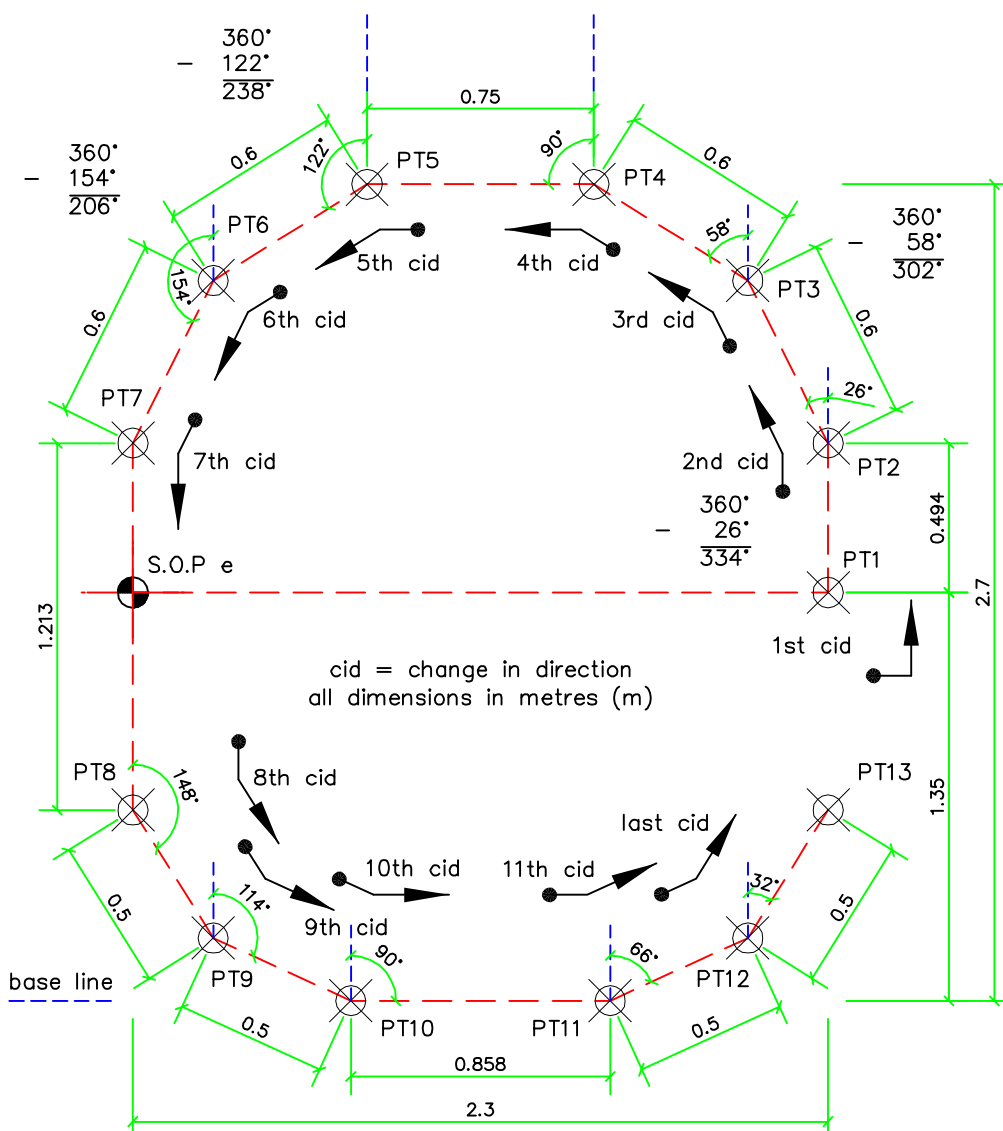
- From S.O.P E walk 3m on a bearing of 270° and mark the location.
- From PT1 Walk 2m on a bearing of 0° and mark the location.
- From PT2 Walk 2.3m on a bearing of 90° and mark the location.
- From PT3 Walk 2.3m on a bearing of 270° .
- From PT4 Walk 2m on a bearing of 0° and mark the location.
- From PT5 Walk 3m on a bearing of 90° and mark the location and finish.

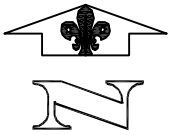




Micro navigation – letter e

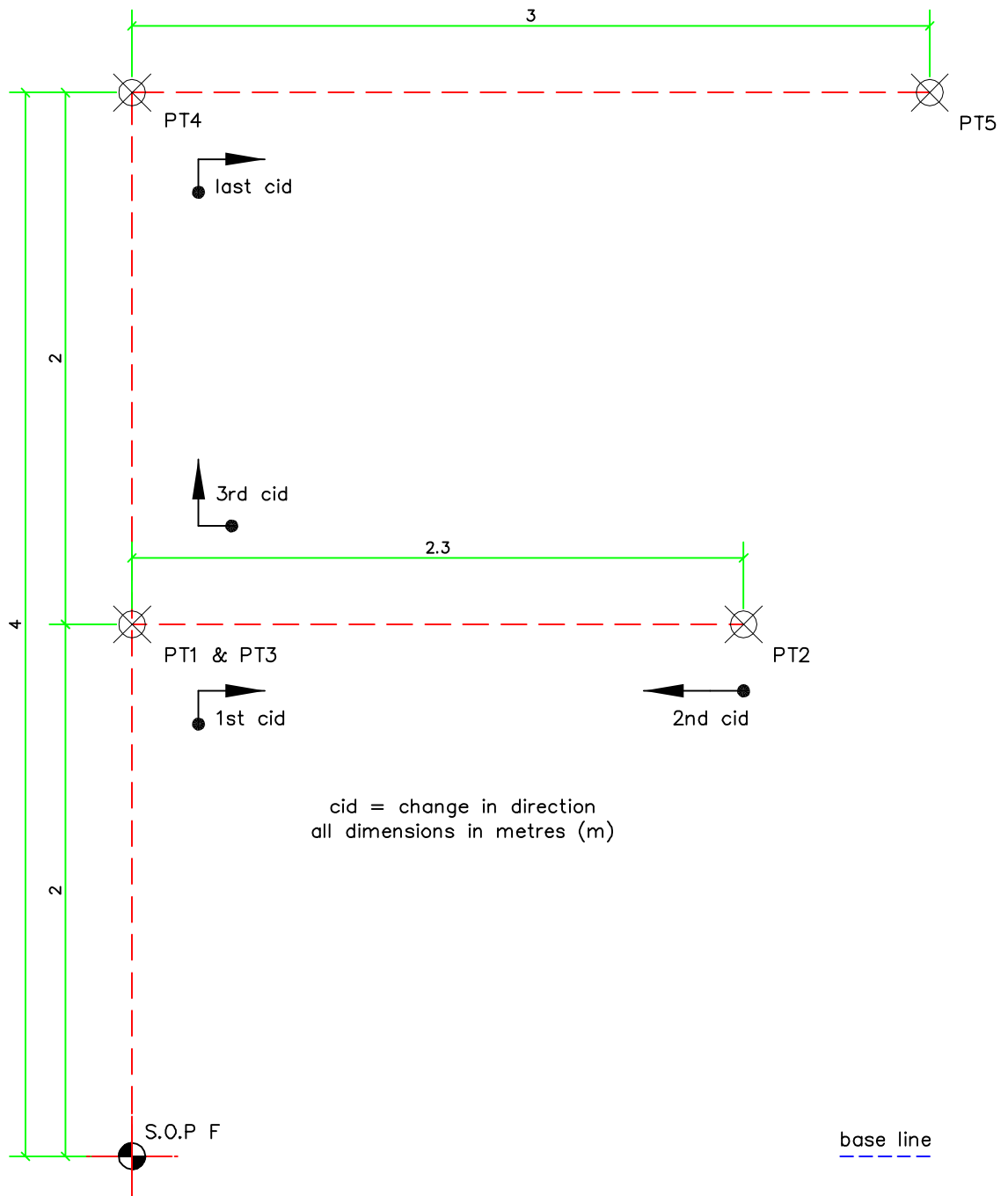
- From S.O.P e walk 2.3m on a bearing of 90° and mark the location.
- From PT1 Walk 0.5m on a bearing of 0° and mark the location.
- From PT2 Walk 0.6m on a bearing of 334° and mark the location.
- From PT3 Walk 0.6m on a bearing of 302° and mark the location.
- From PT4 Walk 0.75m on a bearing of 270° and mark the location.
- From PT5 Walk 0.6m on a bearing of 238° and mark the location.
- From PT6 Walk 0.6m on a bearing of 206° and mark the location.
- From PT7 Walk 1.2m on a bearing of 180° and mark the location.
- From PT8 Walk 0.5m on a bearing of 148° and mark the location.
- From PT9 Walk 0.5m on a bearing of 114° and mark the location.
- From PT10 Walk 0.9m on a bearing of 90° and mark the location.
- From PT11 Walk 0.5m on a bearing of 66° and mark the location.
- From PT12 Walk 0.5m on a bearing of 32° and mark the location and finish.

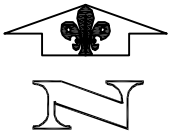




Micro navigation – letter F

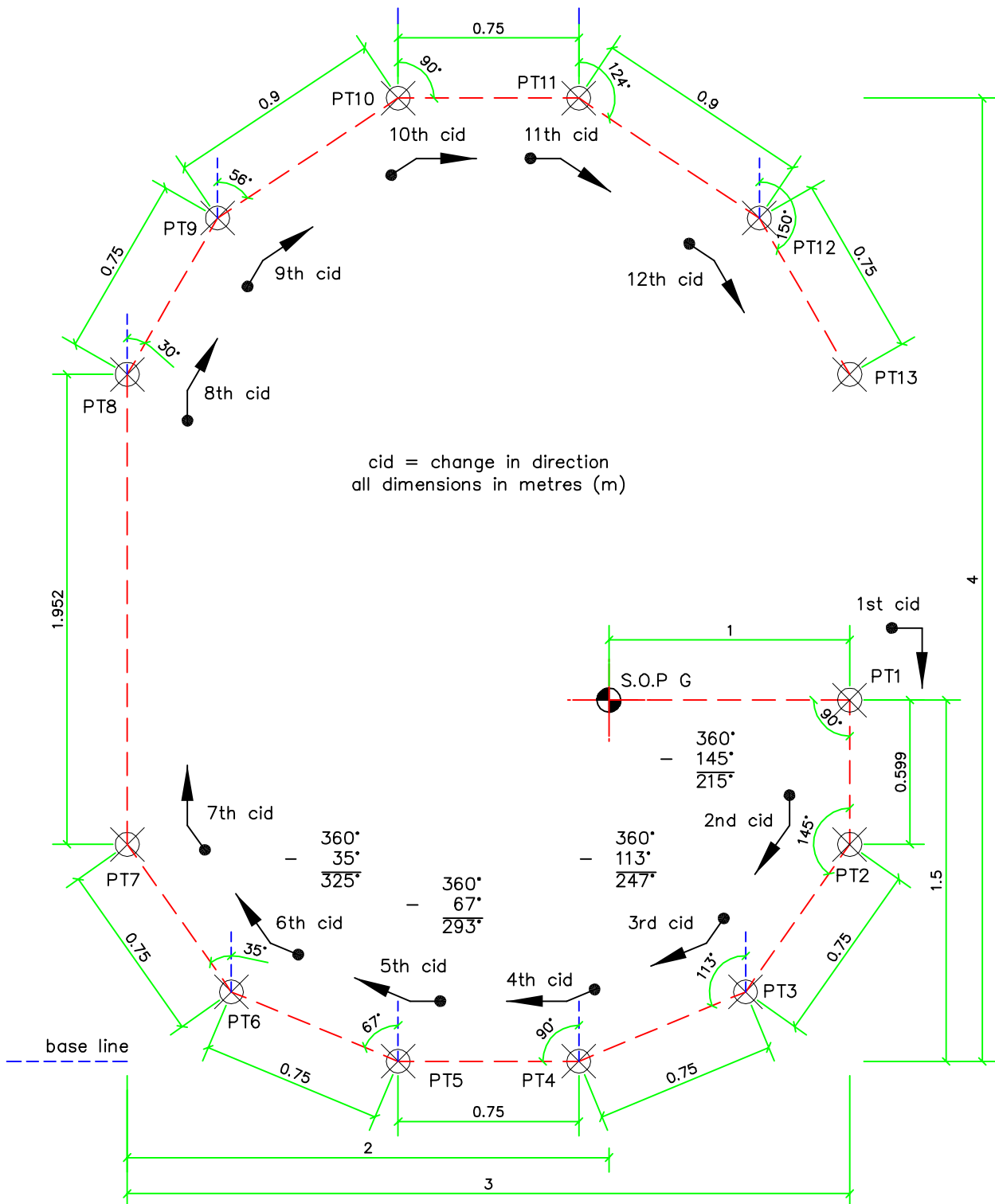
- From S.O.P F Walk 2m on a bearing of 0° and mark the location.
- From PT1 Walk 2.3m on a bearing of 90° and mark the location.
- From PT2 Walk 2.3m on a bearing of 270° .
- From PT3 Walk 2m on a bearing of 0° and mark the location.
- From PT4 Walk 3m on a bearing of 90° and mark the location and finish.

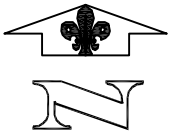




Micro navigation – letter G

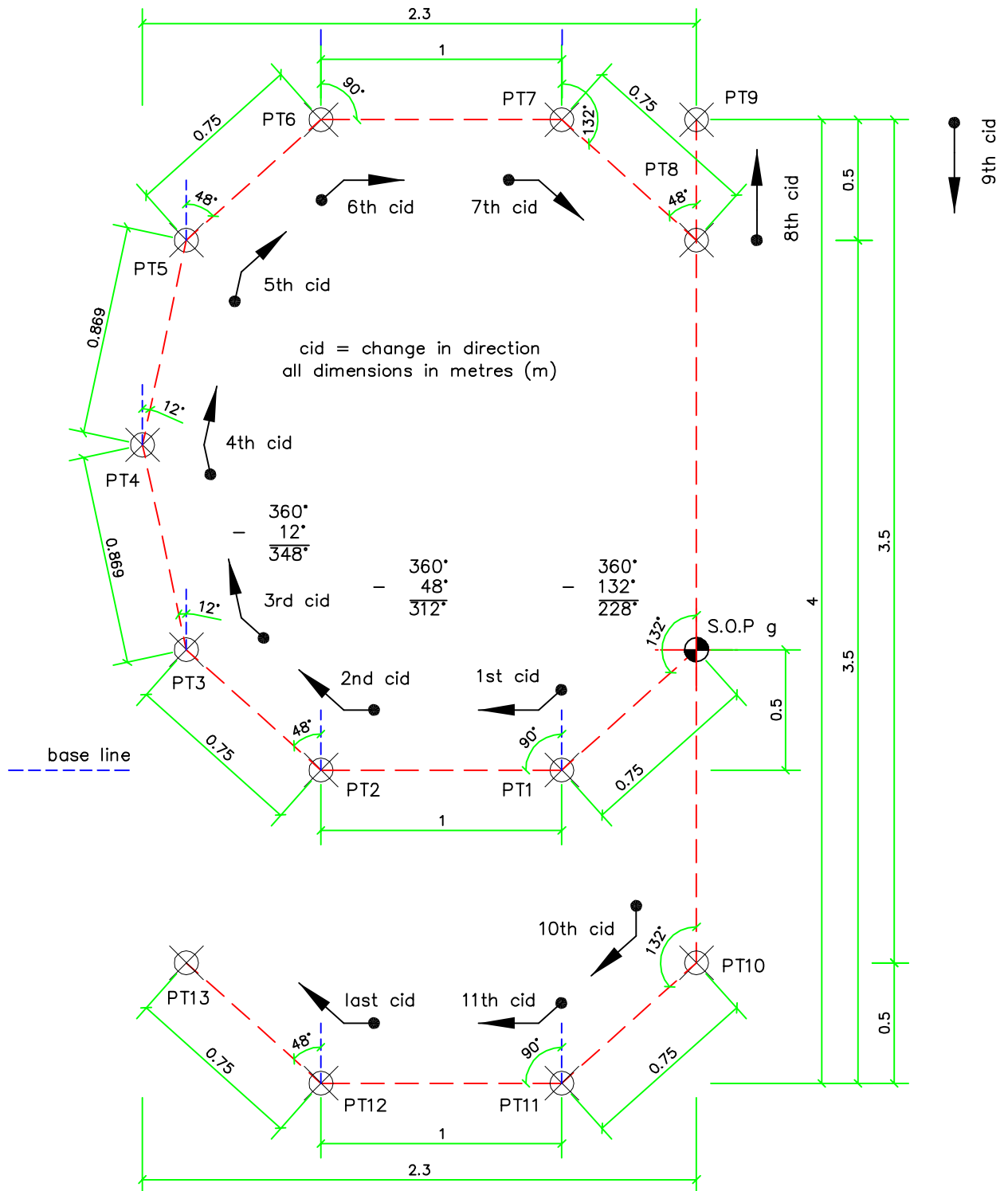
From S.O.P G walk	1m on a bearing of	90°	and mark the location.
From PT1 Walk	0.6m on a bearing of	180°	and mark the location.
From PT2 Walk	0.75m on a bearing of	215°	and mark the location.
From PT3 Walk	0.75m on a bearing of	247°	and mark the location.
From PT4 Walk	0.75m on a bearing of	270°	and mark the location.
From PT5 Walk	0.75m on a bearing of	293°	and mark the location.
From PT6 Walk	0.75m on a bearing of	325°	and mark the location.
From PT7 Walk	2m on a bearing of	0°	and mark the location.
From PT8 Walk	0.75m on a bearing of	30°	and mark the location.
From PT9 Walk	0.9m on a bearing of	56°	and mark the location.
From PT10 Walk	0.75m on a bearing of	90°	and mark the location.
From PT11 Walk	0.9m on a bearing of	124°	and mark the location.
From PT12 Walk	0.75m on a bearing of	150°	and mark the location and finish.

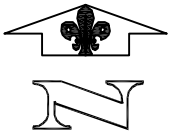




Micro navigation – letter g

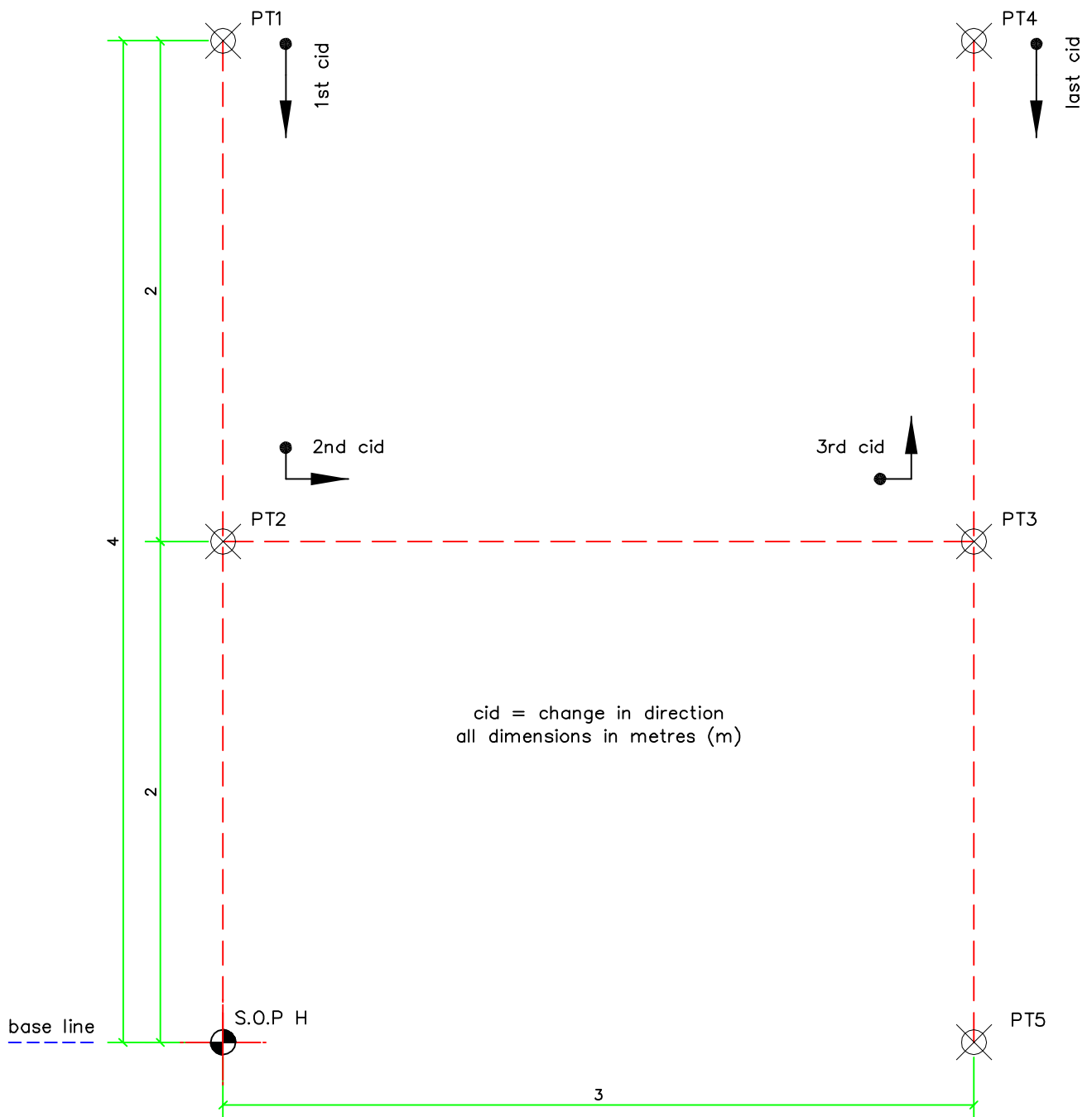
From S.O.P	g walk	0.75m on a bearing of	228°	and mark the location.
From PT1	Walk	1m on a bearing of	270°	and mark the location.
From PT2	Walk	0.75m on a bearing of	312°	and mark the location.
From PT3	Walk	0.9m on a bearing of	348°	and mark the location.
From PT4	Walk	0.9m on a bearing of	12°	and mark the location.
From PT5	Walk	0.75m on a bearing of	48°	and mark the location.
From PT6	Walk	1m on a bearing of	90°	and mark the location.
From PT7	Walk	0.75m on a bearing of	132°	and mark the location.
From PT8	Walk	0.5m on a bearing of	0°	and mark the location.
From PT9	Walk	3.5m on a bearing of	180°	and mark the location.
From PT10	Walk	0.75m on a bearing of	228°	and mark the location.
From PT11	Walk	1m on a bearing of	270°	and mark the location.
From PT12	Walk	0.75m on a bearing of	312°	and mark the location and finish.

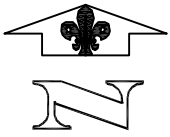




Micro navigation – letter H

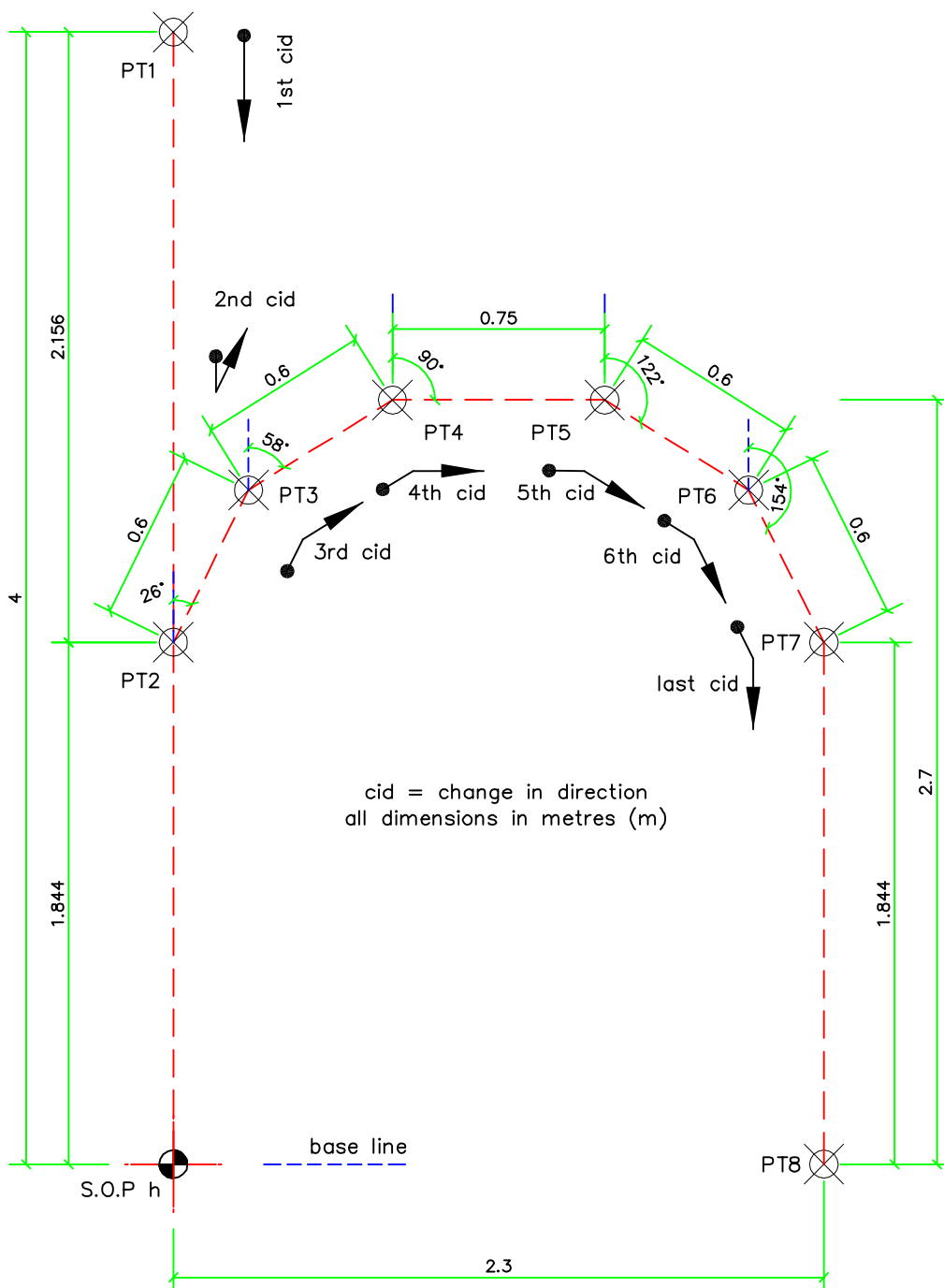
- From S.O.P H walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 2m on a bearing of 180° and mark the location.
- From PT2 Walk 3m on a bearing of 90° and mark the location.
- From PT3 Walk 2m on a bearing of 0° and mark the location.
- From PT4 Walk 4m on a bearing of 180° and mark the location and finish.

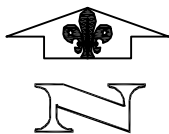




Micro navigation – letter h

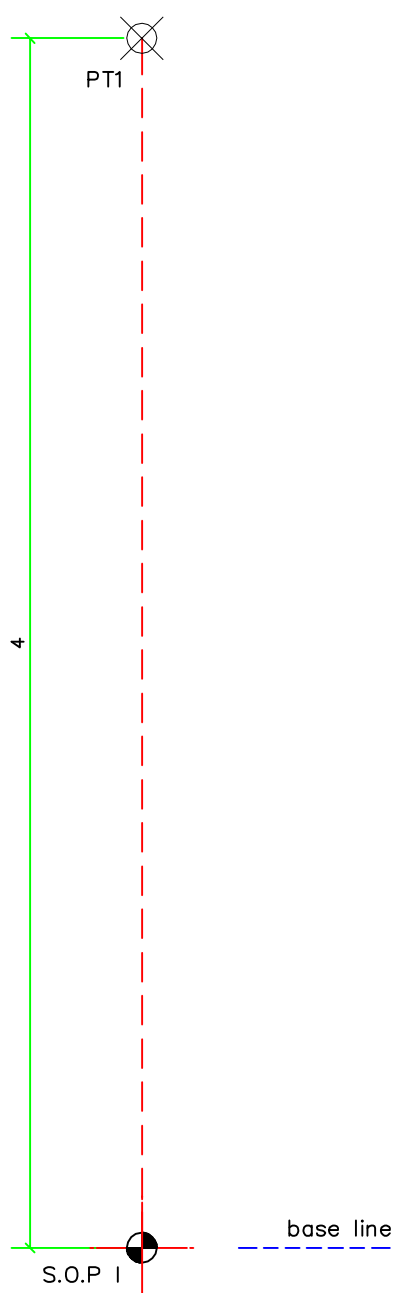
- From S.O.P h walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 2.2m on a bearing of 180° and mark the location.
- From PT2 Walk 0.6m on a bearing of 26° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.75m on a bearing of 90° and mark the location.
- From PT5 Walk 0.6m on a bearing of 122° and mark the location.
- From PT6 Walk 0.6m on a bearing of 154° and mark the location.
- From PT7 Walk 1.8m on a bearing of 180° and mark the location and finish.



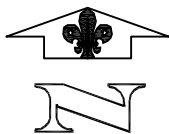


Micro navigation – letter I

From S.O.P I walk 4m on a bearing of 0° and mark the location and finish.

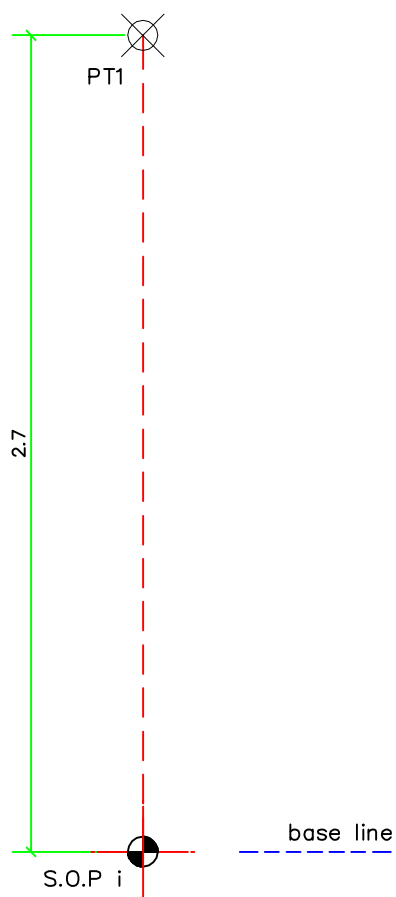


cid = change in direction
all dimensions in metres (m)

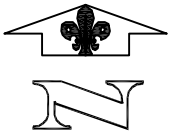


Micro navigation – letter i

From S.O.P i walk 2.7m on a bearing of 0° and mark the location and finish.

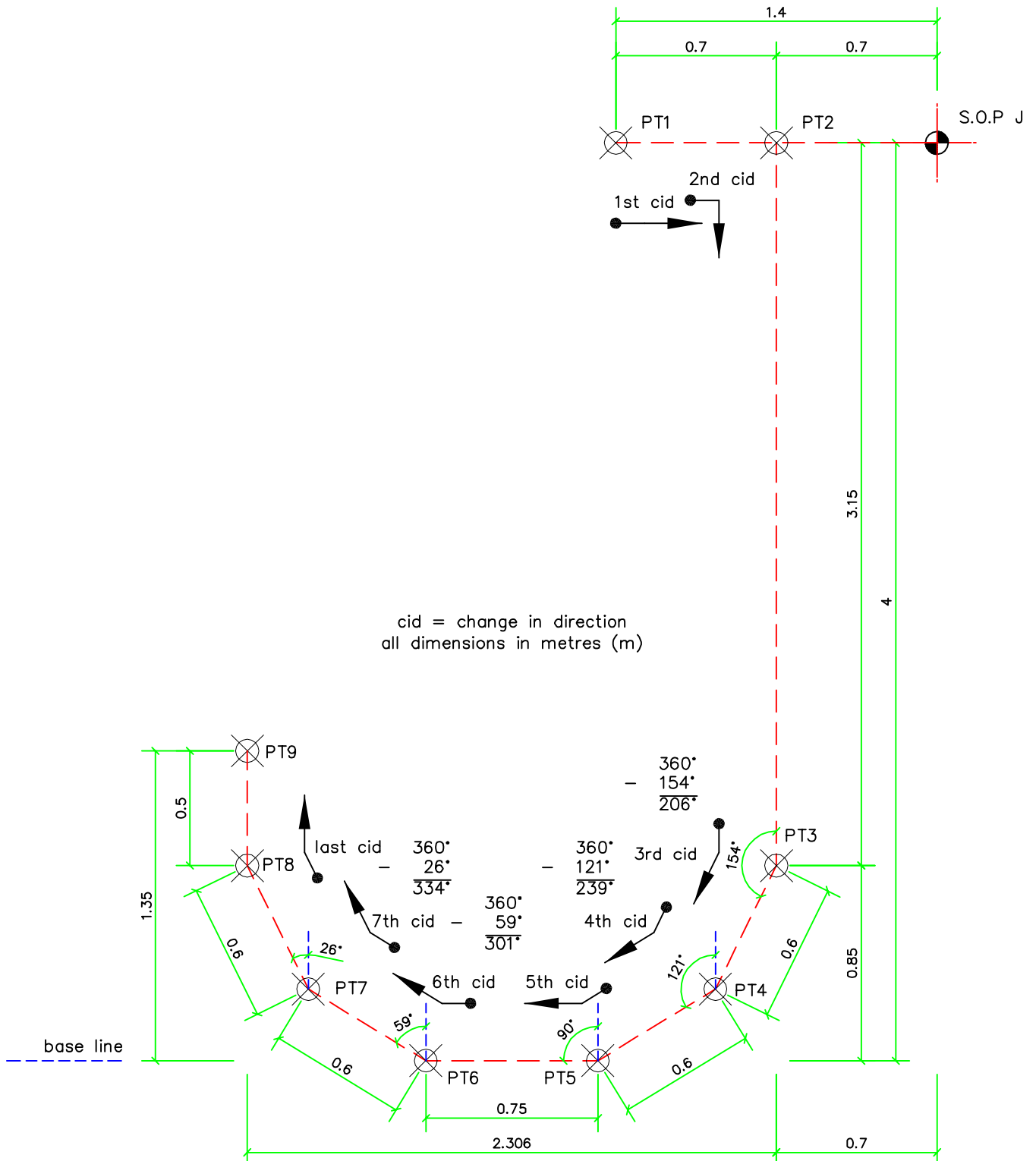


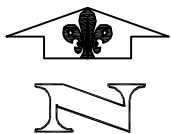
cid = change in direction
all dimensions in metres (m)



Micro navigation – letter J

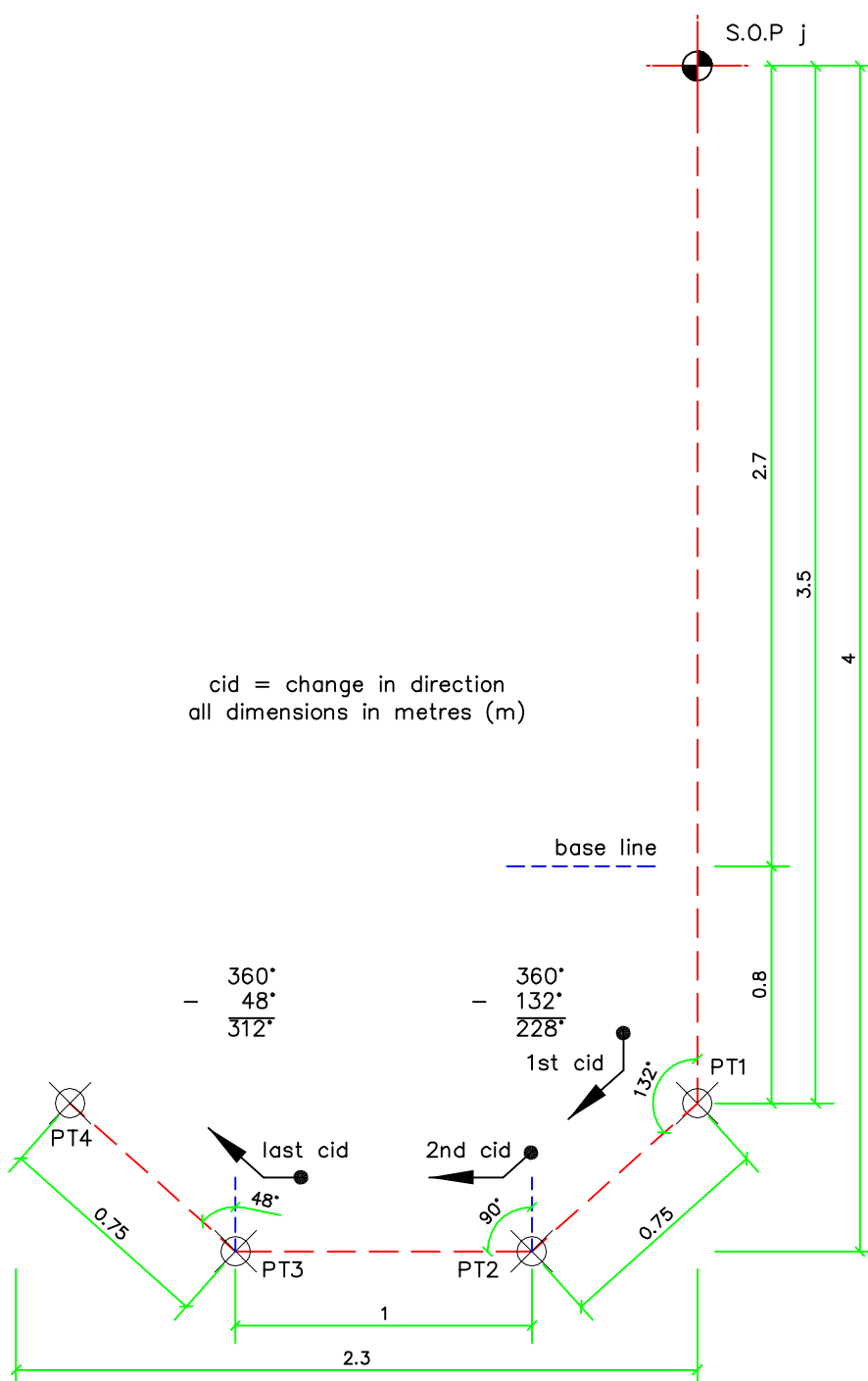
- | | | | |
|-------------------|-----------------------|------|-----------------------------------|
| From S.O.P J walk | 1.4m on a bearing of | 270° | and mark the location. |
| From PT1 Walk | 0.7m on a bearing of | 90° | and mark the location. |
| From PT2 Walk | 3.15m on a bearing of | 180° | and mark the location. |
| From PT3 Walk | 0.6m on a bearing of | 206° | and mark the location. |
| From PT4 Walk | 0.6m on a bearing of | 239° | and mark the location. |
| From PT5 Walk | 0.75m on a bearing of | 270° | and mark the location. |
| From PT6 Walk | 0.6m on a bearing of | 301° | and mark the location. |
| From PT7 Walk | 0.6m on a bearing of | 334° | and mark the location. |
| From PT8 Walk | 0.5m on a bearing of | 0° | and mark the location and finish. |

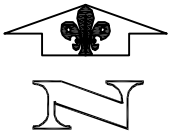




Micro navigation – letter j

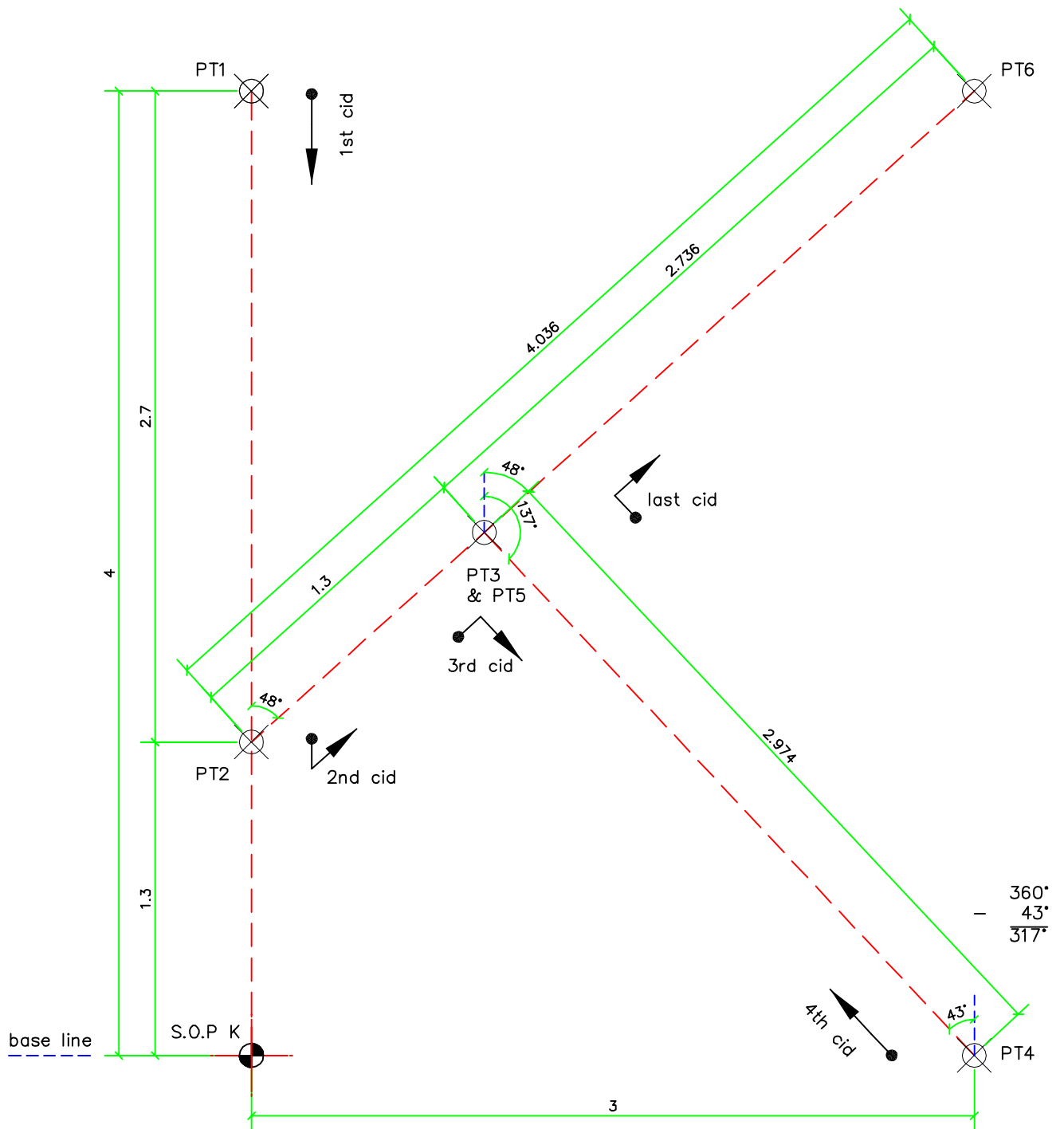
- From S.O.P j walk 3.5m on a bearing of 180° and mark the location.
- From PT1 Walk 0.75m on a bearing of 228° and mark the location.
- From PT2 Walk 1m on a bearing of 270° and mark the location.
- From PT3 Walk 0.75m on a bearing of 312° and mark the location and finish.



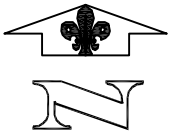


Micro navigation – letter K

- From S.O.P K walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 2.7m on a bearing of 180° and mark the location.
- From PT2 Walk 1.3m on a bearing of 48° and mark the location.
- From PT3 Walk 3m on a bearing of 137° and mark the location.
- From PT4 Walk 3m on a bearing of 317° and mark the location.
- From PT5 Walk 2.7m on a bearing of 48° and mark the location and finish.

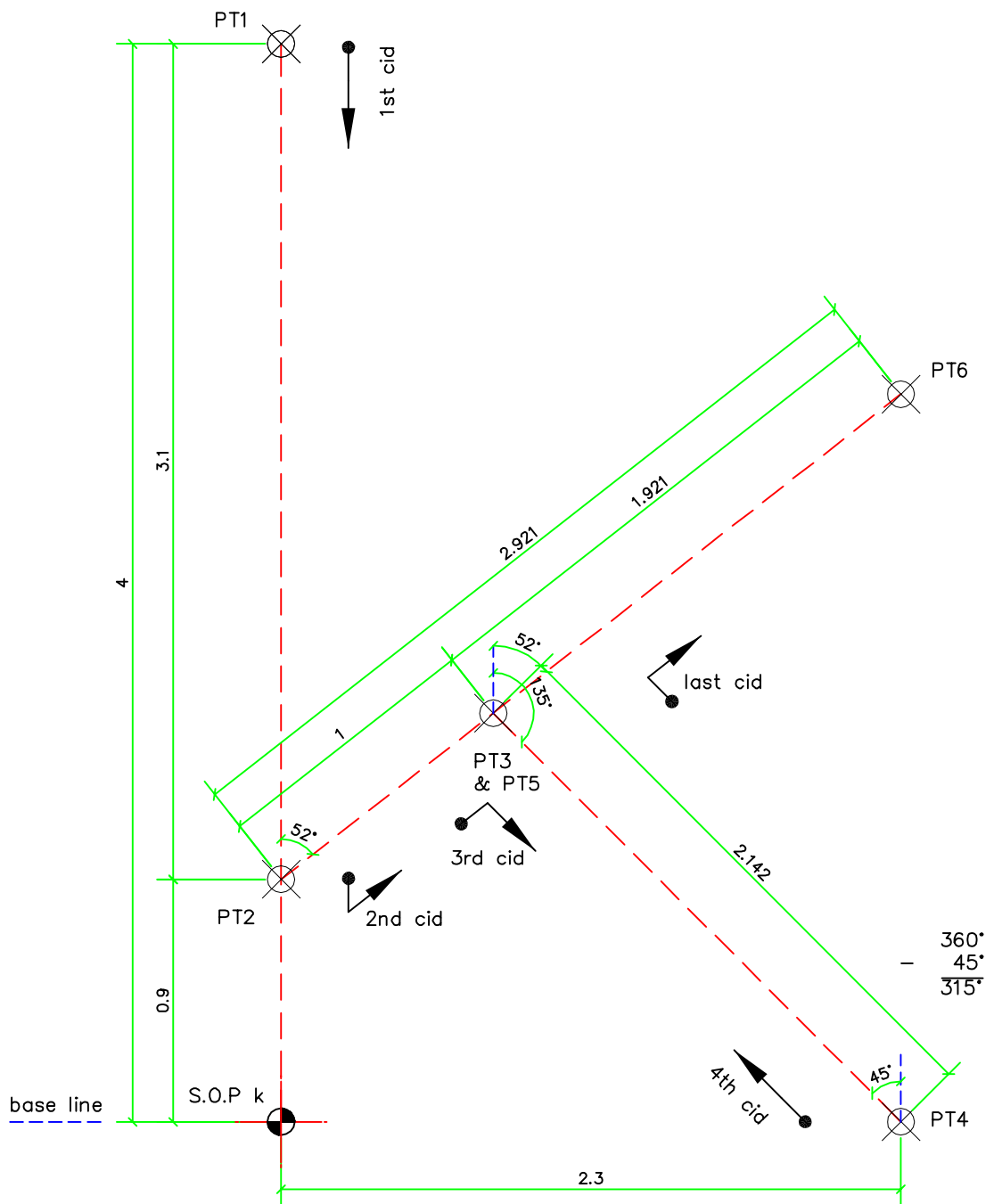


cid = change in direction
all dimensions in metres (m)

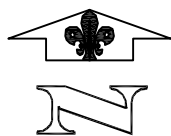


Micro navigation – letter k

- From S.O.P k walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 3.1m on a bearing of 180° and mark the location.
- From PT2 Walk 1m on a bearing of 52° and mark the location.
- From PT3 Walk 2.1m on a bearing of 135° and mark the location.
- From PT4 Walk 2.1m on a bearing of 315° and mark the location.
- From PT5 Walk 1.9m on a bearing of 52° and mark the location and finish.

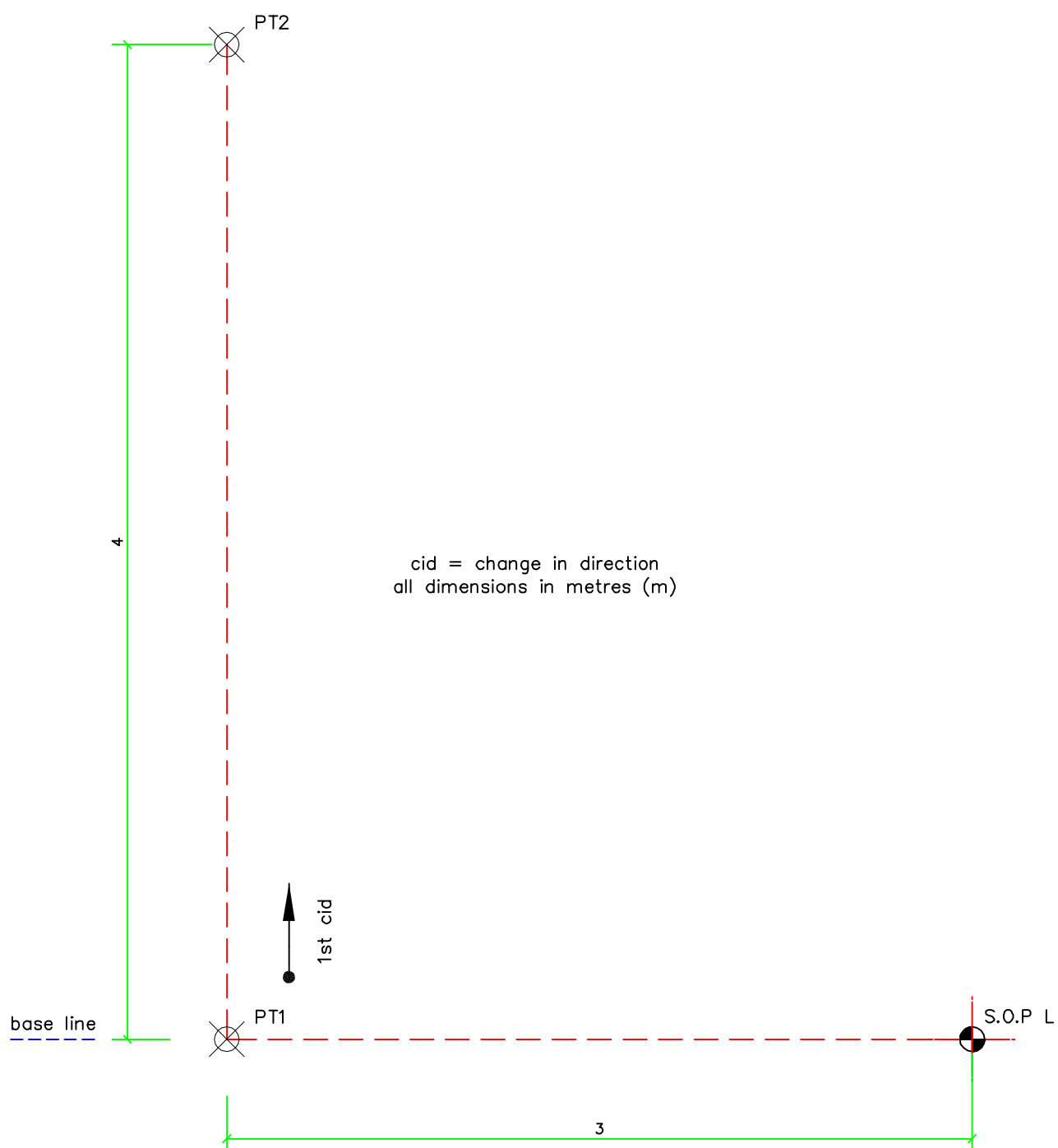


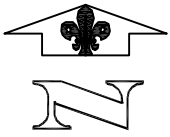
cid = change in direction
all dimensions in metres (m)



Micro navigation – letter L

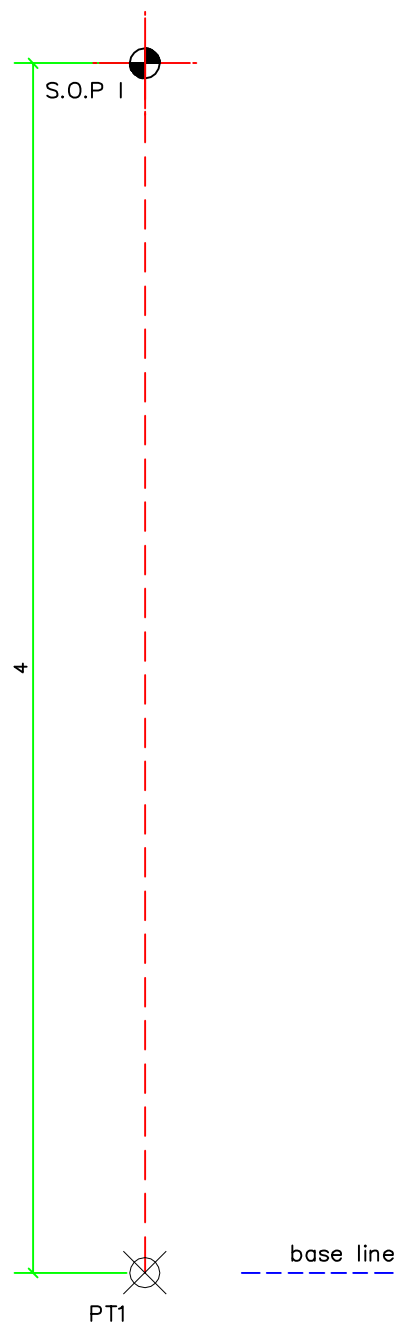
From S.O.P L walk 3m on a bearing of 270° and mark the location.
 From PT1 Walk 4m on a bearing of 0° and mark the location and finish.



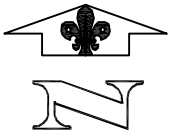


Micro navigation – letter I

From S.O.P I walk 4m on a bearing of 180° and mark the location and finish.

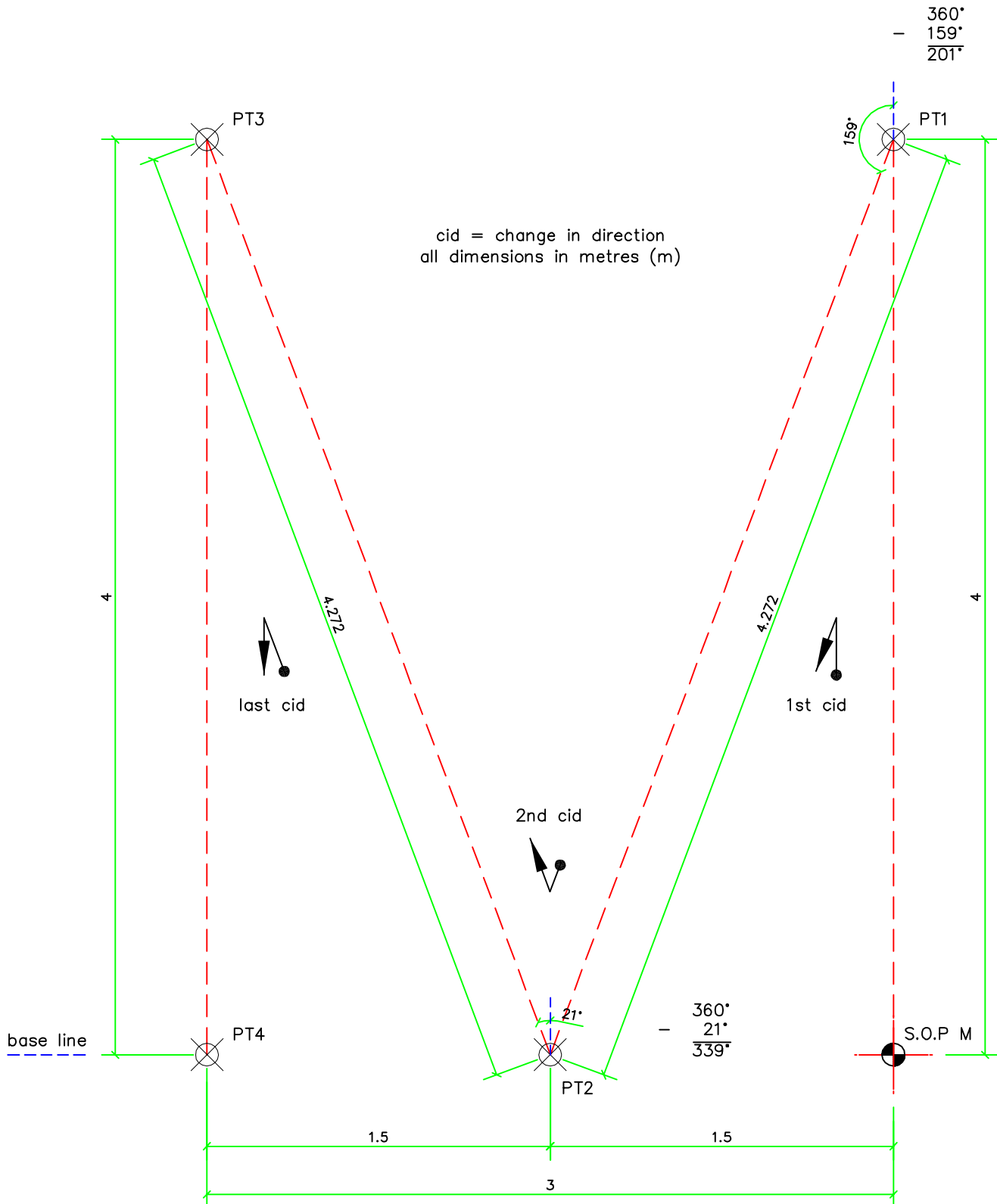


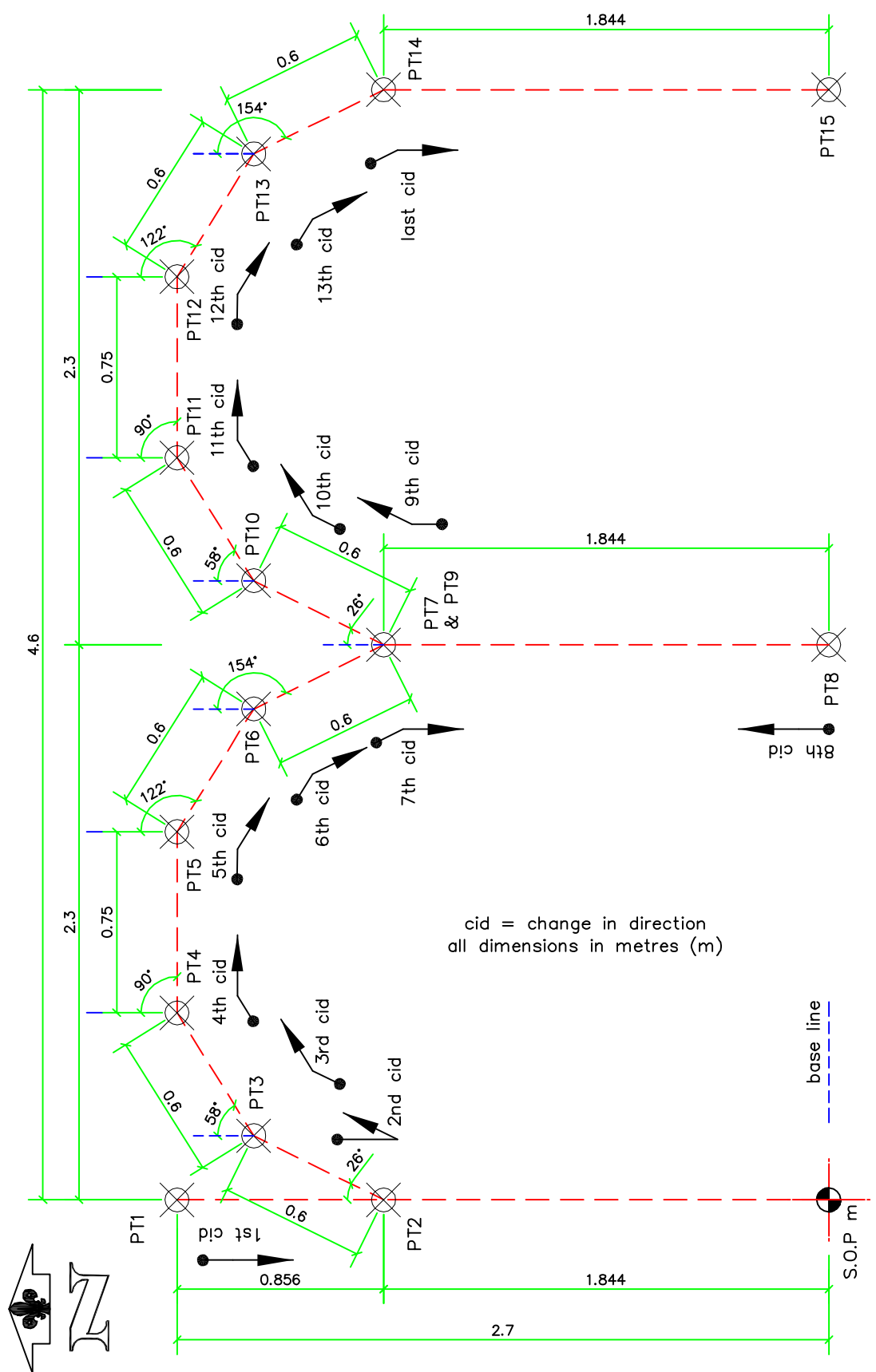
cid = change in direction
all dimensions in metres (m)



Micro navigation – letter M

- From S.O.P M walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 4.3m on a bearing of 201° and mark the location.
- From PT2 Walk 4.3m on a bearing of 339° and mark the location.
- From PT3 Walk 4m on a bearing of 180° and mark the location and finish.

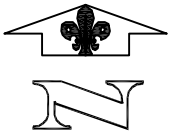




Micro navigation – letter m

- From S.O.P m walk 2.7m on a bearing of 0° and mark the location.
- From PT1 Walk 0.9m on a bearing of 180° and mark the location.
- From PT2 Walk 0.6m on a bearing of 26° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.75m on a bearing of 90° and mark the location.
- From PT5 Walk 0.6m on a bearing of 122° and mark the location.
- From PT6 Walk 0.6m on a bearing of 154° and mark the location.
- From PT7 Walk 1.8m on a bearing of 180° and mark the location.

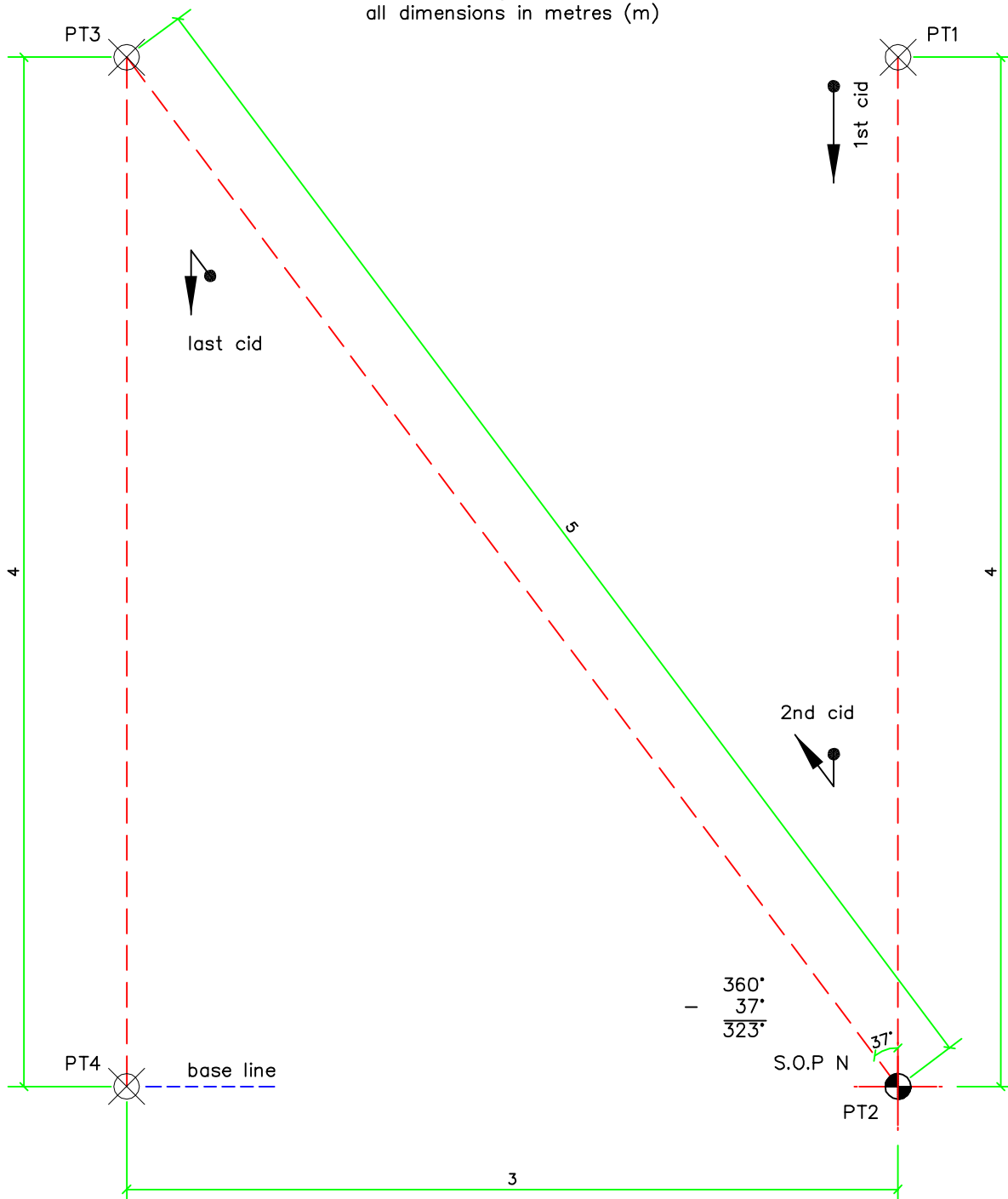
- From PT8 Walk 1.8m on a bearing of 0° and mark the location.
- From PT9 Walk 0.6m on a bearing of 26° and mark the location.
- From PT10 Walk 0.6m on a bearing of 58° and mark the location.
- From PT11 Walk 0.75m on a bearing of 90° and mark the location.
- From PT12 Walk 0.6m on a bearing of 122° and mark the location.
- From PT13 Walk 0.6m on a bearing of 154° and mark the location.
- From PT14 Walk 1.8m on a bearing of 180° and mark the location and finish.

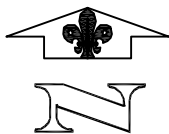


Micro navigation – letter N

- From S.O.P N walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 4m on a bearing of 180° .
- From PT2 Walk 5m on a bearing of 323° and mark the location.
- From PT3 Walk 4m on a bearing of 180° and mark the location and finish.

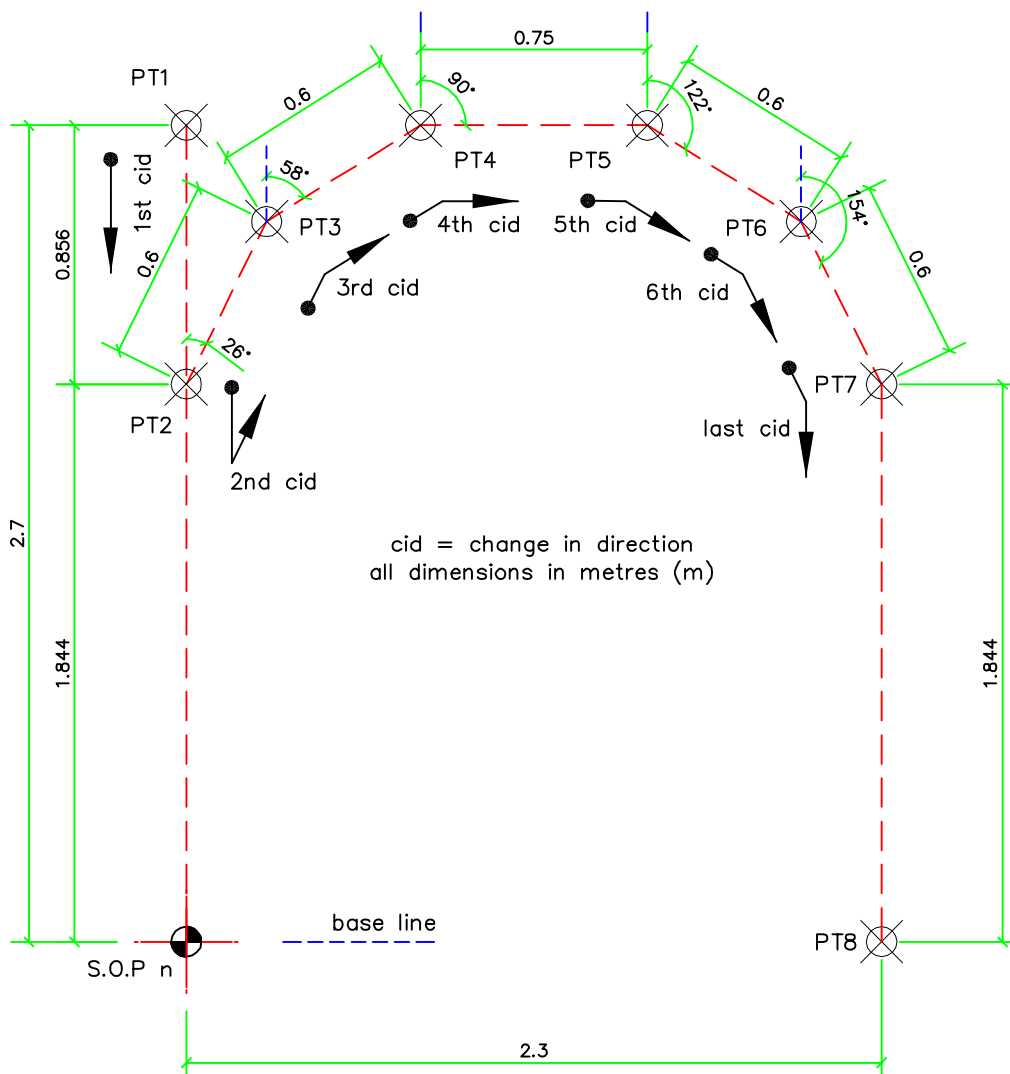
cid = change in direction
all dimensions in metres (m)

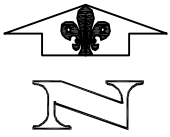




Micro navigation – letter n

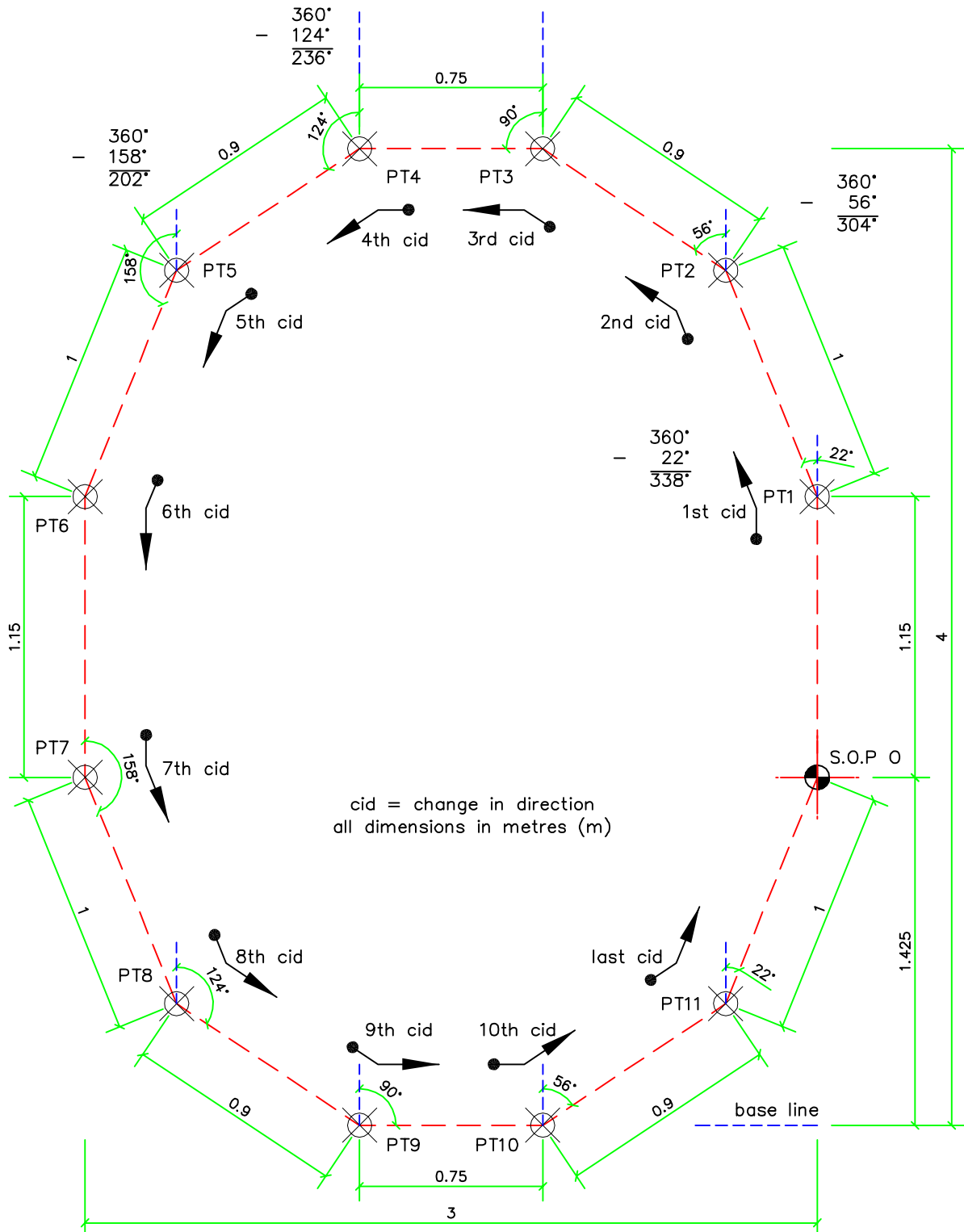
- From S.O.P n walk 2.7m on a bearing of 0° and mark the location.
- From PT1 Walk 0.9m on a bearing of 180° and mark the location.
- From PT2 Walk 0.6m on a bearing of 26° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.75m on a bearing of 90° and mark the location.
- From PT5 Walk 0.6m on a bearing of 122° and mark the location.
- From PT6 Walk 0.6m on a bearing of 154° and mark the location.
- From PT7 Walk 1.8m on a bearing of 180° and mark the location and finish.

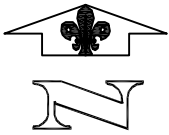




Micro navigation – letter O

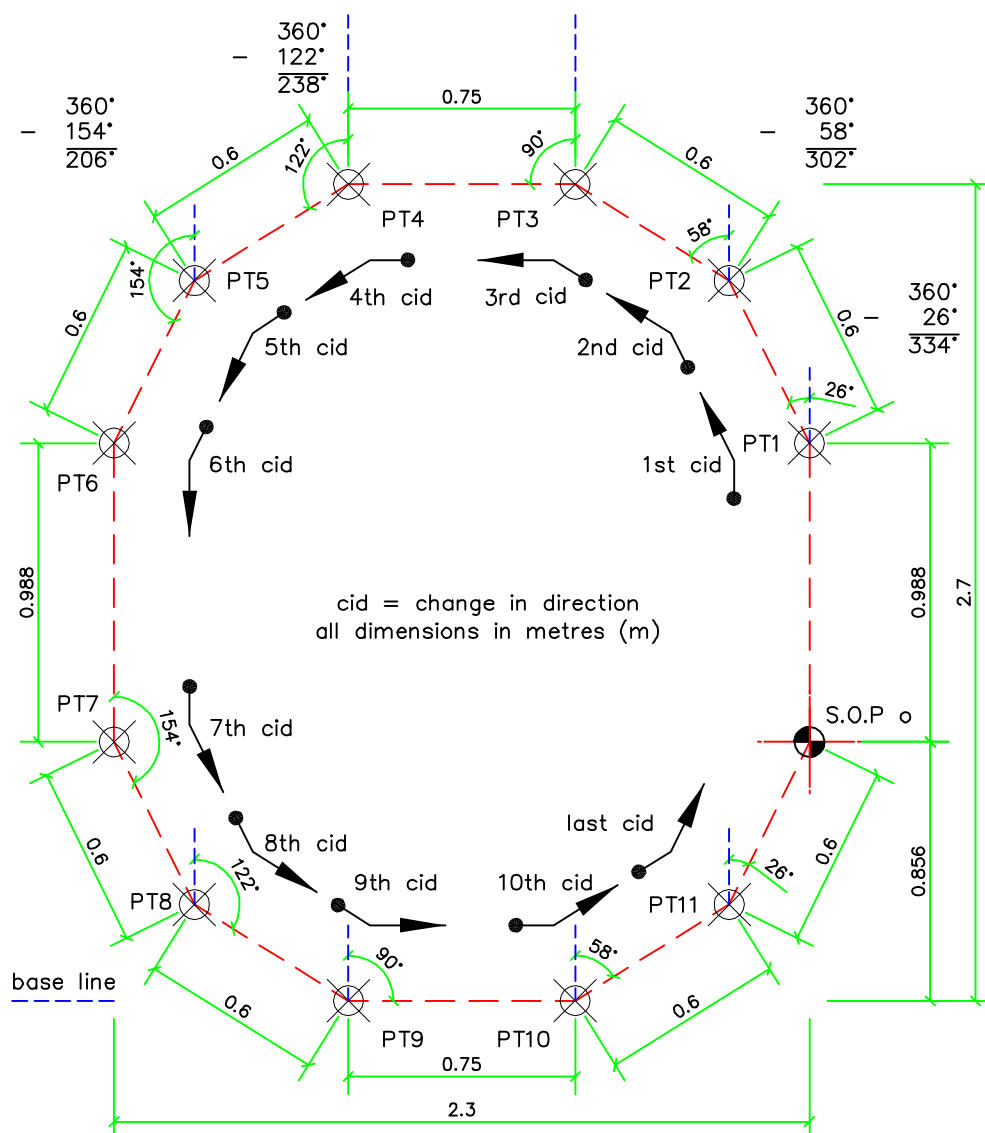
- | | | |
|---|------|------------------------|
| From S.O.P 0 walk 1.15m on a bearing of | 0° | and mark the location. |
| From PT1 Walk 1.0m on a bearing of | 338° | and mark the location. |
| From PT2 Walk 0.9m on a bearing of | 304° | and mark the location. |
| From PT3 Walk 0.75m on a bearing of | 270° | and mark the location. |
| From PT4 Walk 0.9m on a bearing of | 236° | and mark the location. |
| From PT5 Walk 1.0m on a bearing of | 202° | and mark the location. |
| From PT6 Walk 1.15m on a bearing of | 180° | and mark the location. |
| From PT7 Walk 1.0m on a bearing of | 158° | and mark the location. |
| From PT8 Walk 0.9m on a bearing of | 124° | and mark the location. |
| From PT9 Walk 0.75m on a bearing of | 90° | and mark the location. |
| From PT10 Walk 0.9m on a bearing of | 56° | and mark the location. |
| From PT11 walk 1.0m on a bearing of | 22° | and finish. |

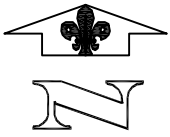




Micro navigation – letter o

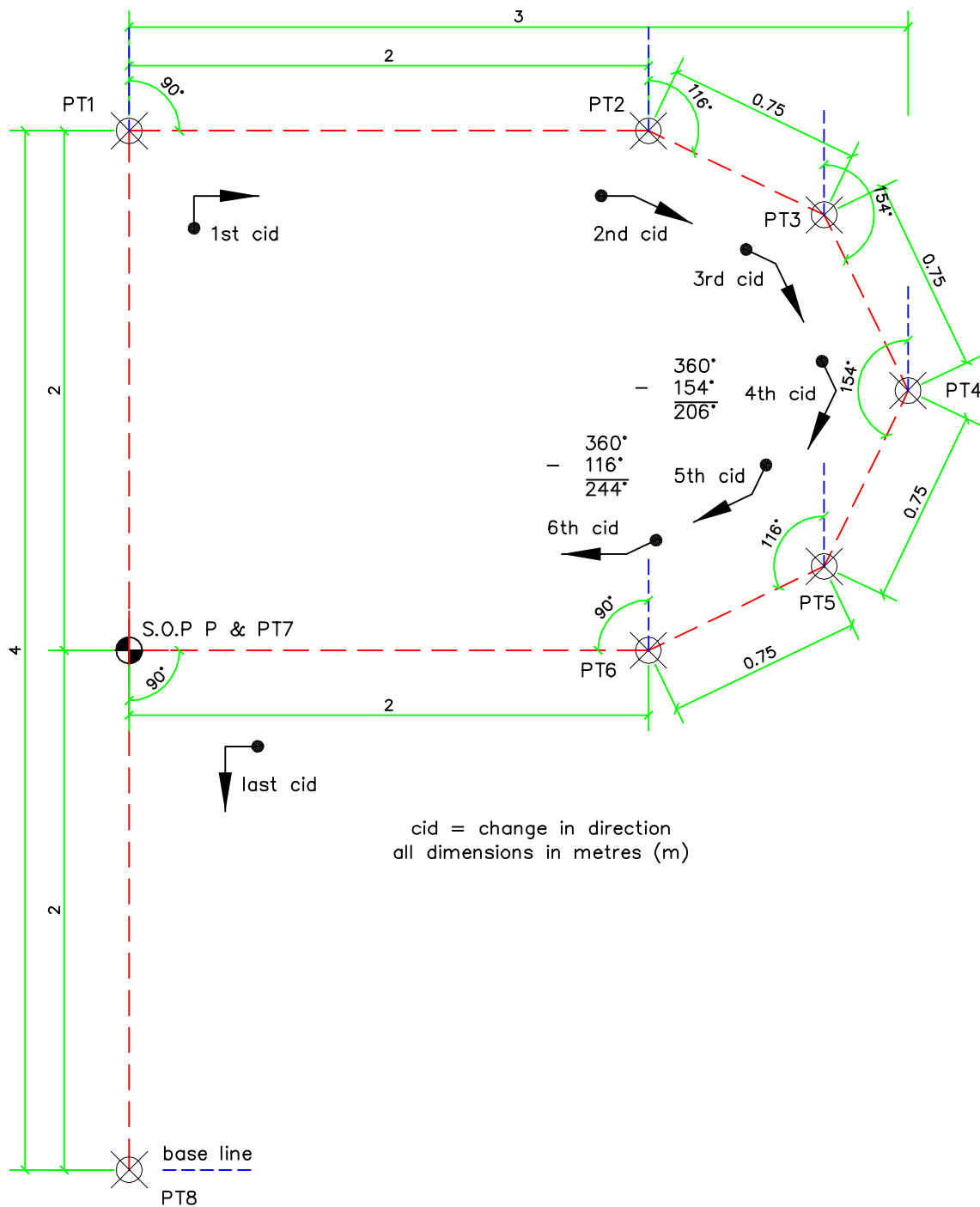
- | | | |
|--|------|------------------------|
| From S.O.P o walk 1.0m on a bearing of | 0° | and mark the location. |
| From PT1 Walk 0.6m on a bearing of | 334° | and mark the location. |
| From PT2 Walk 0.6m on a bearing of | 302° | and mark the location. |
| From PT3 Walk 0.75m on a bearing of | 270° | and mark the location. |
| From PT4 Walk 0.6m on a bearing of | 238° | and mark the location. |
| From PT5 Walk 0.6m on a bearing of | 206° | and mark the location. |
| From PT6 Walk 1.0m on a bearing of | 180° | and mark the location. |
| From PT7 Walk 0.6m on a bearing of | 154° | and mark the location. |
| From PT8 Walk 0.6m on a bearing of | 122° | and mark the location. |
| From PT9 Walk 0.75m on a bearing of | 90° | and mark the location. |
| From PT10 Walk 0.6m on a bearing of | 58° | and mark the location. |
| From PT11 walk 0.6m on a bearing of | 26° | and finish. |

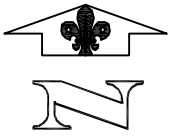




Micro navigation – letter P

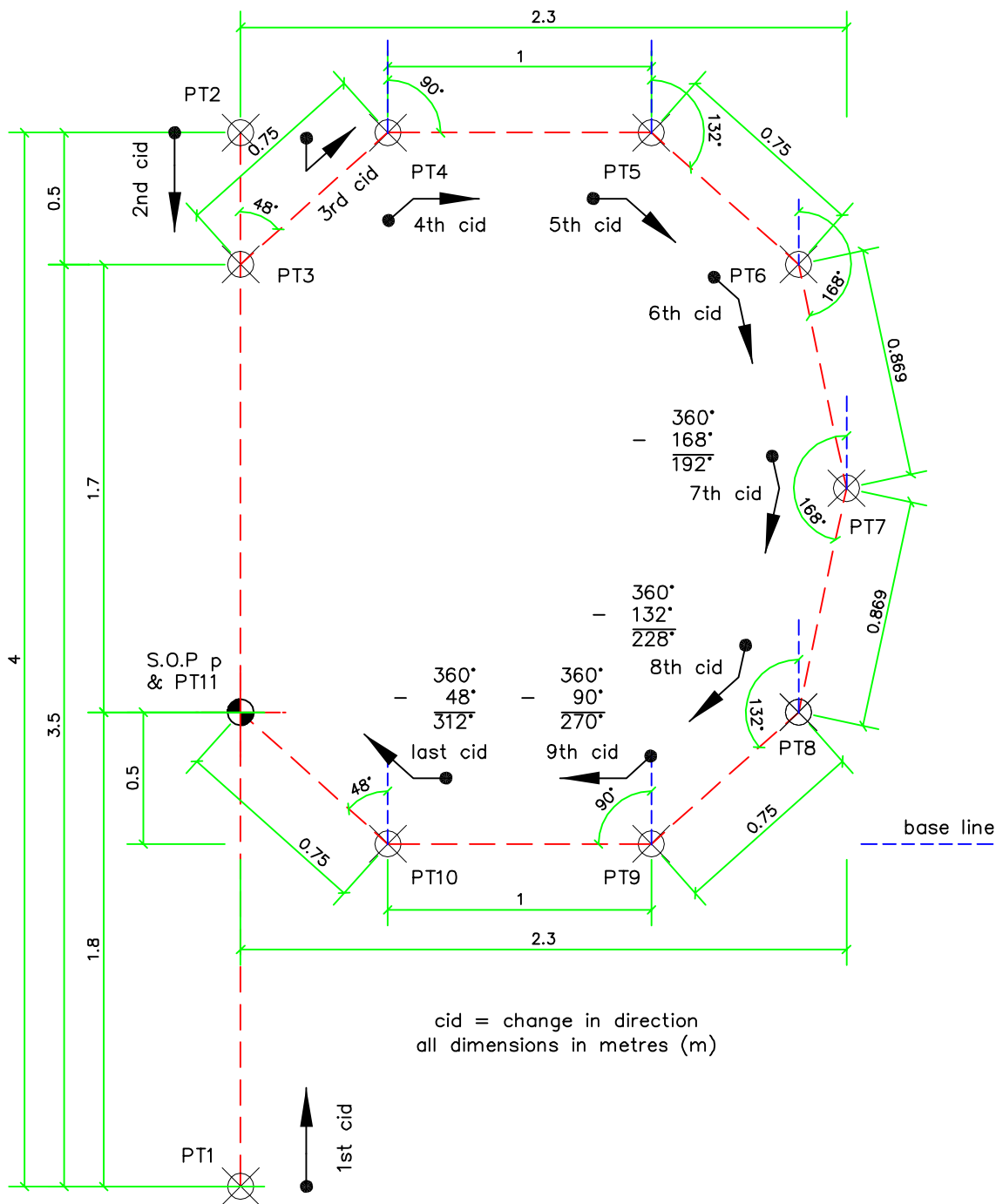
- From S.O.P P walk 2m on a bearing of 0° and mark the location.
- From PT1 Walk 2m on a bearing of 90° and mark the location.
- From PT2 Walk 0.75m on a bearing of 116° and mark the location.
- From PT3 Walk 0.75m on a bearing of 154° and mark the location.
- From PT4 Walk 0.75m on a bearing of 206° and mark the location.
- From PT5 Walk 0.75m on a bearing of 244° and mark the location.
- From PT6 Walk 2m on a bearing of 270° .
- From PT7 Walk 2m on a bearing of 180° and mark the location and finish.

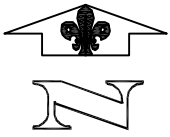




Micro navigation – letter p

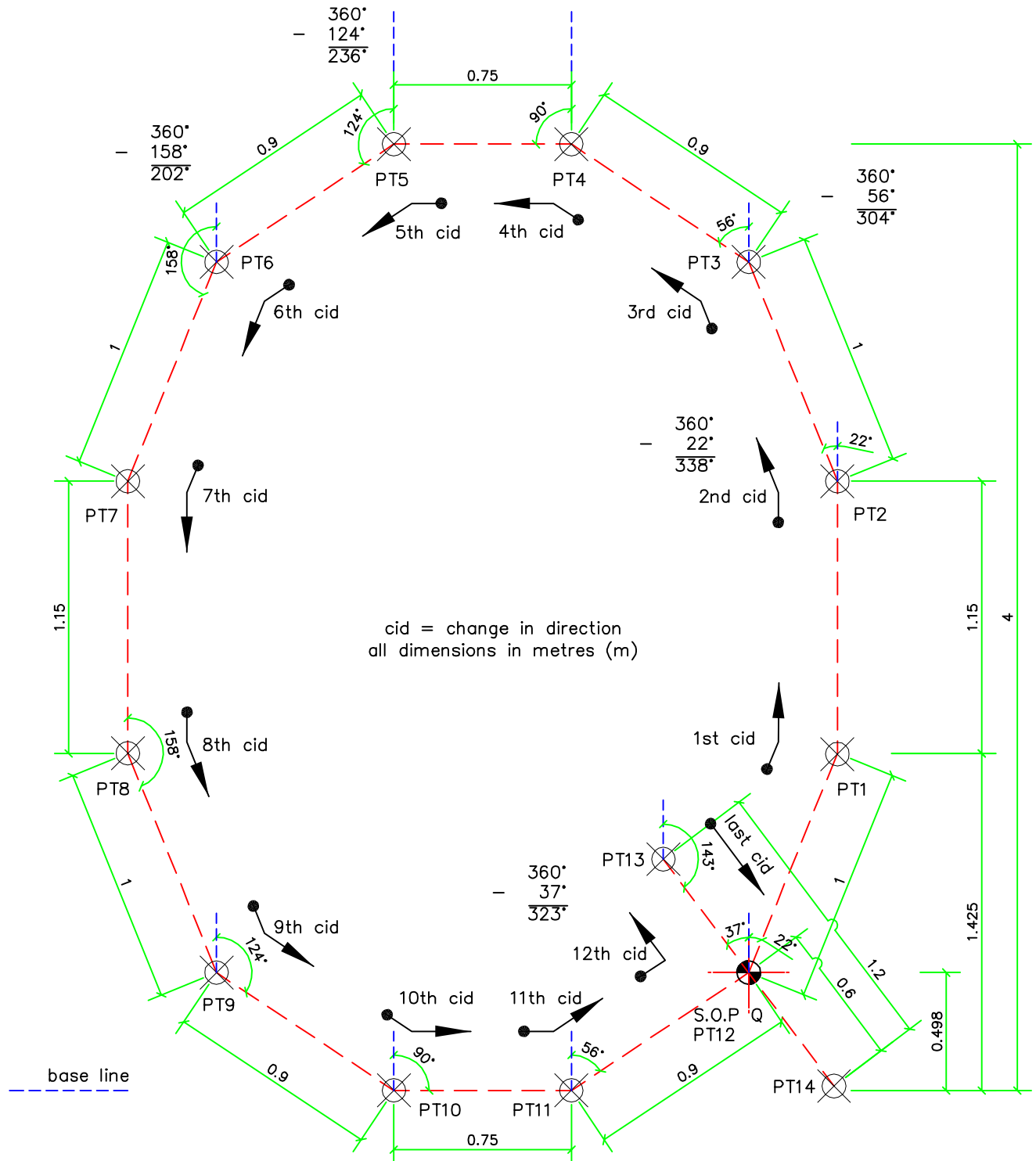
- | | | |
|--|------|------------------------|
| From S.O.P p walk 1.8m on a bearing of | 180° | and mark the location. |
| From PT1 Walk 4m on a bearing of | 0° | and mark the location. |
| From PT2 Walk 0.5m on a bearing of | 180° | and mark the location. |
| From PT3 Walk 0.75m on a bearing of | 48° | and mark the location. |
| From PT4 Walk 1m on a bearing of | 90° | and mark the location. |
| From PT5 Walk 0.75m on a bearing of | 132° | and mark the location. |
| From PT6 Walk 0.9m on a bearing of | 168° | and mark the location. |
| From PT7 Walk 0.9m on a bearing of | 192° | and mark the location. |
| From PT8 Walk 0.75m on a bearing of | 228° | and mark the location. |
| From PT9 Walk 1m on a bearing of | 270° | and mark the location. |
| From PT10 Walk 0.75m on a bearing of | 312° | and finish. |

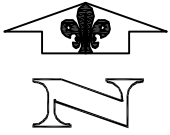




Micro navigation – letter Q

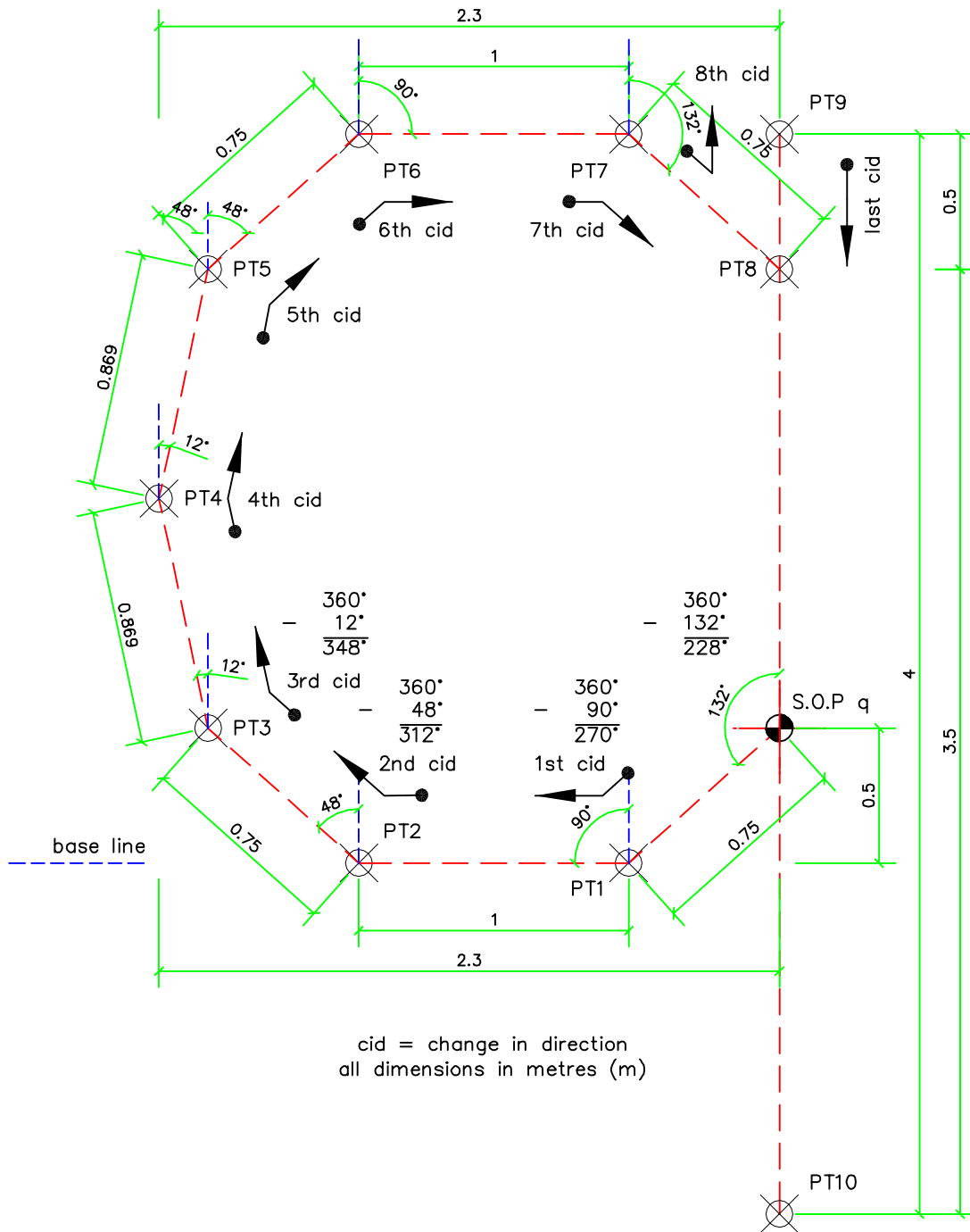
- | | | |
|--|------|-----------------------------------|
| From S.O.P Q walk 1.0m on a bearing of | 22° | and mark the location. |
| From PT1 Walk 1.15m on a bearing of | 0° | and mark the location. |
| From PT2 Walk 1.0m on a bearing of | 338° | and mark the location. |
| From PT3 Walk 0.9m on a bearing of | 304° | and mark the location. |
| From PT4 Walk 0.75m on a bearing of | 270° | and mark the location. |
| From PT5 Walk 0.9m on a bearing of | 236° | and mark the location. |
| From PT6 Walk 1.0m on a bearing of | 202° | and mark the location. |
| From PT7 Walk 1.15m on a bearing of | 180° | and mark the location. |
| From PT8 Walk 1.0m on a bearing of | 158° | and mark the location. |
| From PT9 Walk 0.9m on a bearing of | 124° | and mark the location. |
| From PT10 Walk 0.75m on a bearing of | 90° | and mark the location. |
| From PT11 Walk 0.9m on a bearing of | 56° | |
| From PT12 Walk 0.6m on a bearing of | 323° | and mark the location. |
| From PT13 Walk 1.2m on a bearing of | 143° | and mark the location and finish. |

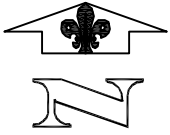




Micro navigation – letter q

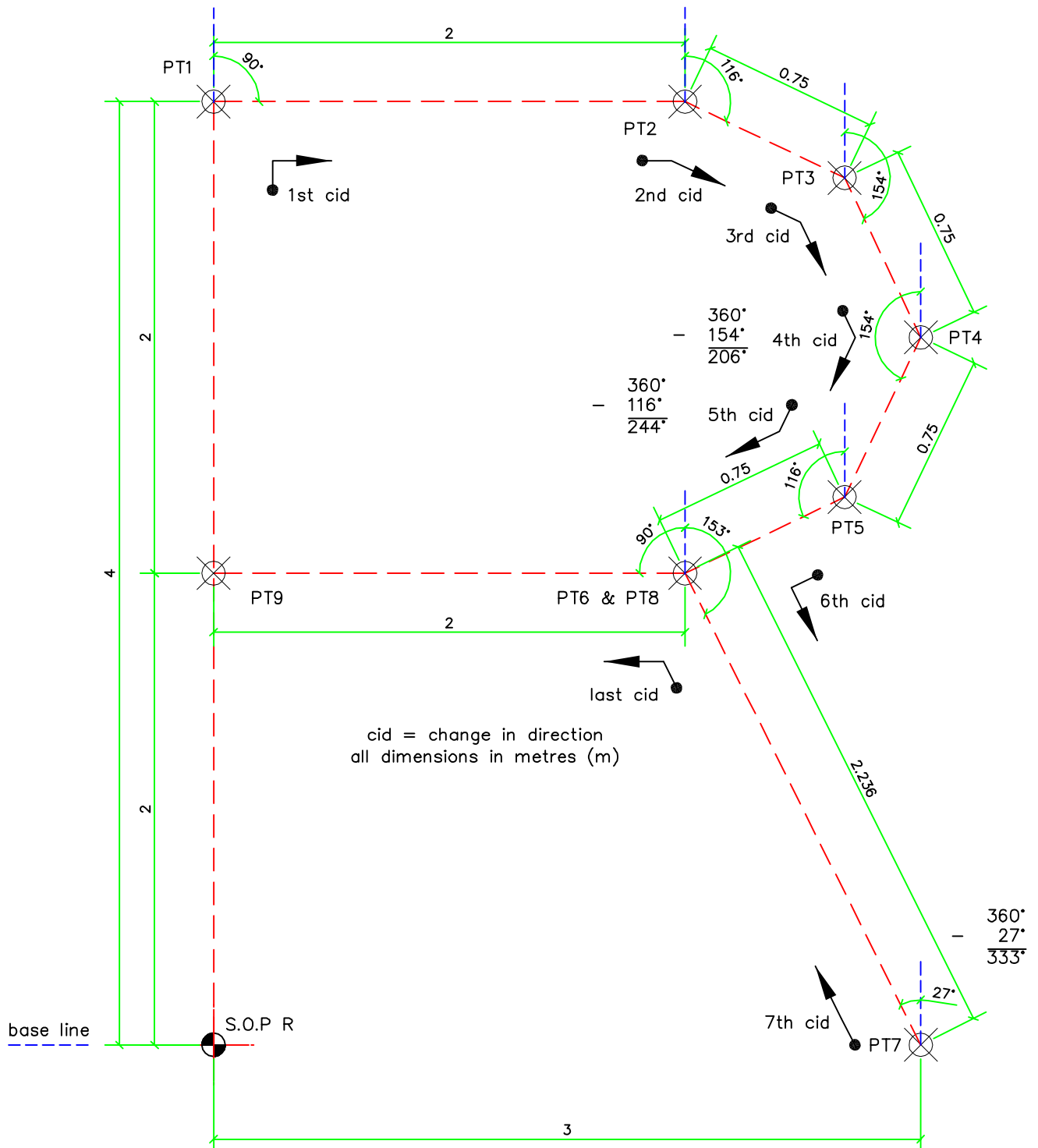
- From S.O.P q walk 0.75m on a bearing of 228° and mark the location.
- From PT1 Walk 1m on a bearing of 270° and mark the location.
- From PT2 Walk 0.75m on a bearing of 312° and mark the location.
- From PT3 Walk 0.9m on a bearing of 348° and mark the location.
- From PT4 Walk 0.9m on a bearing of 12° and mark the location.
- From PT5 Walk 0.75m on a bearing of 48° and mark the location.
- From PT6 Walk 1m on a bearing of 90° and mark the location.
- From PT7 Walk 0.75m on a bearing of 132° and mark the location.
- From PT8 Walk 0.5m on a bearing of 0° and mark the location.
- From PT9 Walk 4m on a bearing of 180° and mark the location and finish.

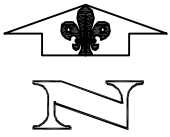




Micro navigation – letter R

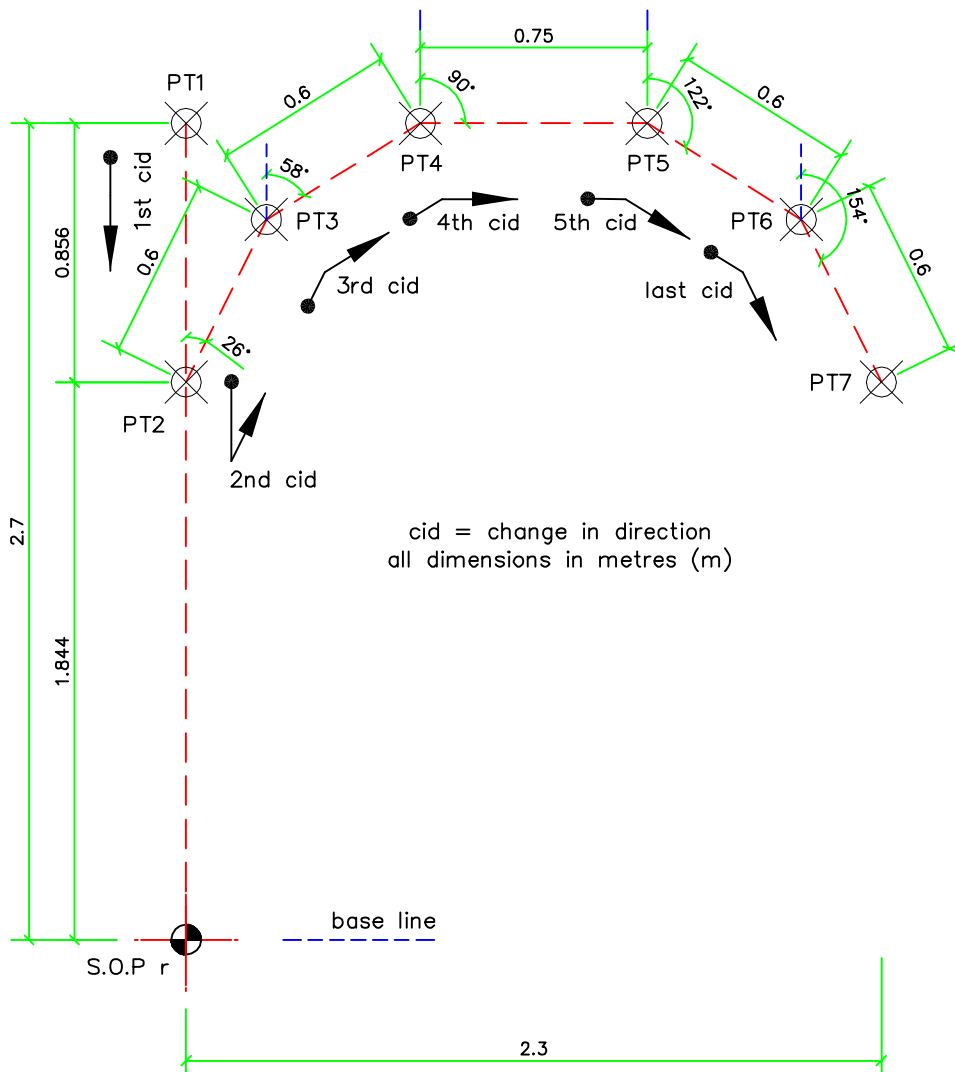
- From S.O.P R walk 4m on a bearing of 0° and mark the location.
- From PT1 Walk 2m on a bearing of 90° and mark the location.
- From PT2 Walk 0.75m on a bearing of 116° and mark the location.
- From PT3 Walk 0.75m on a bearing of 154° and mark the location.
- From PT4 Walk 0.75m on a bearing of 206° and mark the location.
- From PT5 Walk 0.75m on a bearing of 244° and mark the location.
- From PT6 Walk 2.2m on a bearing of 153° and mark the location.
- From PT7 Walk 2.2m on a bearing of 333° and mark the location.
- From PT8 Walk 2m on a bearing of 90° and mark the location and finish.

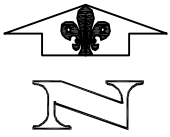




Micro navigation – letter r

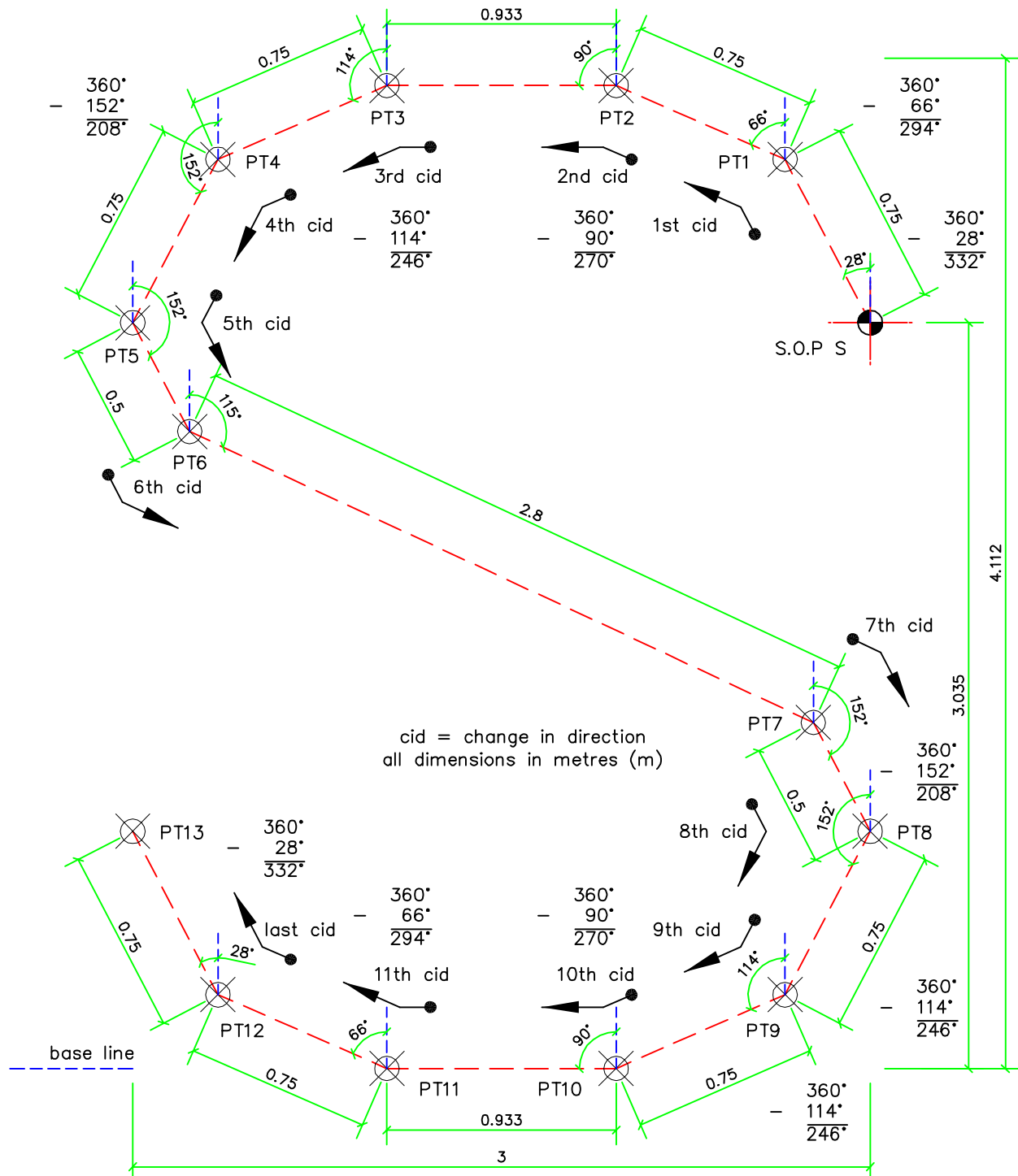
- From S.O.P r walk 2.7m on a bearing of 0° and mark the location.
- From PT1 Walk 0.9m on a bearing of 180° and mark the location.
- From PT2 Walk 0.6m on a bearing of 26° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.75m on a bearing of 90° and mark the location.
- From PT5 Walk 0.6m on a bearing of 122° and mark the location.
- From PT6 Walk 0.6m on a bearing of 154° and mark the location and finish.

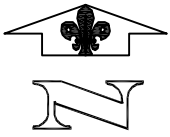




Micro navigation – letter S

From S.O.P S walk	0.75m on a bearing of	332°	and mark the location.
From PT1 Walk	0.75m on a bearing of	294°	and mark the location.
From PT2 Walk	0.9m on a bearing of	270°	and mark the location.
From PT3 Walk	0.75m on a bearing of	246°	and mark the location.
From PT4 Walk	0.75m on a bearing of	208°	and mark the location.
From PT5 Walk	0.5m on a bearing of	152°	and mark the location.
From PT6 Walk	2.8m on a bearing of	115°	and mark the location.
From PT7 Walk	0.5m on a bearing of	152°	and mark the location.
From PT8 Walk	0.75m on a bearing of	208°	and mark the location.
From PT9 Walk	0.75m on a bearing of	246°	and mark the location.
From PT10 Walk	0.9m on a bearing of	270°	and mark the location.
From PT11 Walk	0.75m on a bearing of	294°	and mark the location.
From PT12 Walk	0.75m on a bearing of	332°	and mark the location and finish.

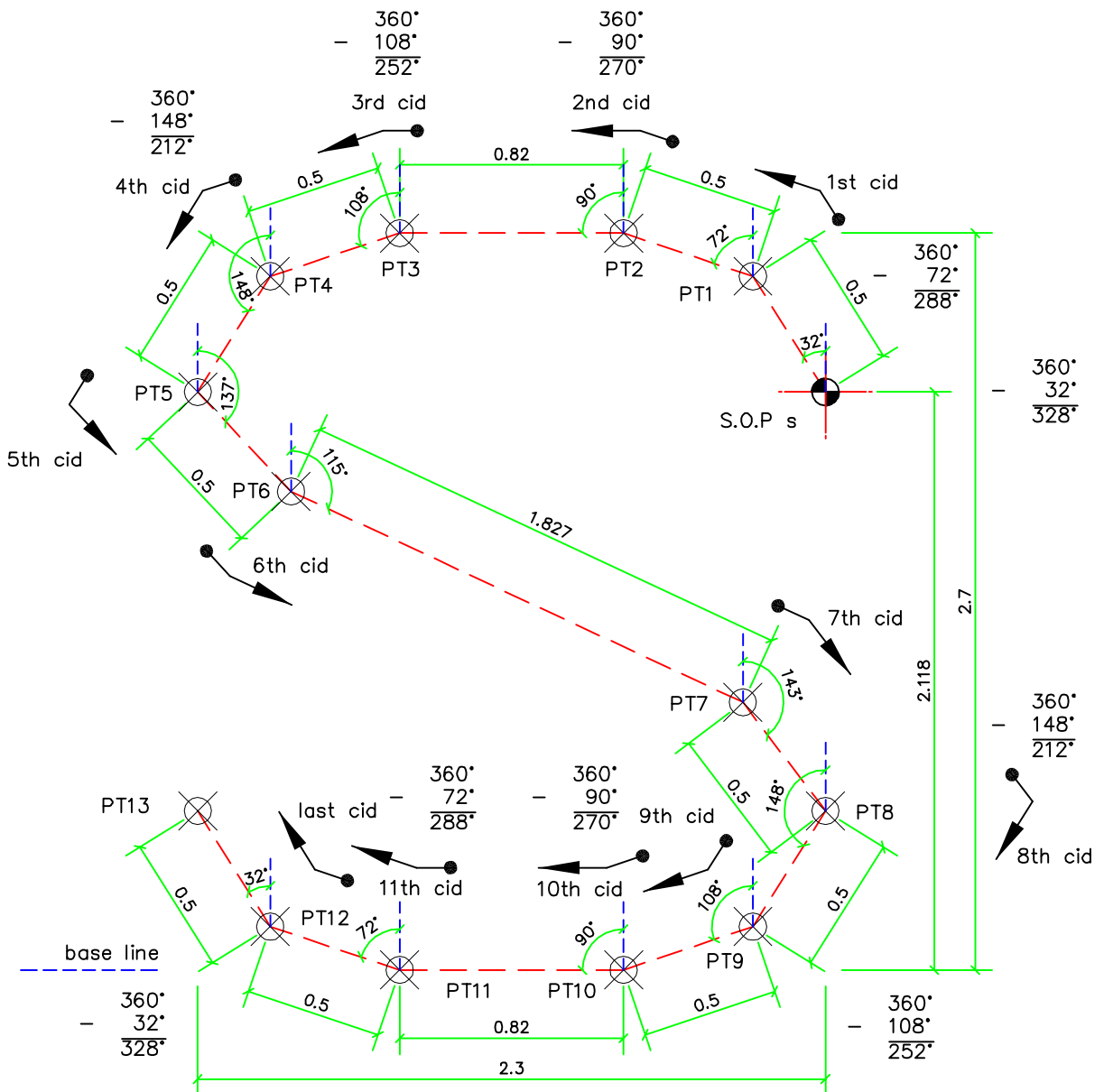


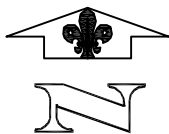


Micro navigation – letter s

From S.O.P s walk	0.5m on a bearing of	328°	and mark the location.
From PT1 Walk	0.5m on a bearing of	288°	and mark the location.
From PT2 Walk	0.8m on a bearing of	270°	and mark the location.
From PT3 Walk	0.5m on a bearing of	252°	and mark the location.
From PT4 Walk	0.5m on a bearing of	212°	and mark the location.
From PT5 Walk	0.5m on a bearing of	137°	and mark the location.
From PT6 Walk	1.8m on a bearing of	115°	and mark the location.
From PT7 Walk	0.5m on a bearing of	143°	and mark the location.
From PT8 Walk	0.5m on a bearing of	212°	and mark the location.
From PT9 Walk	0.5m on a bearing of	252°	and mark the location.
From PT10 Walk	0.8m on a bearing of	270°	and mark the location.
From PT11 Walk	0.5m on a bearing of	288°	and mark the location.
From PT12 Walk	0.5m on a bearing of	328°	and mark the location and finish.

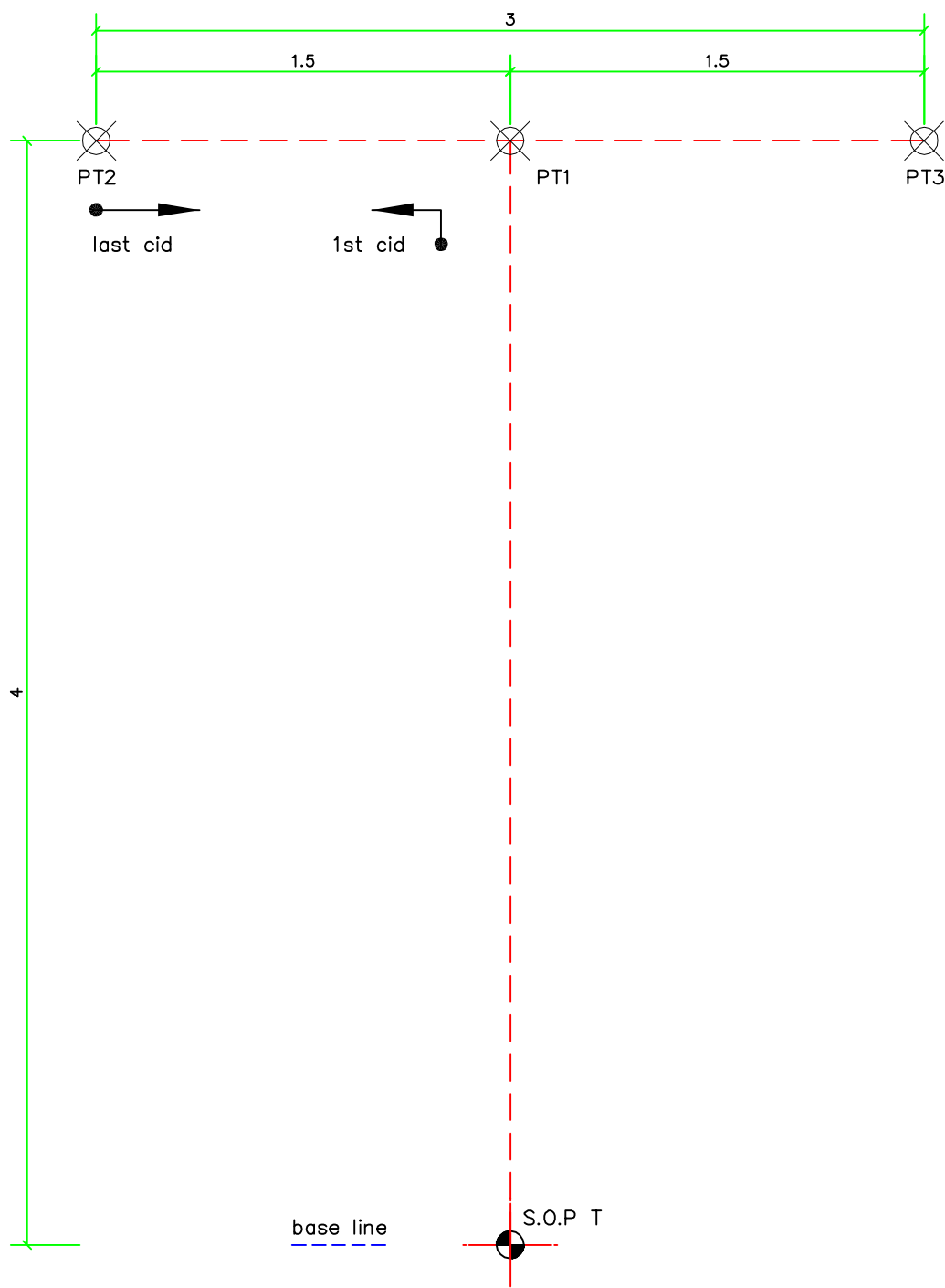
cid = change in direction
all dimensions in metres (m)



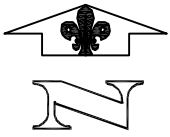


Micro navigation – letter T

From S.O.P T walk 4m on a bearing of 0° and mark the location.
 From PT1 Walk 1.5m on a bearing of 270° and mark the location.
 From PT2 Walk 3m on a bearing of 90° and mark the location and finish.

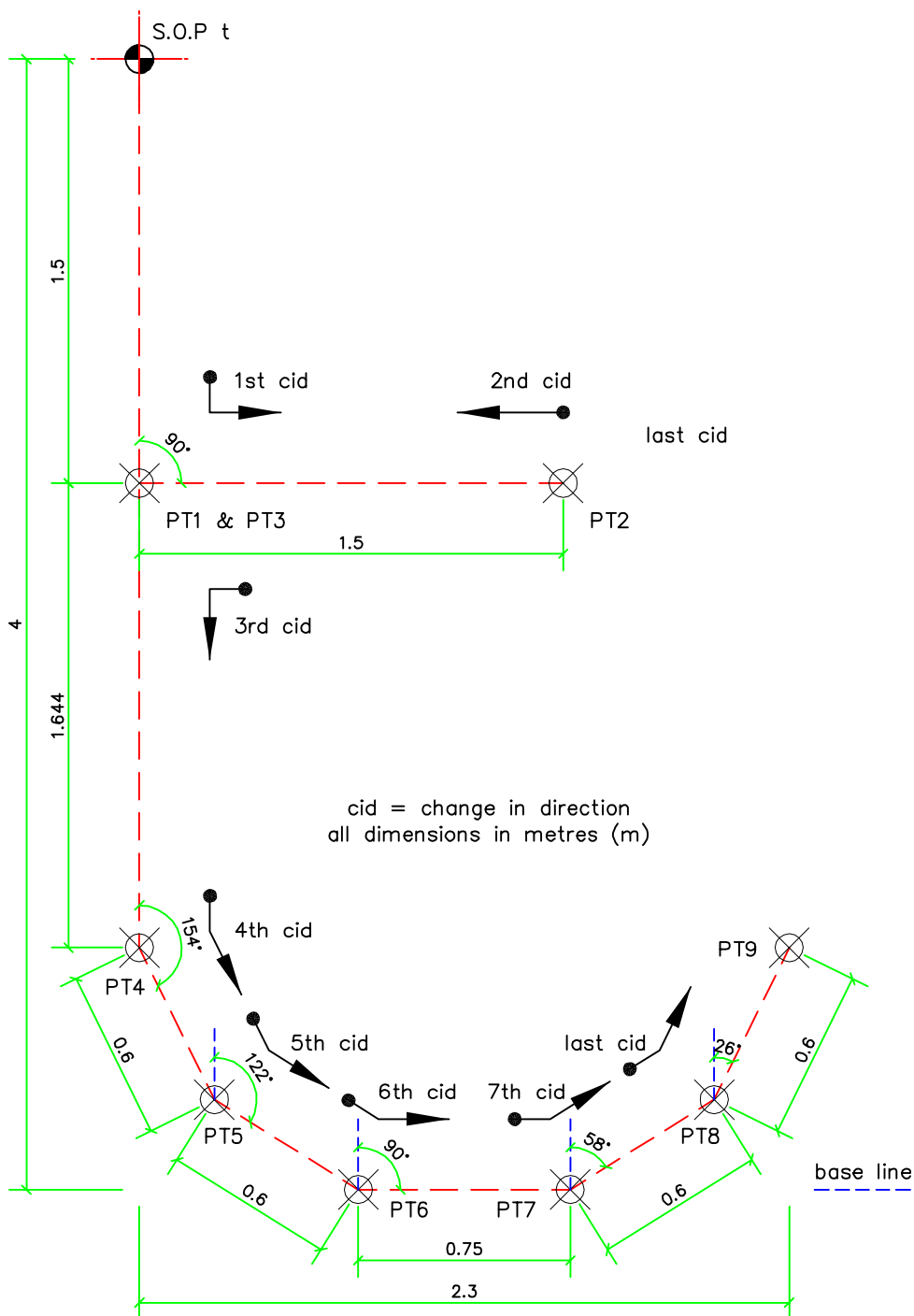


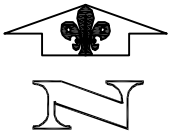
cid = change in direction
 all dimensions in metres (m)



Micro navigation – letter t

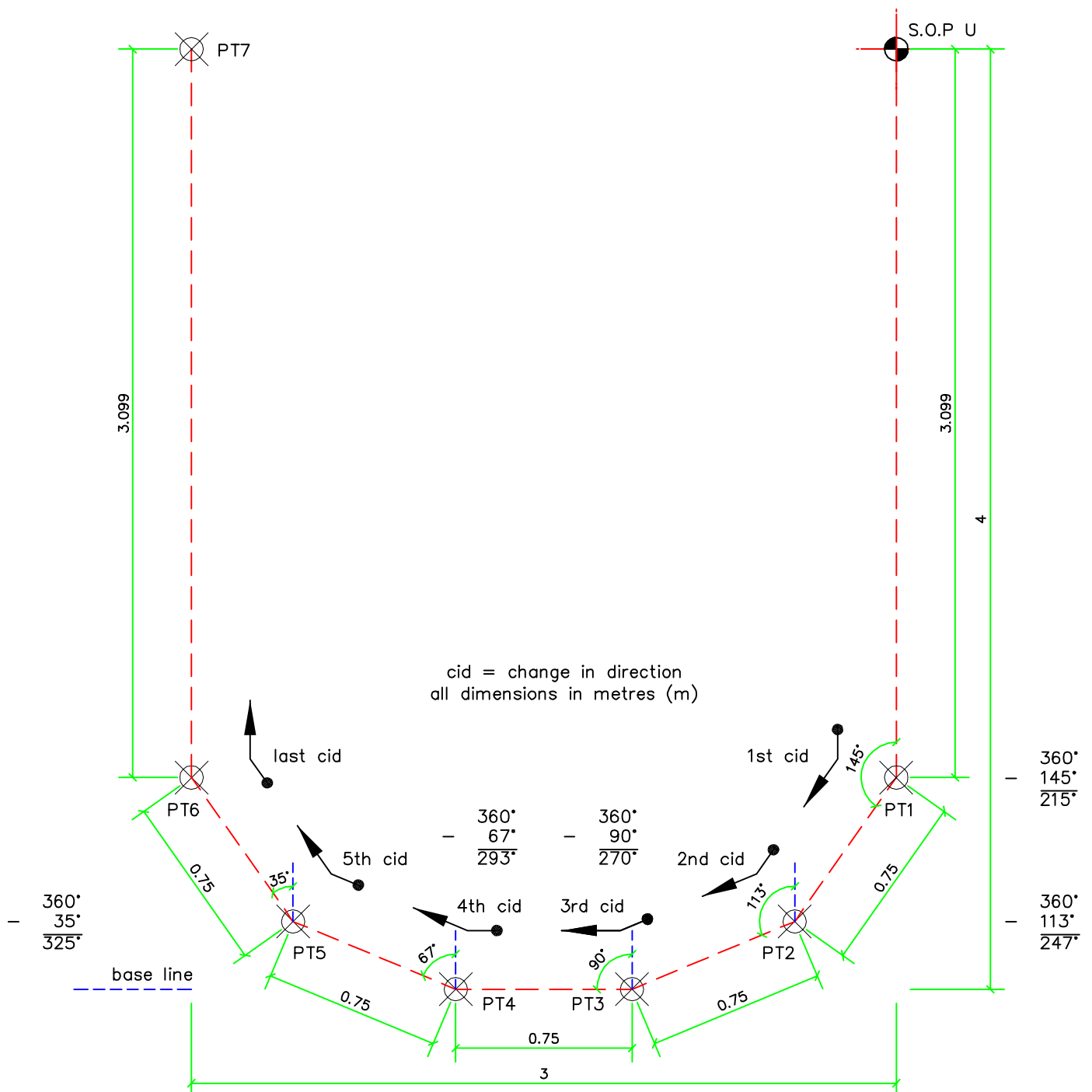
- From S.O.P t walk 1.5m on a bearing of 180° and mark the location.
- From PT1 Walk 1.5m on a bearing of 90° and mark the location.
- From PT2 Walk 1.5m on a bearing of 270° .
- From PT3 Walk 1.6m on a bearing of 180° and mark the location.
- From PT4 Walk 0.6m on a bearing of 154° and mark the location.
- From PT5 Walk 0.6m on a bearing of 122° and mark the location.
- From PT6 Walk 0.75m on a bearing of 90° and mark the location.
- From PT7 Walk 0.6m on a bearing of 58° and mark the location.
- From PT8 Walk 0.6m on a bearing of 26° and mark the location and finish.

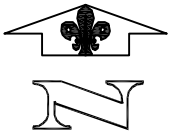




Micro navigation – letter U

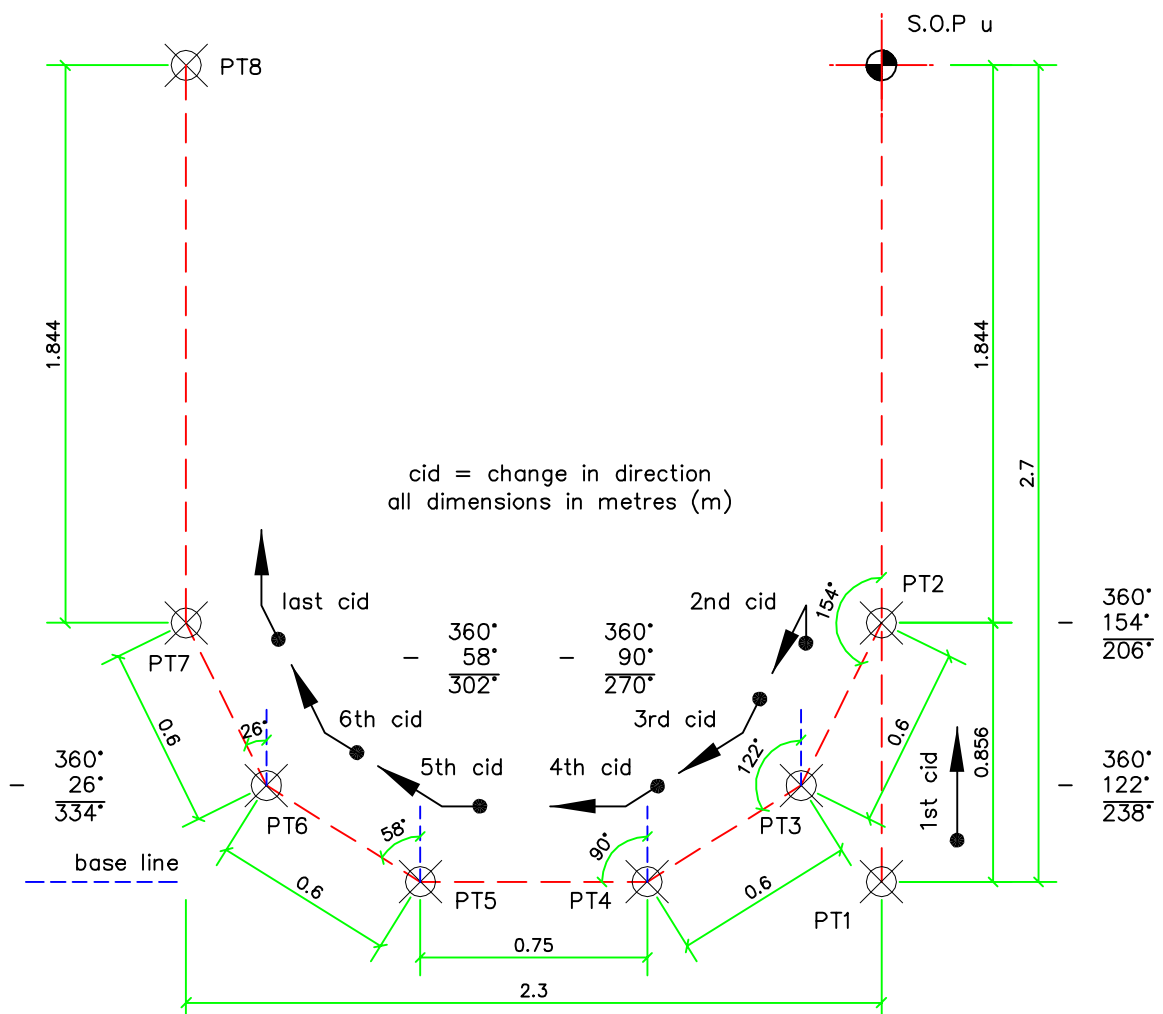
- From S.O.P U walk 3.1m on a bearing of 180° and mark the location.
- From PT1 Walk 0.75m on a bearing of 215° and mark the location.
- From PT2 Walk 0.75m on a bearing of 247° and mark the location.
- From PT3 Walk 0.75m on a bearing of 270° and mark the location.
- From PT4 Walk 0.75m on a bearing of 293° and mark the location.
- From PT5 Walk 0.75m on a bearing of 325° and mark the location.
- From PT6 Walk 3.1m on a bearing of 0° and mark the location and finish.

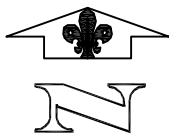




Micro navigation – letter u

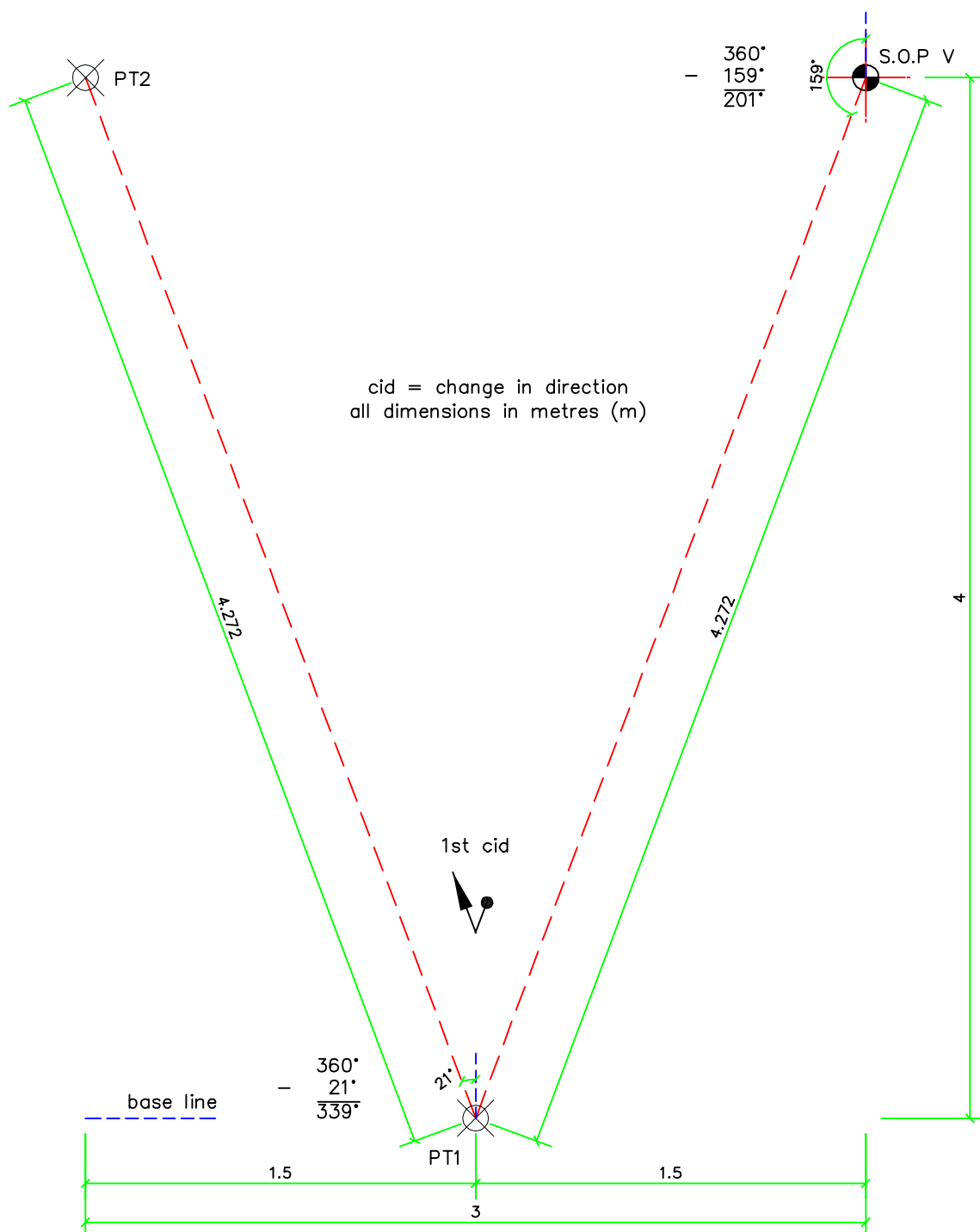
From S.O.P u walk	2.7m on a bearing of	180°	and mark the location.
From PT1 Walk	0.9m on a bearing of	0°	and mark the location.
From PT2 Walk	0.6m on a bearing of	206°	and mark the location.
From PT3 Walk	0.6m on a bearing of	238°	and mark the location.
From PT4 Walk	0.75m on a bearing of	270°	and mark the location.
From PT5 Walk	0.6m on a bearing of	302°	and mark the location.
From PT6 Walk	0.6m on a bearing of	334°	and mark the location.
From PT7 Walk	1.8m on a bearing of	0°	and mark the location and finish.

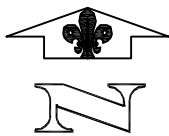




Micro navigation – letter V

From S.O.P V walk 4.3m on a bearing of 201° and mark the location.
 From PT1 Walk 4.3m on a bearing of 339° and mark the location and finish.

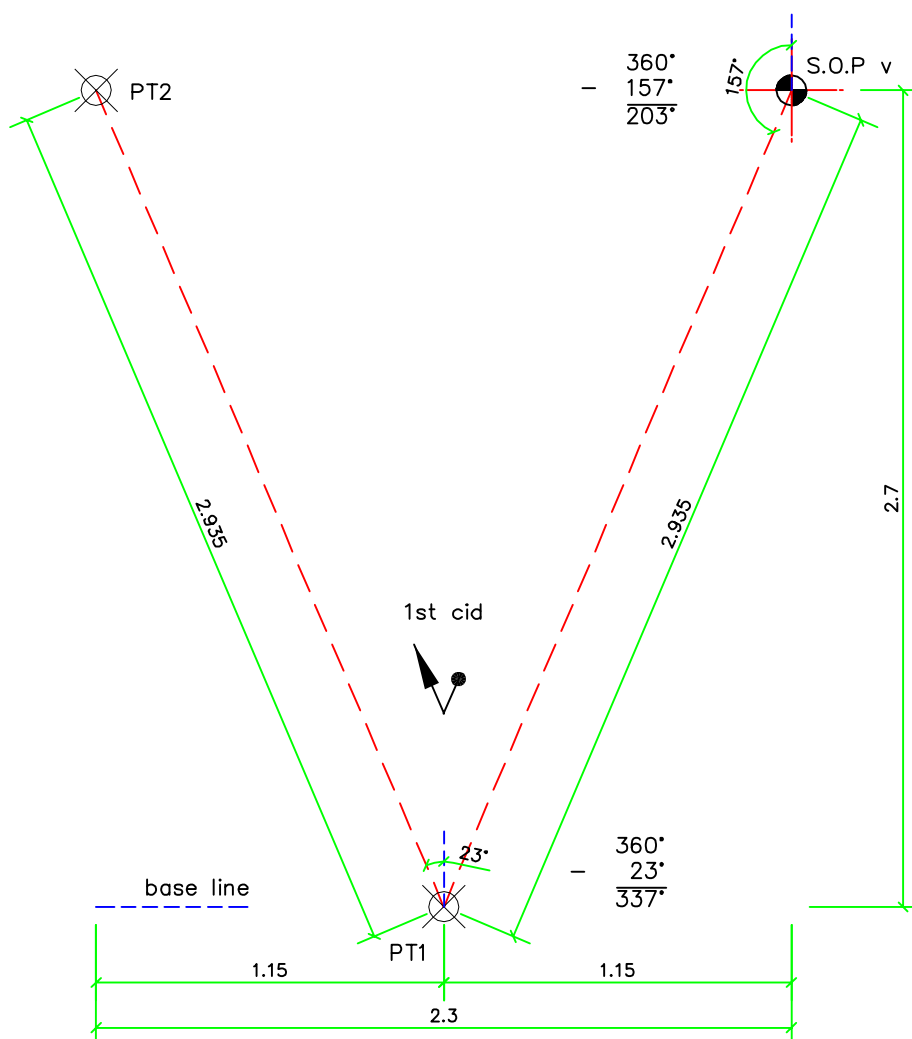


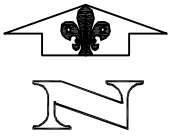


Micro navigation – letter v

From S.O.P v walk 2.9m on a bearing of 203° and mark the location.
 From PT1 Walk 2.9m on a bearing of 337° and mark the location and finish.

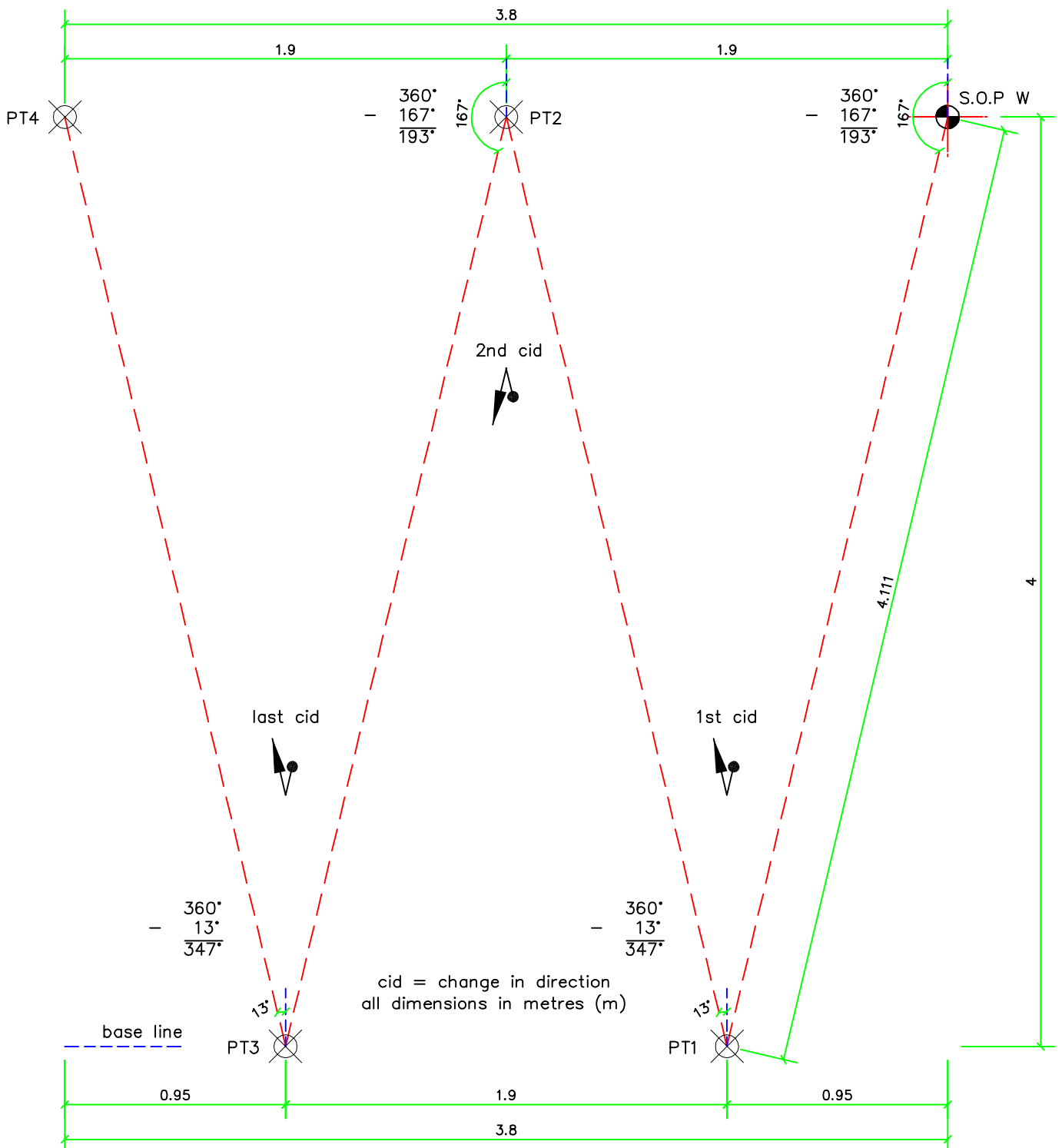
cid = change in direction
 all dimensions in metres (m)

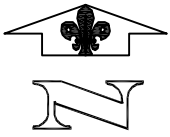




Micro navigation – letter W

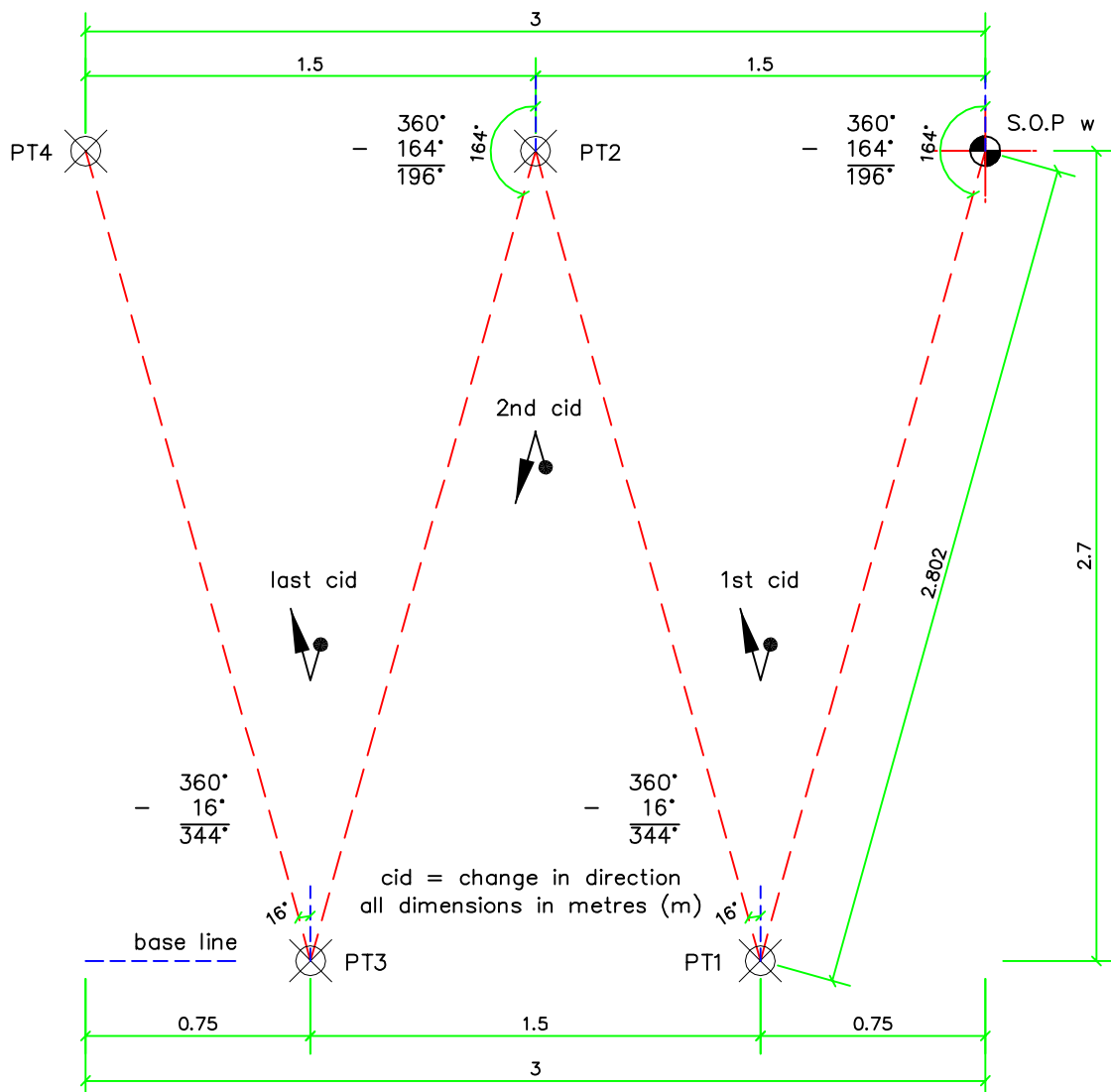
- From S.O.P W walk 4.1m on a bearing of 193° and mark the location.
- From PT1 Walk 4.1m on a bearing of 347° and mark the location.
- From PT2 Walk 4.1m on a bearing of 193° and mark the location.
- From PT3 Walk 4.1m on a bearing of 347° and mark the location and finish.

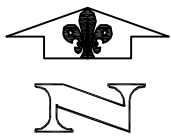




Micro navigation – letter w

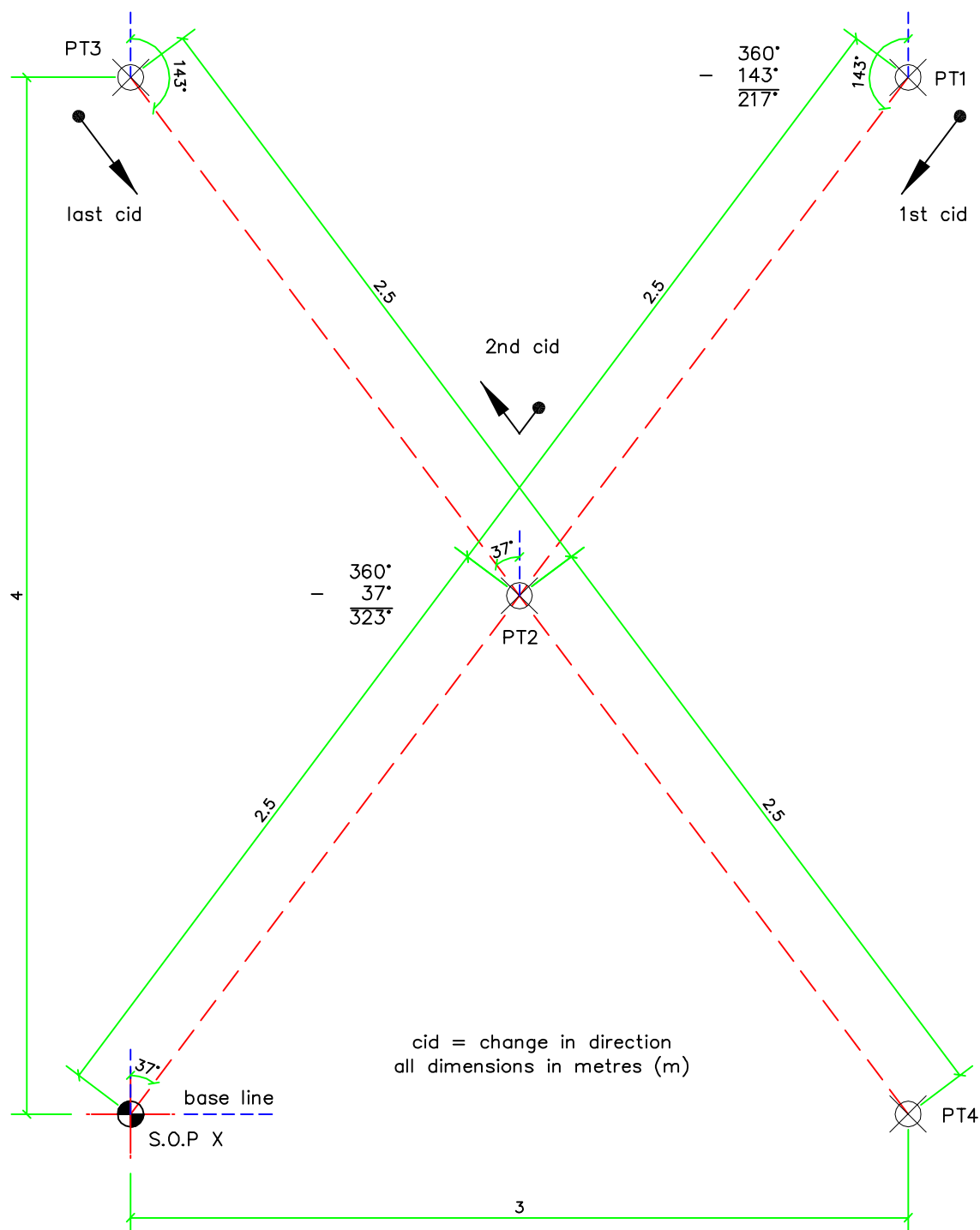
- From S.O.P w walk 2.8m on a bearing of 196° and mark the location.
- From PT1 Walk 2.8m on a bearing of 344° and mark the location.
- From PT2 Walk 2.8m on a bearing of 196° and mark the location.
- From PT3 Walk 2.8m on a bearing of 344° and mark the location and finish.

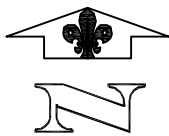




Micro navigation – letter X

- From S.O.P X walk 5m on a bearing of 37° and mark the location.
- From PT1 Walk 2.5m on a bearing of 217° and mark the location.
- From PT2 Walk 2.5m on a bearing of 323° and mark the location.
- From PT3 Walk 5m on a bearing of 143° and mark the location.

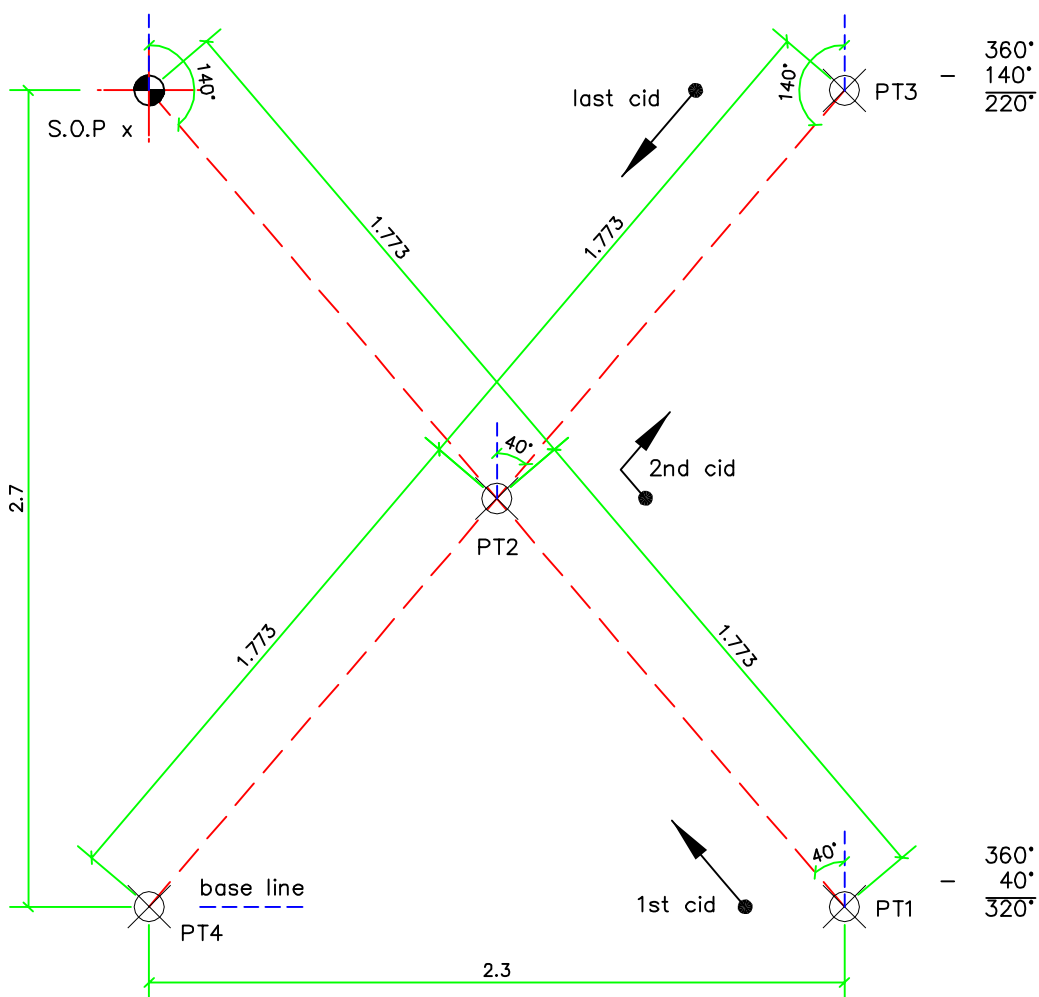


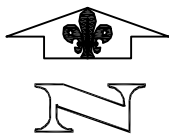


Micro navigation – letter x

- From S.O.P x walk 3.6m on a bearing of 140° and mark the location.
- From PT1 Walk 1.8m on a bearing of 320° and mark the location.
- From PT2 Walk 1.8m on a bearing of 40° and mark the location.
- From PT3 Walk 3.6m on a bearing of 220° and mark the location and finish.

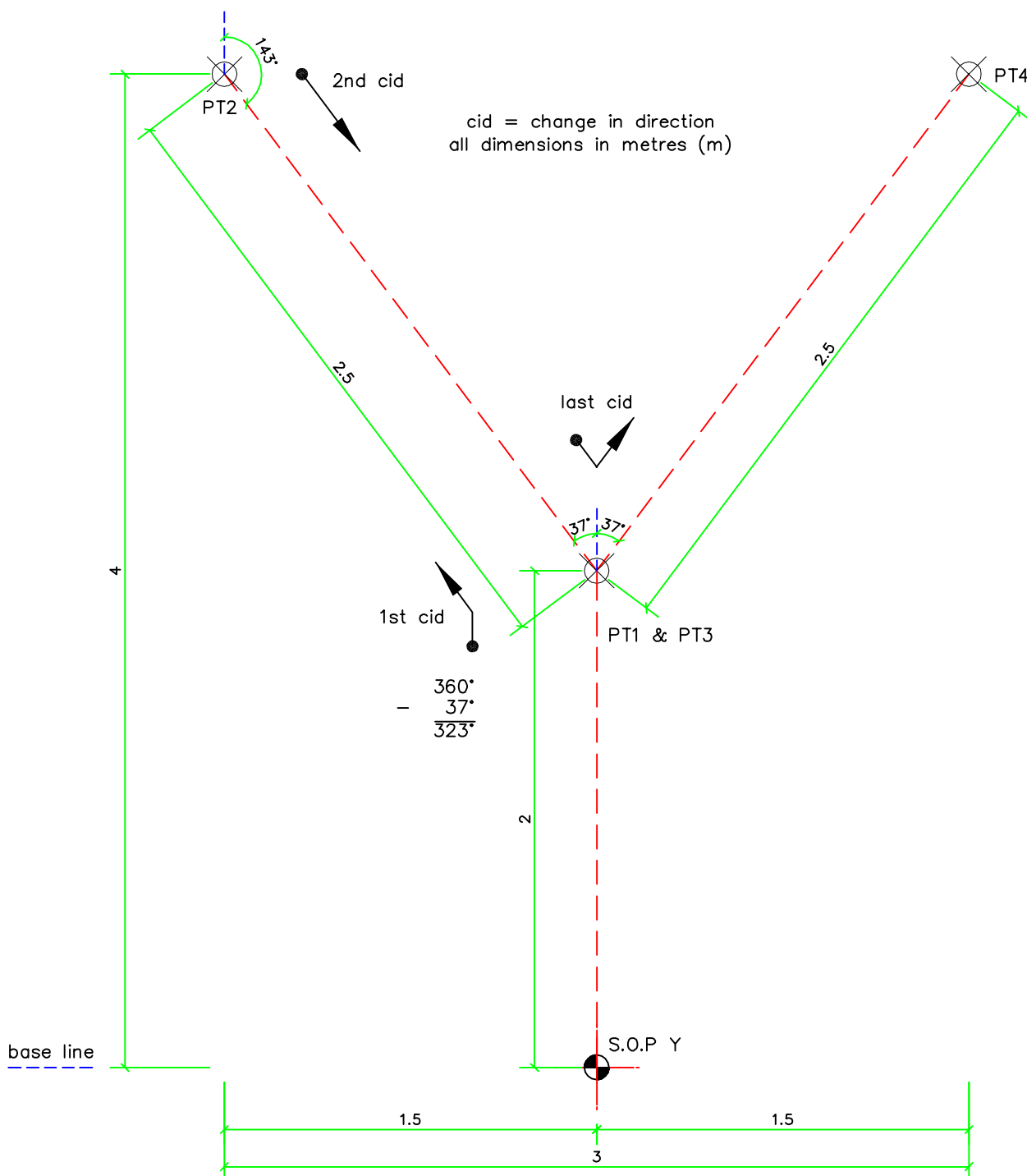
cid = change in direction
all dimensions in metres (m)

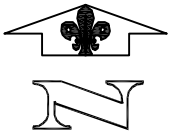




Micro navigation – letter Y

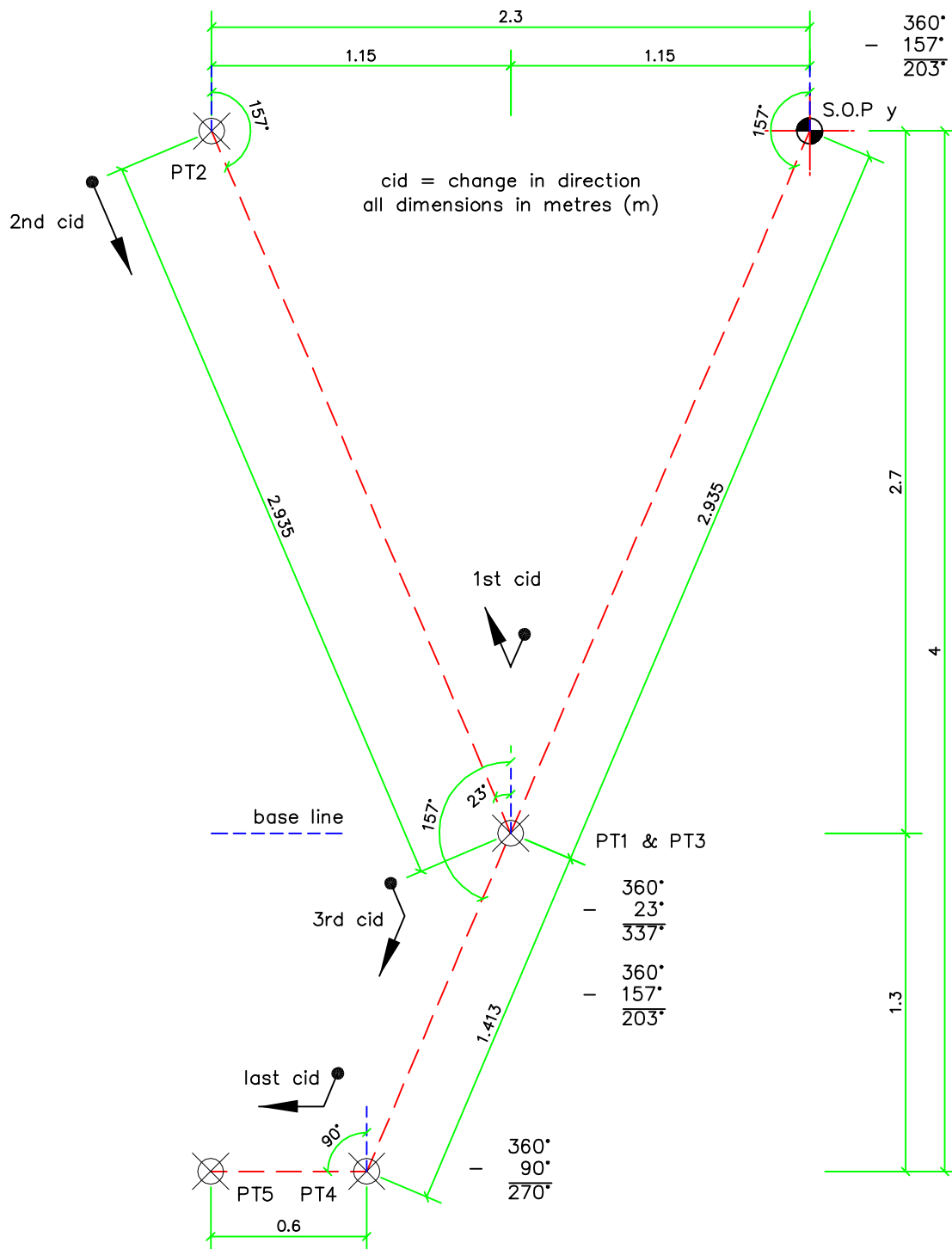
- From S.O.P Y walk 2m on a bearing of 0° and mark the location.
- From PT1 Walk 2.5m on a bearing of 323° and mark the location.
- From PT2 Walk 2.5m on a bearing of 143° .
- From PT3 Walk 2.5m on a bearing of 37° and mark the location and finish.

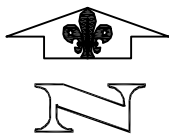




Micro navigation – letter y

- From S.O.P y walk 2.9m on a bearing of 203° and mark the location.
- From PT1 Walk 2.9m on a bearing of 337° and mark the location.
- From PT2 Walk 2.9m on a bearing of 157° .
- From PT3 Walk 1.4m on a bearing of 203° and mark the location.
- From PT4 Walk 0.6m on a bearing of 270° and mark the location and finish.

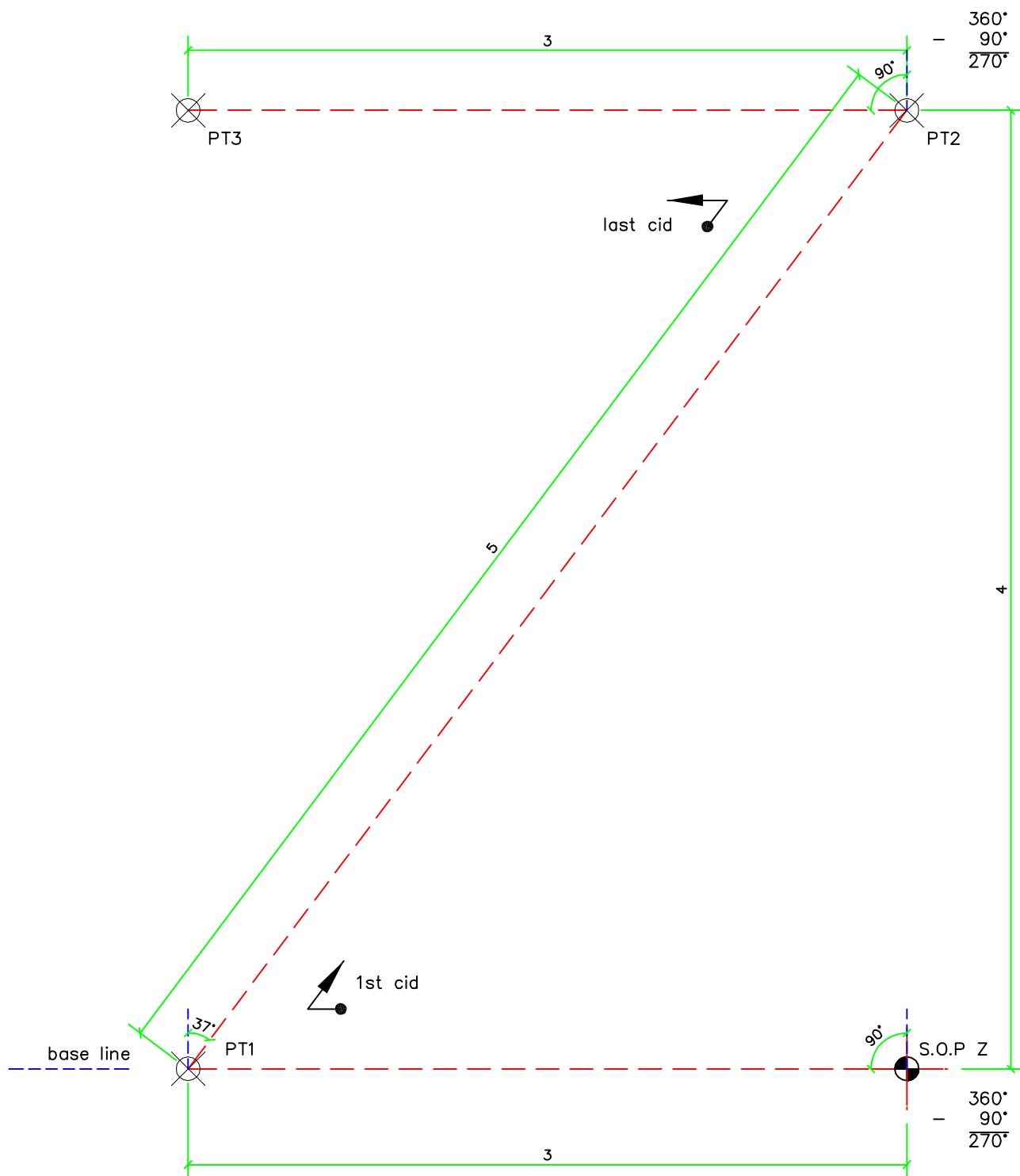


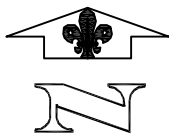


Micro navigation – letter Z

- From S.O.P Z walk 3m on a bearing of 270° and mark the location.
- From PT1 Walk 5m on a bearing of 37° and mark the location.
- From PT2 Walk 3m on a bearing of 270° and mark the location and finish.

cid = change in direction
all dimensions in metres (m)

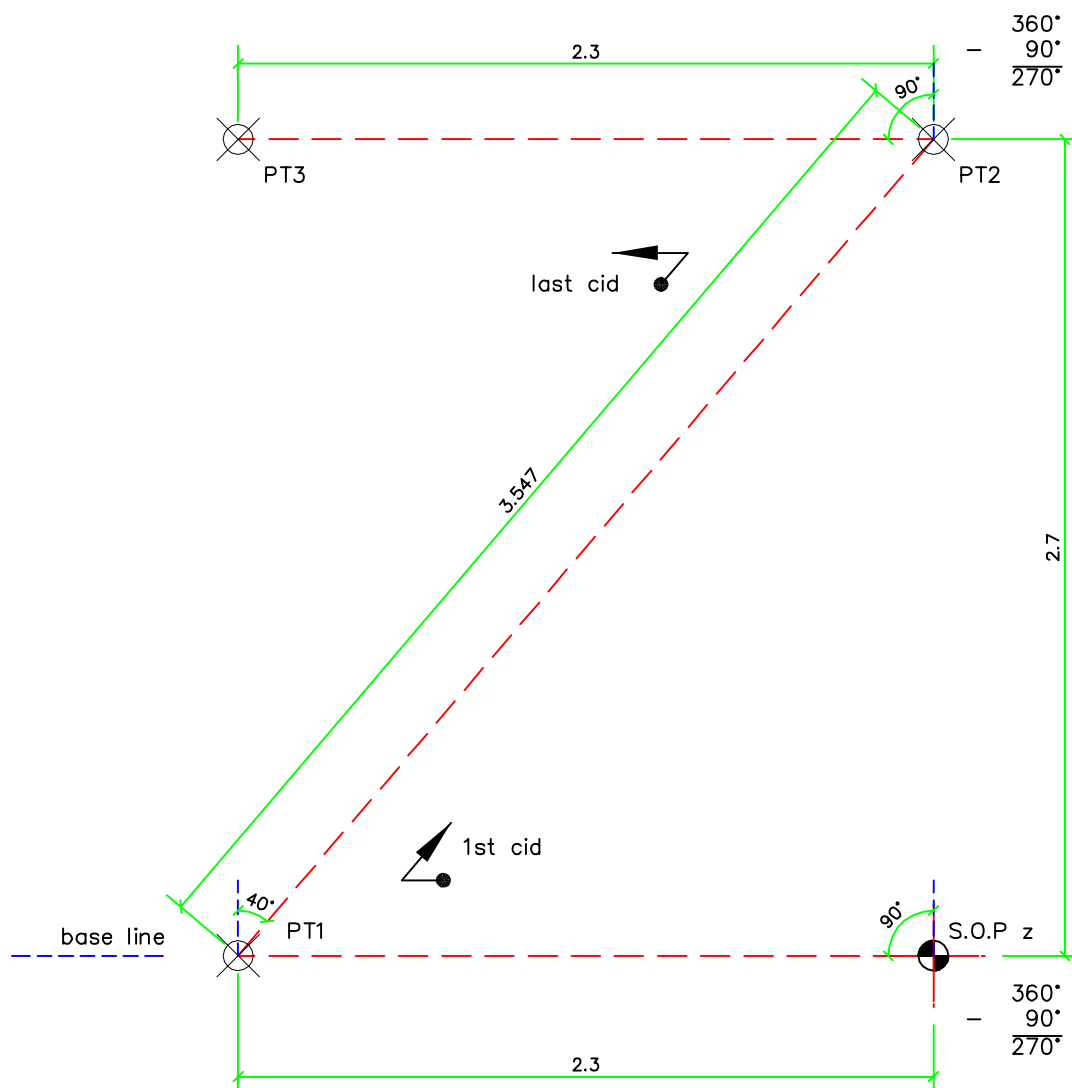


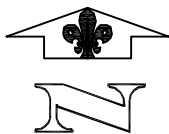


Micro navigation – letter z

- From S.O.P z walk 2.3m on a bearing of 270° and mark the location.
- From PT1 Walk 3.5m on a bearing of 40° and mark the location.
- From PT2 Walk 2.3m on a bearing of 270° and mark the location and finish.

cid = change in direction
all dimensions in metres (m)

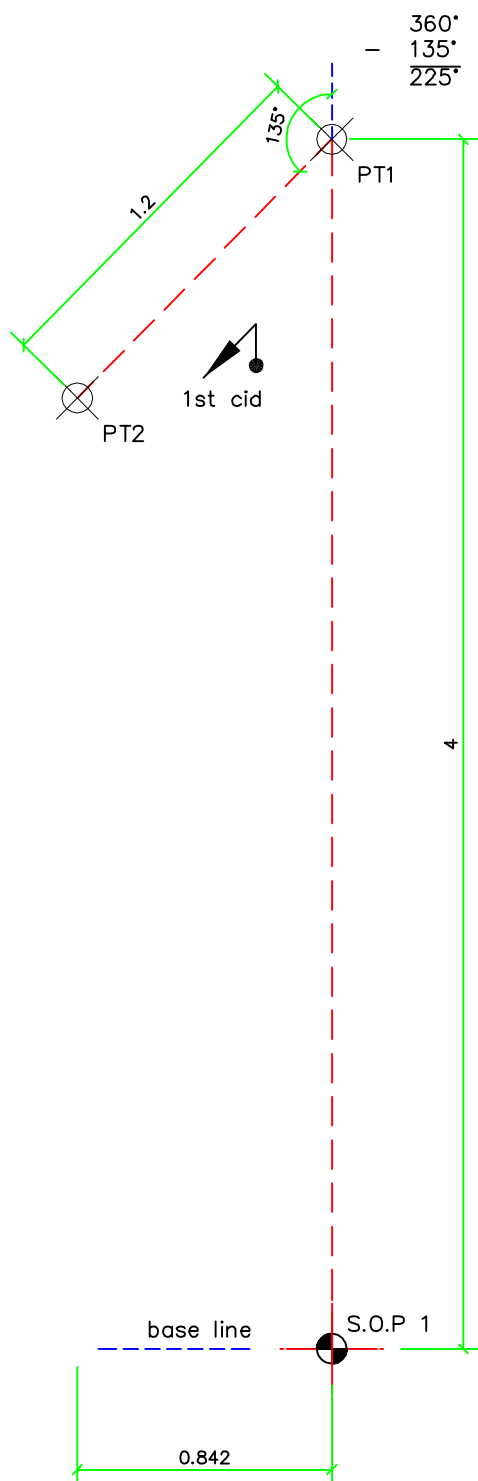


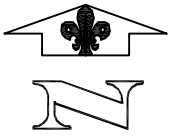


Micro navigation – number 1

From S.O.P 1 walk 4m on a bearing of 0° and mark the location.
 From PT1 Walk 1.2m on a bearing of 225° and mark the location.

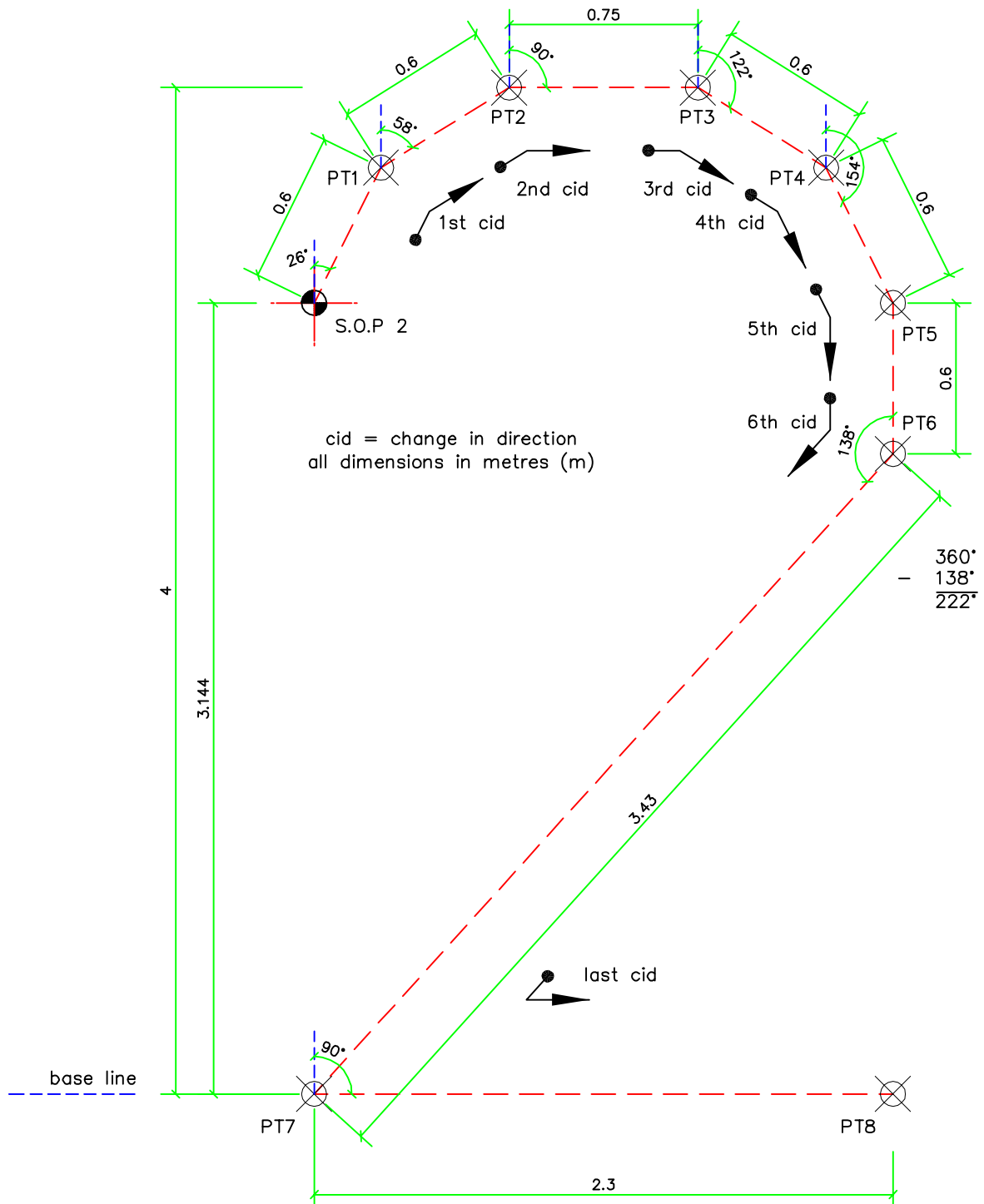
cid = change in direction
 all dimensions in metres (m)

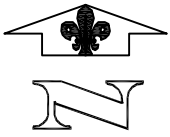




Micro navigation – number 2

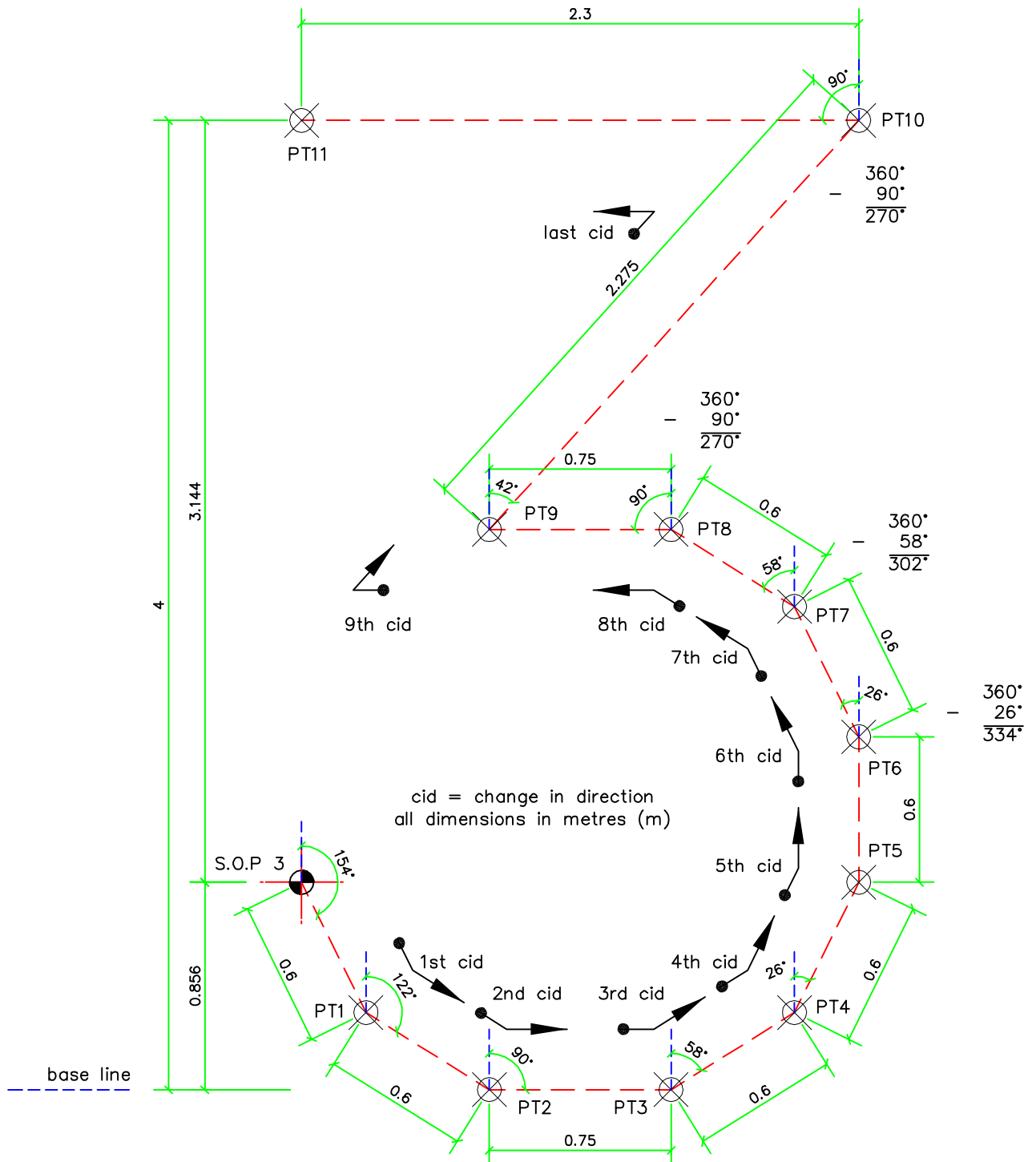
- | | | |
|--------------|--------------------------------|-----------------------------------|
| From S.O.P 2 | walk 0.6m on a bearing of 26° | and mark the location. |
| From PT1 | Walk 0.6m on a bearing of 58° | and mark the location. |
| From PT2 | Walk 0.75m on a bearing of 90° | and mark the location. |
| From PT3 | Walk 0.6m on a bearing of 122° | and mark the location. |
| From PT4 | Walk 0.6m on a bearing of 154° | and mark the location. |
| From PT5 | Walk 0.6m on a bearing of 180° | and mark the location. |
| From PT6 | Walk 3.4m on a bearing of 222° | and mark the location. |
| From PT7 | Walk 2.3m on a bearing of 90° | and mark the location and finish. |

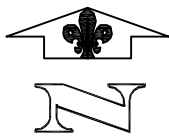




Micro navigation – number 3

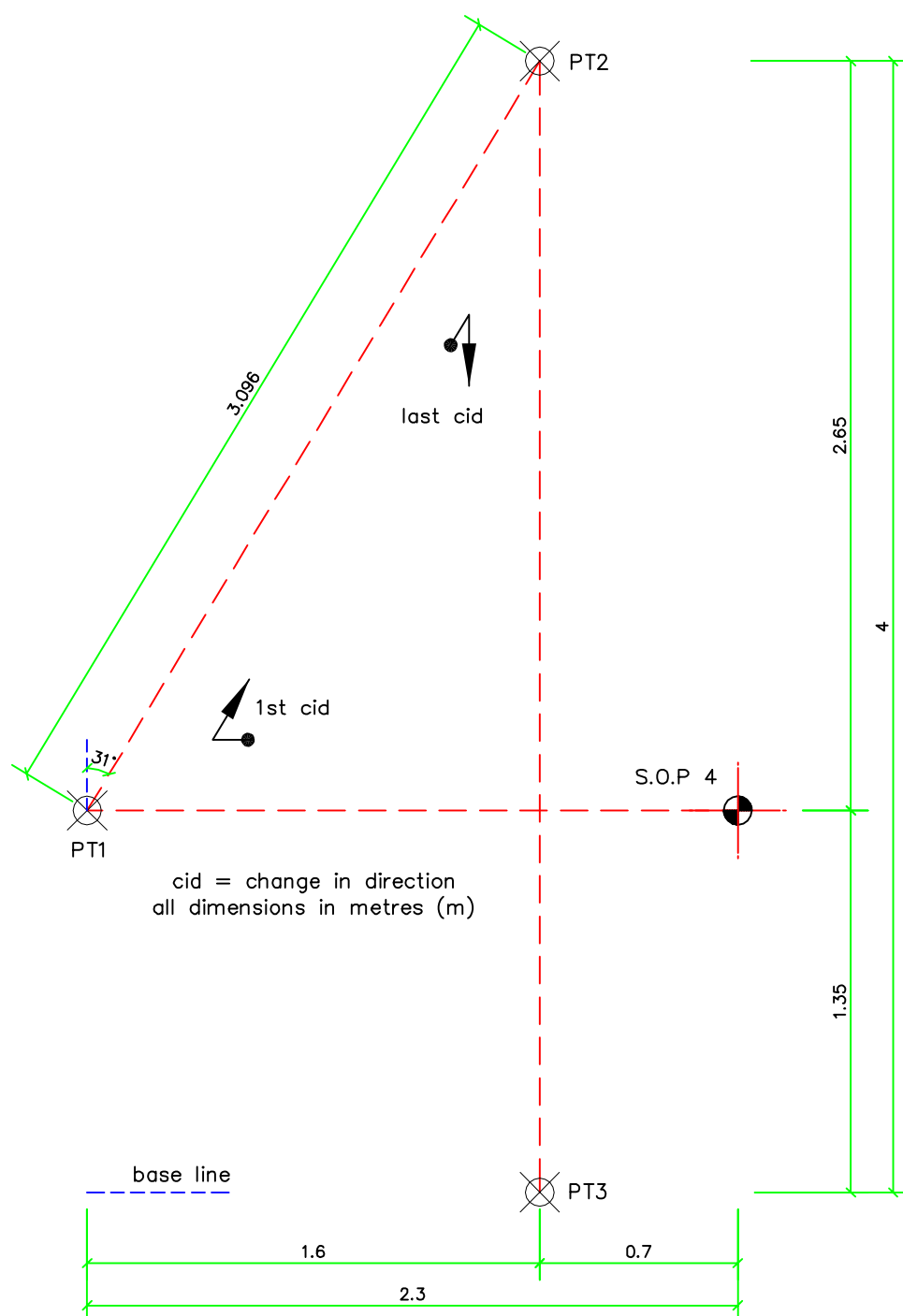
- From S.O.P 3 walk 0.6m on a bearing of 154° and mark the location.
- From PT1 Walk 0.6m on a bearing of 122° and mark the location.
- From PT2 Walk 0.75m on a bearing of 90° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.6m on a bearing of 26° and mark the location.
- From PT5 Walk 0.6m on a bearing of 0° and mark the location.
- From PT6 Walk 0.6m on a bearing of 334° and mark the location.
- From PT7 Walk 0.6m on a bearing of 302° and mark the location.
- From PT8 Walk 0.6m on a bearing of 270° and mark the location.
- From PT9 Walk 0.75m on a bearing of 42° and mark the location.
- From PT10 Walk 2.3m on a bearing of 270° and mark the location and finish.

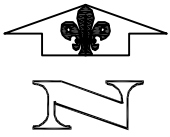




Micro navigation – number 4

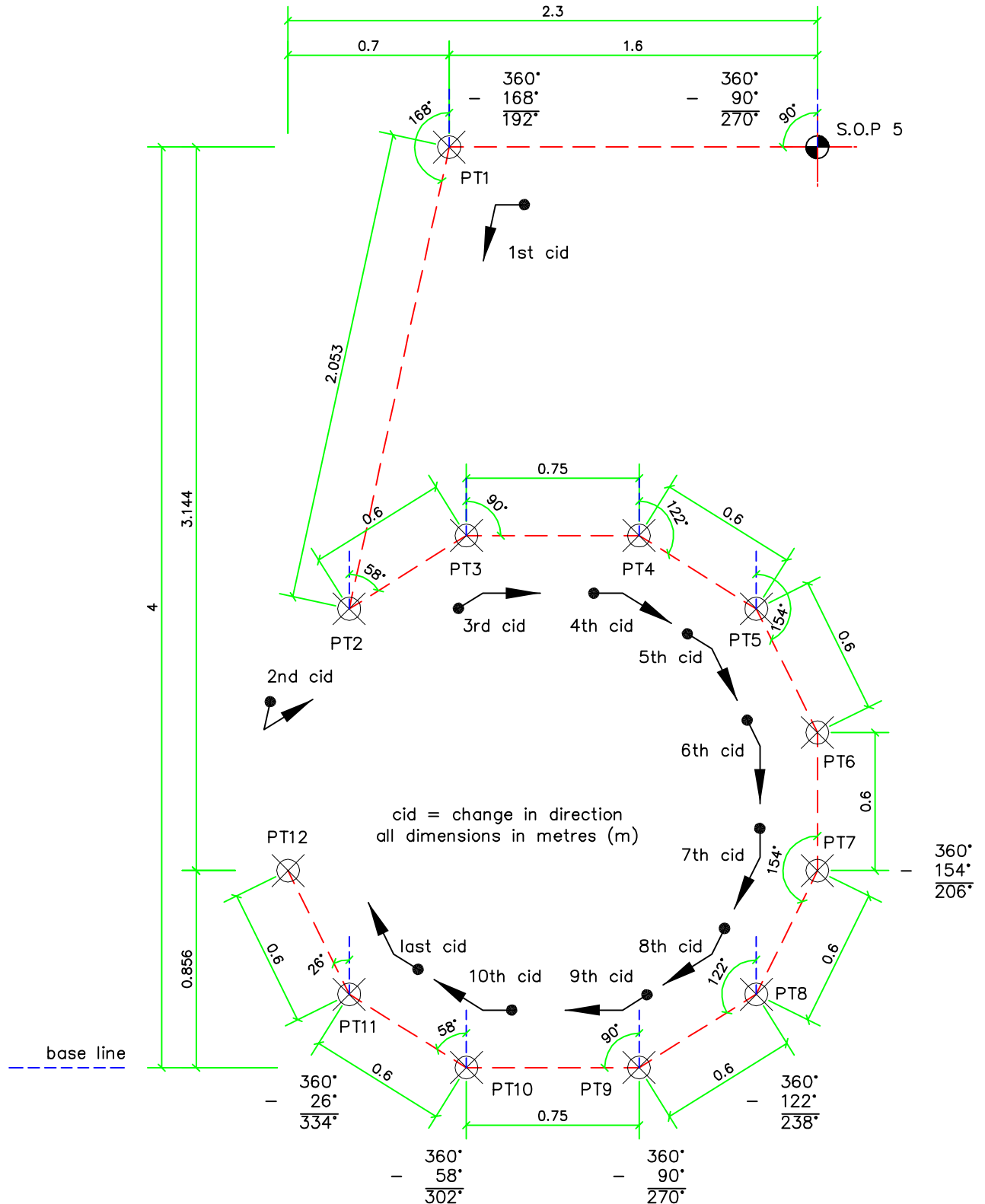
- From S.O.P 4 walk 2.3m on a bearing of 270° and mark the location.
- From PT1 Walk 3.1m on a bearing of 31° and mark the location.
- From PT2 Walk 4m on a bearing of 180° and mark the location and finish.

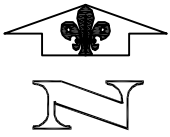




Micro navigation – number 5

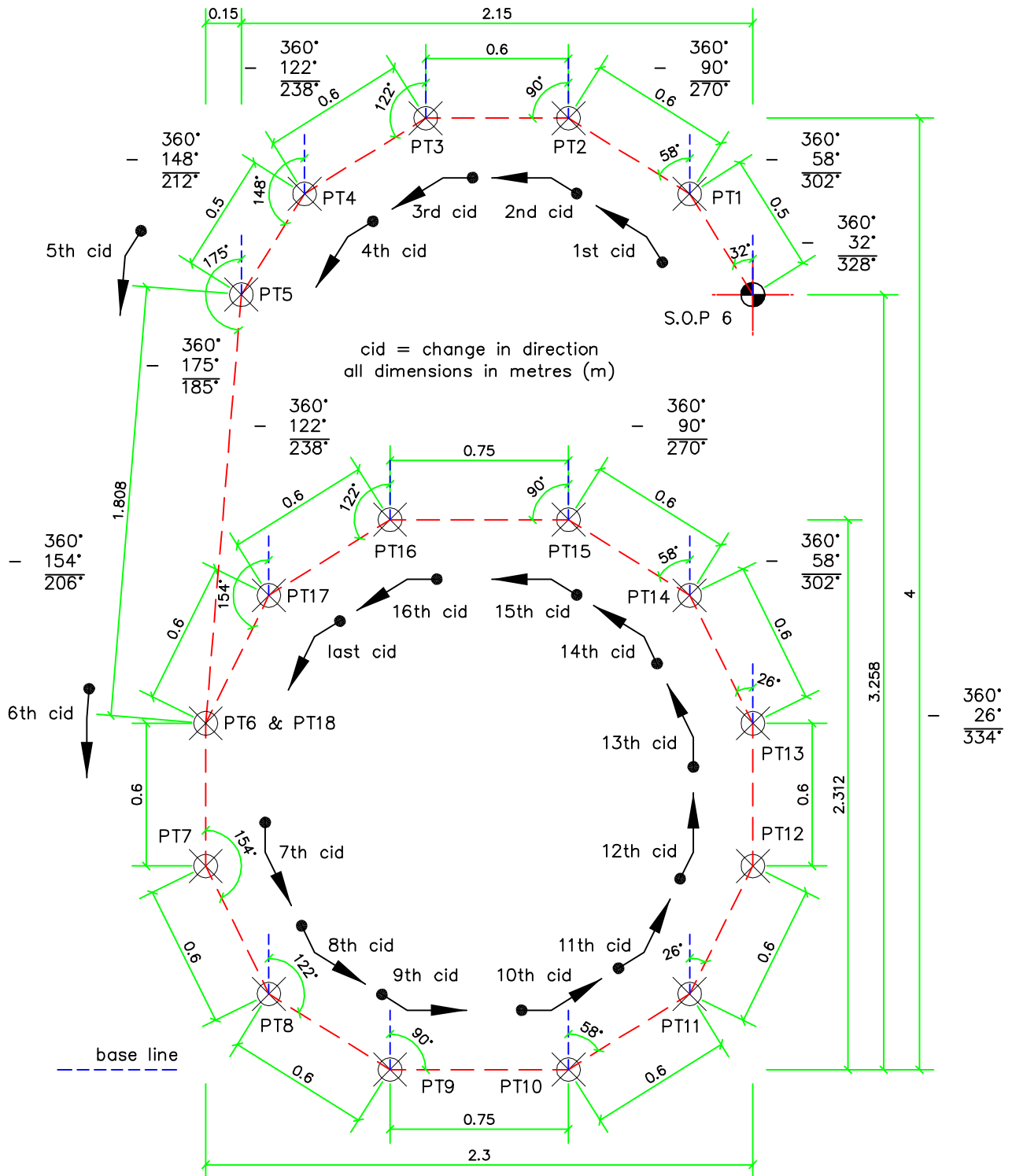
- From S.O.P 5 walk 1.6m on a bearing of 270° and mark the location.
- From PT1 Walk 2m on a bearing of 192° and mark the location.
- From PT2 Walk 0.6m on a bearing of 58° and mark the location.
- From PT3 Walk 0.75m on a bearing of 90° and mark the location.
- From PT4 Walk 0.6m on a bearing of 122° and mark the location.
- From PT5 Walk 0.6m on a bearing of 154° and mark the location.
- From PT6 Walk 0.6m on a bearing of 180° and mark the location.
- From PT7 Walk 0.6m on a bearing of 206° and mark the location.
- From PT8 Walk 0.6m on a bearing of 238° and mark the location.
- From PT9 Walk 0.75m on a bearing of 270° and mark the location.
- From PT10 Walk 0.6m on a bearing of 302° and mark the location.
- From PT11 Walk 0.6m on a bearing of 334° and mark the location and finish.

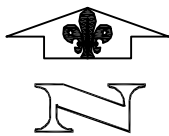




Micro navigation – number 6

- From S.O.P 6 walk 0.5m on a bearing of 328° and mark the location.
- From PT1 Walk 0.6m on a bearing of 302° and mark the location.
- From PT2 Walk 0.6m on a bearing of 270° and mark the location.
- From PT3 Walk 0.6m on a bearing of 238° and mark the location.
- From PT4 Walk 0.5m on a bearing of 212° and mark the location.
- From PT5 Walk 1.8m on a bearing of 185° and mark the location.
- From PT6 Walk 0.6m on a bearing of 180° and mark the location.
- From PT7 Walk 0.6m on a bearing of 154° and mark the location.
- From PT8 Walk 0.6m on a bearing of 122° and mark the location.
- From PT9 Walk 0.75m on a bearing of 90° and mark the location.
- From PT10 Walk 0.6m on a bearing of 58° and mark the location.
- From PT11 Walk 0.6m on a bearing of 26° and mark the location.
- From PT12 Walk 0.6m on a bearing of 0° and mark the location.
- From PT13 Walk 0.6m on a bearing of 334° and mark the location.
- From PT14 Walk 0.6m on a bearing of 302° and mark the location.
- From PT15 Walk 0.75m on a bearing of 270° and mark the location.
- From PT16 Walk 0.6m on a bearing of 238° and mark the location.
- From PT17 Walk 0.6m on a bearing of 206° and finish.

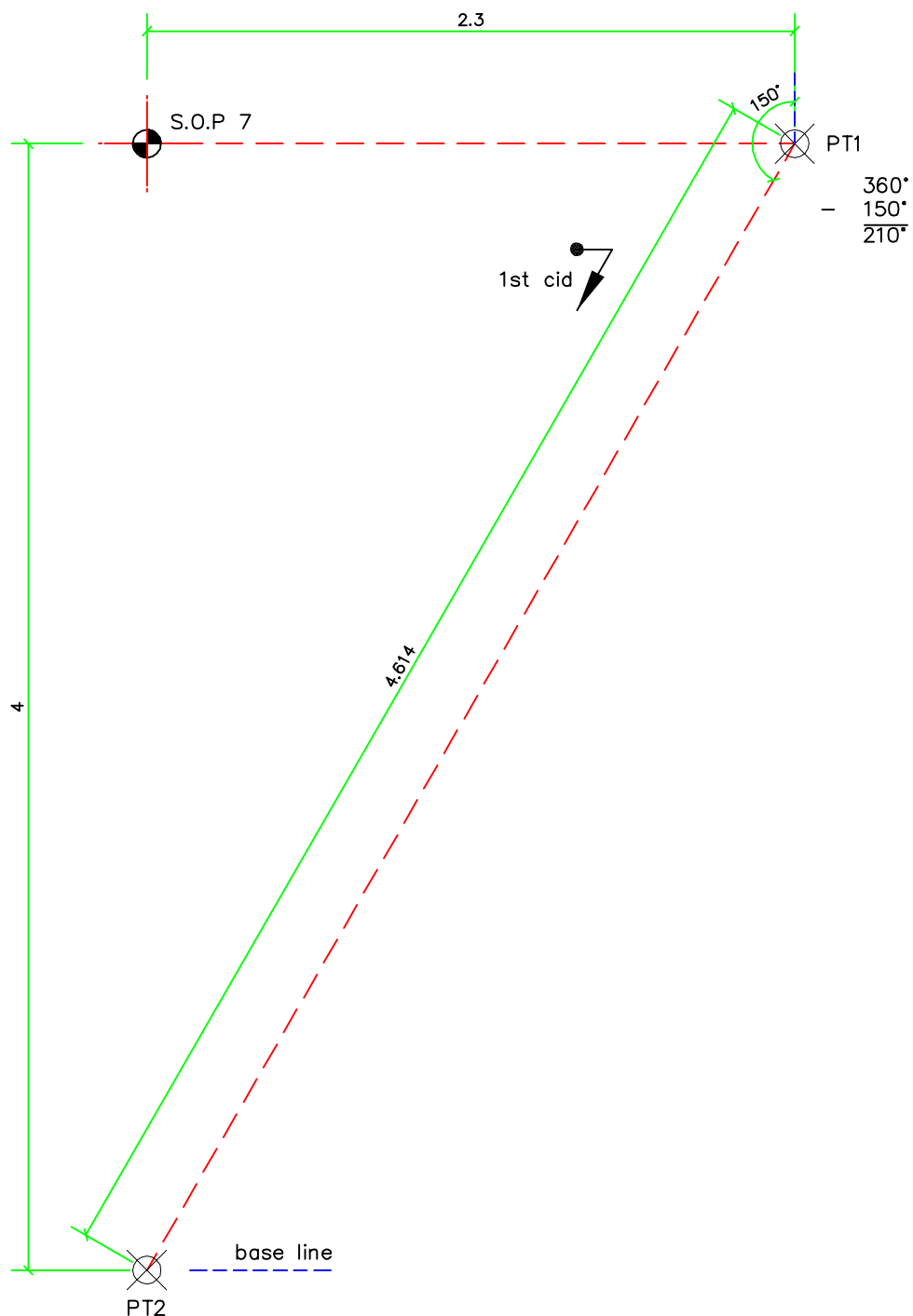




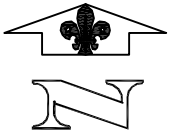
Micro navigation – number 7

From S.O.P 7 walk 2.3m on a bearing of 90° and mark the location.
 From PT1 Walk 4.6m on a bearing of 210° and mark the location and finish.

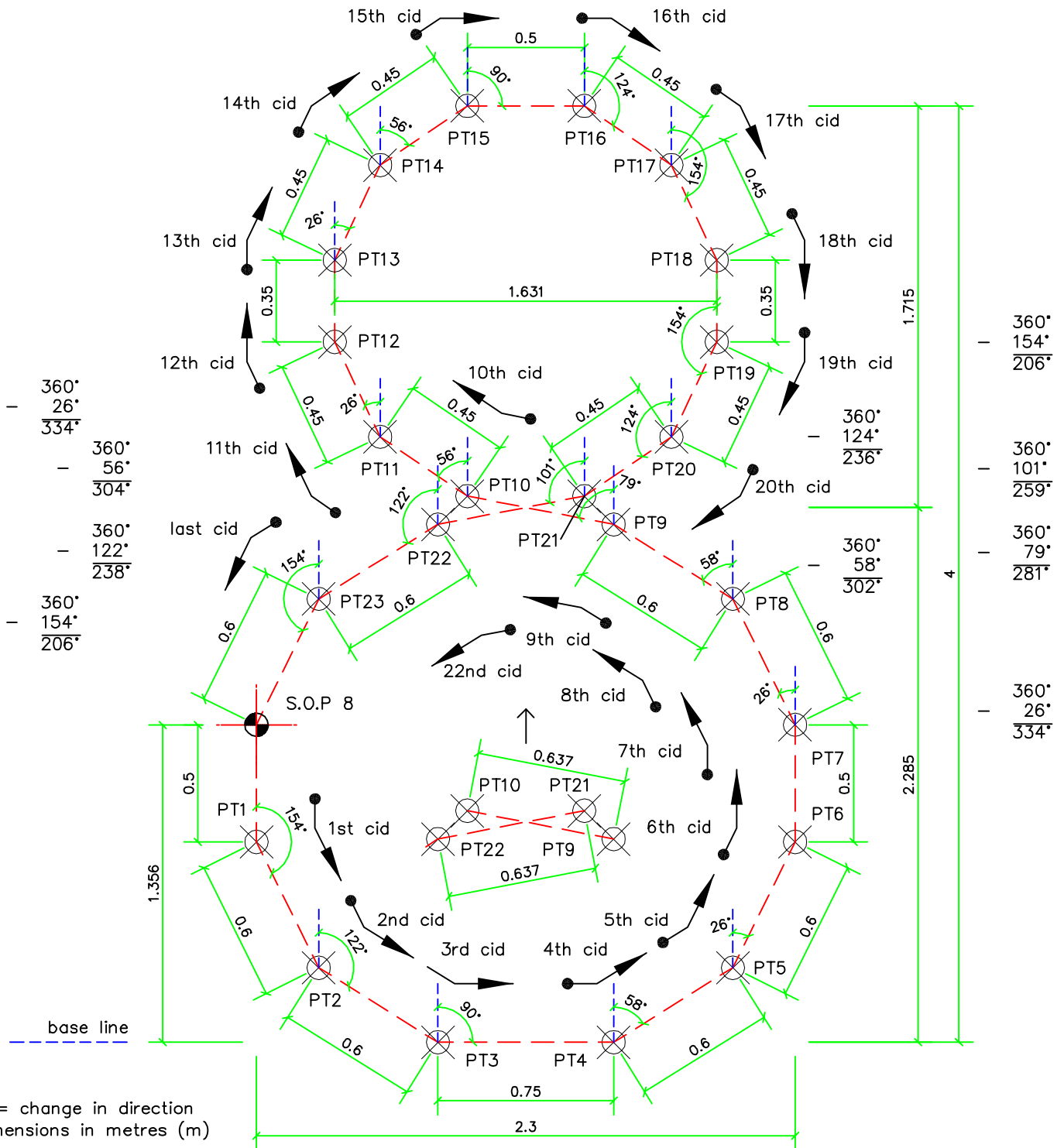
cid = change in direction
 all dimensions in metres (m)

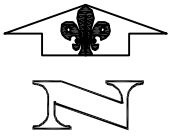


Micro navigation – number 8



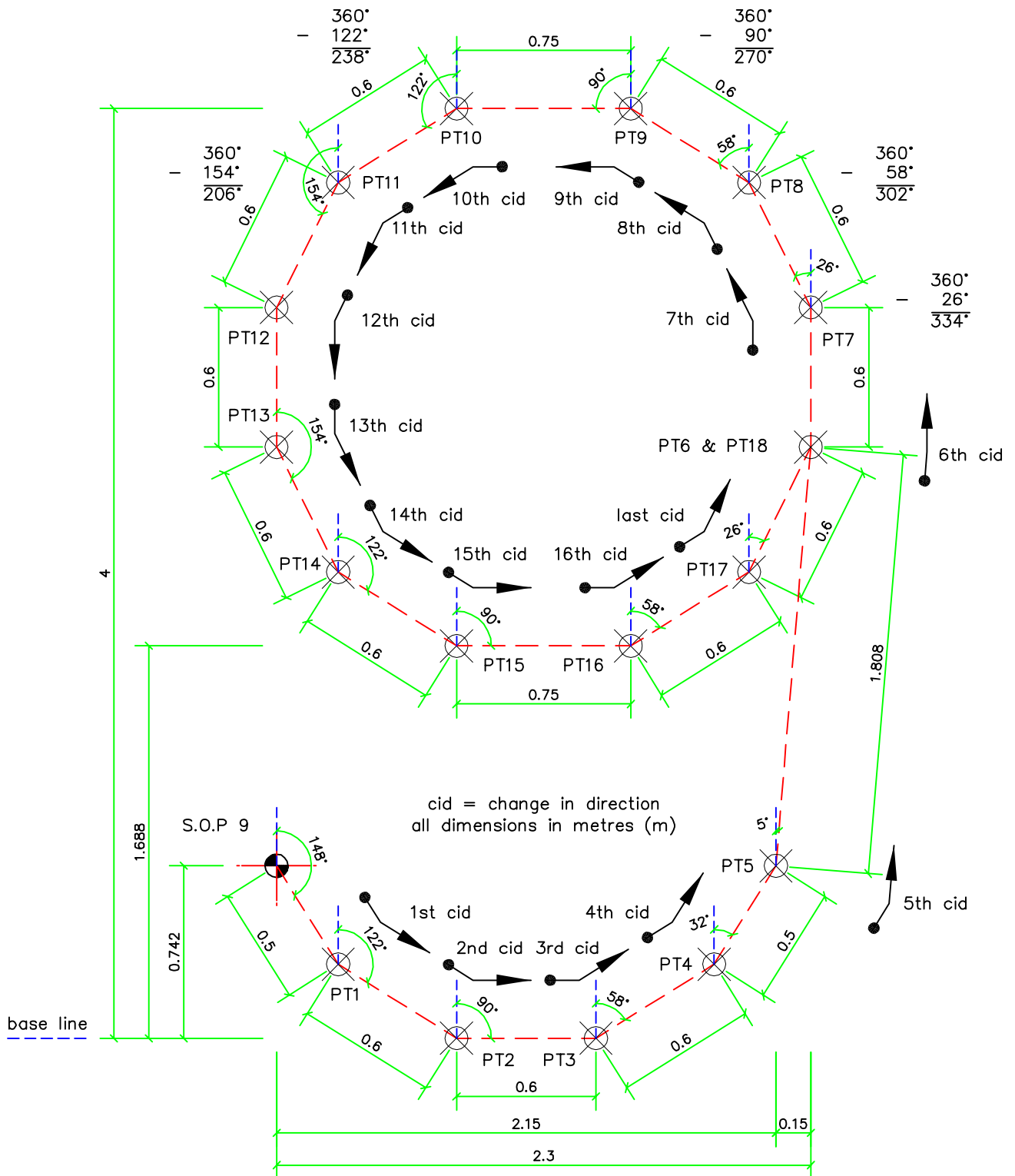
From S.O.P 8 walk	0.5m on a bearing of	180°	and mark the location.
From PT1 Walk	0.6m on a bearing of	154°	and mark the location.
From PT2 Walk	0.6m on a bearing of	122°	and mark the location.
From PT3 Walk	0.75m on a bearing of	90°	and mark the location.
From PT4 Walk	0.6m on a bearing of	58°	and mark the location.
From PT5 Walk	0.6m on a bearing of	26°	and mark the location.
From PT6 Walk	0.5m on a bearing of	0°	and mark the location.
From PT7 Walk	0.6m on a bearing of	334°	and mark the location.
From PT8 Walk	0.6m on a bearing of	302°	and mark the location.
From PT9 Walk	0.65m on a bearing of	281°	and mark the location.
From PT10 Walk	0.45m on a bearing of	304°	and mark the location.
From PT11 Walk	0.45m on a bearing of	334°	and mark the location.
From PT12 Walk	0.35m on a bearing of	0°	and mark the location.
From PT13 Walk	0.45m on a bearing of	26°	and mark the location.
From PT14 Walk	0.45m on a bearing of	56°	and mark the location.
From PT15 Walk	0.5m on a bearing of	90°	and mark the location.
From PT16 Walk	0.45m on a bearing of	124°	and mark the location.
From PT17 Walk	0.45m on a bearing of	154°	and mark the location.
From PT18 Walk	0.35m on a bearing of	180°	and mark the location.
From PT19 Walk	0.45m on a bearing of	206°	and mark the location.
From PT20 Walk	0.45m on a bearing of	236°	and mark the location.
From PT21 Walk	0.65m on a bearing of	259°	and mark the location.
From PT22 Walk	0.6m on a bearing of	238°	and mark the location.
From PT23 Walk	0.6m on a bearing of	206°	and finish.

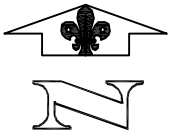




Micro navigation – number 9

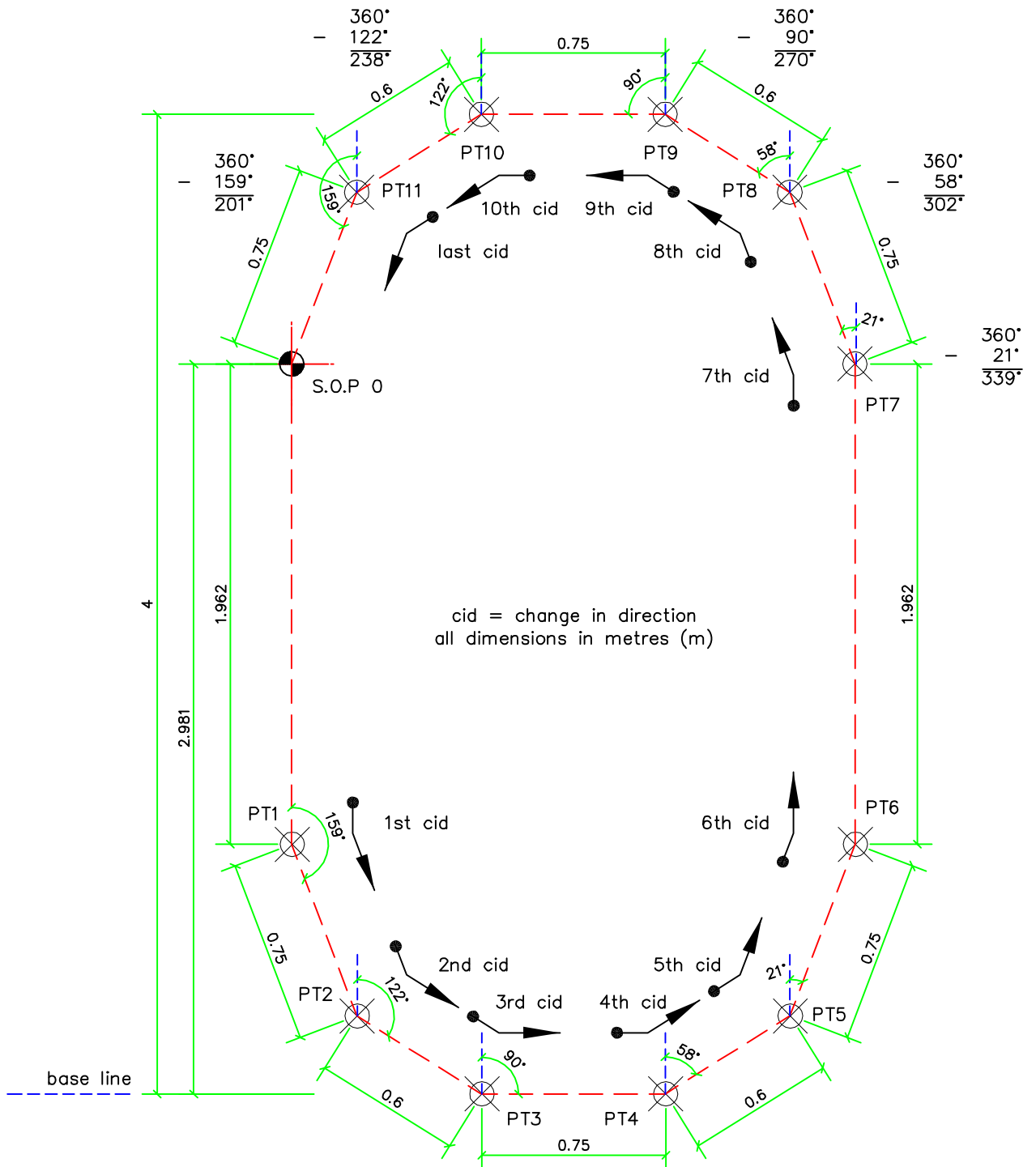
- From S.O.P 9 walk 0.5m on a bearing of 148° and mark the location.
- From PT1 Walk 0.6m on a bearing of 122° and mark the location.
- From PT2 Walk 0.6m on a bearing of 90° and mark the location.
- From PT3 Walk 0.6m on a bearing of 58° and mark the location.
- From PT4 Walk 0.5m on a bearing of 32° and mark the location.
- From PT5 Walk 1.8m on a bearing of 5° and mark the location.
- From PT6 Walk 0.6m on a bearing of 0° and mark the location.
- From PT7 Walk 0.6m on a bearing of 334° and mark the location.
- From PT8 Walk 0.6m on a bearing of 302° and mark the location.
- From PT9 Walk 0.75m on a bearing of 270° and mark the location.
- From PT10 Walk 0.6m on a bearing of 238° and mark the location.
- From PT11 Walk 0.6m on a bearing of 206° and mark the location.
- From PT12 Walk 0.6m on a bearing of 180° and mark the location.
- From PT13 Walk 0.6m on a bearing of 154° and mark the location.
- From PT14 Walk 0.6m on a bearing of 122° and mark the location.
- From PT15 Walk 0.75m on a bearing of 90° and mark the location.
- From PT16 Walk 0.6m on a bearing of 58° and mark the location.
- From PT17 Walk 0.6m on a bearing of 26° and finish.

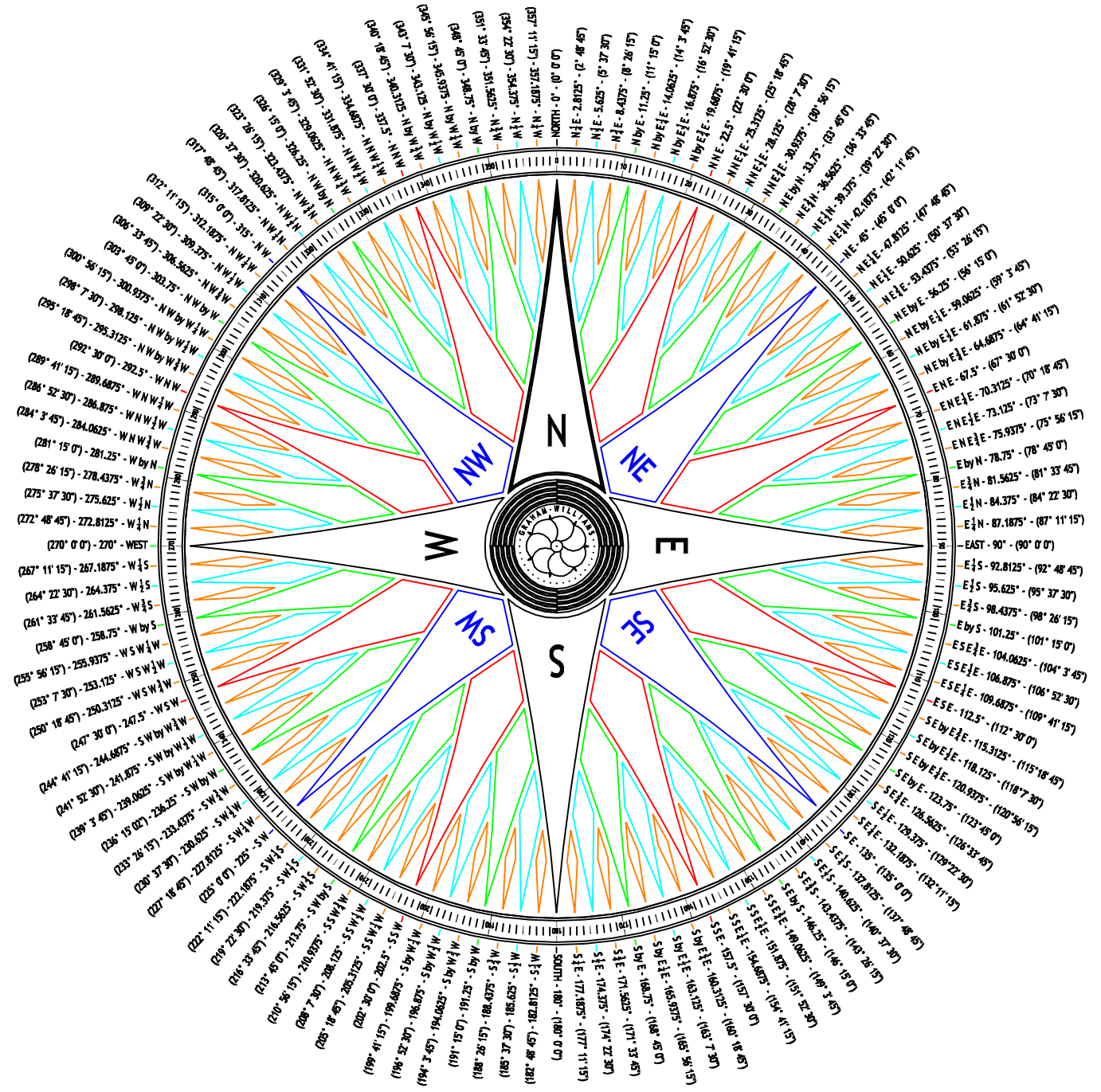
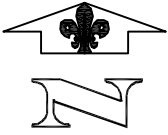




Micro navigation – number 0

- From S.O.P 0 walk 2m on a bearing of 180° and mark the location.
- From PT1 Walk 0.75m on a bearing of 159° and mark the location.
- From PT2 Walk 0.6m on a bearing of 122° and mark the location.
- From PT3 Walk 0.75m on a bearing of 90° and mark the location.
- From PT4 Walk 0.6m on a bearing of 58° and mark the location.
- From PT5 Walk 0.75m on a bearing of 21° and mark the location.
- From PT6 Walk 2m on a bearing of 0° and mark the location.
- From PT7 Walk 0.75m on a bearing of 339° and mark the location.
- From PT8 Walk 0.6m on a bearing of 302° and mark the location.
- From PT9 Walk 0.75m on a bearing of 270° and mark the location.
- From PT10 Walk 0.6m on a bearing of 238° and mark the location.
- From PT11 Walk 0.75m on a bearing of 201° and finish.





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Micro navigation – letter A

Appendix (ii)

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From S.O.P _ walk 1.5m on a bearing of 21° and mark the location.
 From PT1 Walk 1.9m on a bearing of 90° and mark the location.
 From PT2 Walk 2.8m on a bearing of 339° and mark the location.
 From PT3 Walk 2.8m on a bearing of 201° .
 From PT4 Walk 1.9m on a bearing of 90° .
 From PT5 Walk 1.5m on a bearing of 159° and mark the location and finish.

Micro navigation – letter a

From S.O.P _ walk 0.75m on a bearing of 312° and mark the location.
 From PT1 Walk 1m on a bearing of 270° and mark the location.
 From PT2 Walk 0.75m on a bearing of 228° and mark the location.
 From PT3 Walk 0.9m on a bearing of 192° and mark the location.
 From PT4 Walk 0.9m on a bearing of 168° and mark the location.
 From PT5 Walk 0.75m on a bearing of 132° and mark the location.
 From PT6 Walk 1m on a bearing of 90° and mark the location.
 From PT7 Walk 0.75m on a bearing of 48° and mark the location.
 From PT8 Walk 2.2m on a bearing of 0° and mark the location.
 From PT9 Walk 2.7m on a bearing of 180° and mark the location and finish.

Micro navigation – letter B

From S.O.P _ walk 2m on a bearing of 0° and mark the location.
 From PT1 Walk 2m on a bearing of 90° and mark the location.
 From PT2 Walk 0.75m on a bearing of 116° and mark the location.
 From PT3 Walk 0.75m on a bearing of 154° and mark the location.
 From PT4 Walk 0.75m on a bearing of 206° and mark the location.
 From PT5 Walk 0.75m on a bearing of 244° and mark the location.
 From PT6 Walk 2m on a bearing of 270° .
 From PT7 Walk 2m on a bearing of 180° and mark the location.
 From PT8 Walk 2m on a bearing of 90° and mark the location.
 From PT9 Walk 0.75m on a bearing of 64° and mark the location.
 From PT10 Walk 0.75m on a bearing of 26° and mark the location.
 From PT11 Walk 0.75m on a bearing of 334° and mark the location.
 From PT12 Walk 0.75m on a bearing of 296° and finish.

Micro navigation – letter b

From S.O.P _ walk 0.75m on a bearing of 48° and mark the location.
 From PT1 Walk 1m on a bearing of 90° and mark the location.
 From PT2 Walk 0.75m on a bearing of 132° and mark the location.
 From PT3 Walk 0.9m on a bearing of 168° and mark the location.
 From PT4 Walk 0.9m on a bearing of 192° and mark the location.
 From PT5 Walk 0.75m on a bearing of 228° and mark the location.
 From PT6 Walk 1m on a bearing of 270° and mark the location.
 From PT7 Walk 0.75m on a bearing of 312° and mark the location.
 From PT8 Walk 0.5m on a bearing of 180° and mark the location.
 From PT9 Walk 4m on a bearing of 0° and mark the location and finish.

Micro navigation – letter C

From S.O.P _ walk 0.75m on a bearing of 210° and mark the location.
 From PT1 Walk 0.9m on a bearing of 236° and mark the location.
 From PT2 Walk 0.75m on a bearing of 270° and mark the location.
 From PT3 Walk 0.9m on a bearing of 304° and mark the location.
 From PT4 Walk 0.75m on a bearing of 330° and mark the location.
 From PT5 Walk 1.7m on a bearing of 0° and mark the location.
 From PT6 Walk 0.75m on a bearing of 30° and mark the location.
 From PT7 Walk 0.9m on a bearing of 56° and mark the location.
 From PT8 Walk 0.75m on a bearing of 90° and mark the location.
 From PT9 Walk 0.9m on a bearing of 124° and mark the location.
 From PT10 Walk 0.75m on a bearing of 150° and mark the location and finish.

Micro navigation – letter c

From S.O.P _ walk 0.75m on a bearing of 312° and mark the location.
 From PT1 Walk 1m on a bearing of 270° and mark the location.
 From PT2 Walk 0.75m on a bearing of 228° and mark the location.
 From PT3 Walk 0.9m on a bearing of 192° and mark the location.
 From PT4 Walk 0.9m on a bearing of 168° and mark the location.
 From PT5 Walk 0.75m on a bearing of 132° and mark the location.
 From PT6 Walk 1m on a bearing of 90° and mark the location.
 From PT7 Walk 0.75m on a bearing of 48° and mark the location and finish.

Micro navigation – letter D

Appendix (iii)

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From S.O.P _ walk 1.5m on a bearing of 180° and mark the location.
 From PT1 Walk 0.85m on a bearing of 199° and mark the location.
 From PT2 Walk 0.85m on a bearing of 238° and mark the location.
 From PT3 Walk 2m on a bearing of 270° and mark the location.
 From PT4 Walk 4m on a bearing of 0° and mark the location.
 From PT5 Walk 2m on a bearing of 90° and mark the location.
 From PT6 Walk 0.85m on a bearing of 122° and mark the location.
 From PT7 Walk 0.85m on a bearing of 161° and finish.

Micro navigation – letter d

From S.O.P _ walk 0.75m on a bearing of 312° and mark the location.
 From PT1 Walk 1m on a bearing of 270° and mark the location.
 From PT2 Walk 0.75m on a bearing of 228° and mark the location.
 From PT3 Walk 0.9m on a bearing of 192° and mark the location.
 From PT4 Walk 0.9m on a bearing of 168° and mark the location.
 From PT5 Walk 0.75m on a bearing of 132° and mark the location.
 From PT6 Walk 1m on a bearing of 90° and mark the location.
 From PT7 Walk 0.75m on a bearing of 48° and mark the location.
 From PT8 Walk 3.5m on a bearing of 0° and mark the location.
 From PT9 Walk 4m on a bearing of 180° and mark the location and finish.

Micro navigation – letter E

From S.O.P _ walk 3m on a bearing of 270° and mark the location.
 From PT1 Walk 2m on a bearing of 0° and mark the location.
 From PT2 Walk 2.3m on a bearing of 90° and mark the location.
 From PT3 Walk 2.3m on a bearing of 270° .
 From PT4 Walk 2m on a bearing of 0° and mark the location.
 From PT5 Walk 3m on a bearing of 90° and mark the location and finish.

Micro navigation – letter e

From S.O.P _ walk 2.3m on a bearing of 90° and mark the location.
 From PT1 Walk 0.5m on a bearing of 0° and mark the location.
 From PT2 Walk 0.6m on a bearing of 334° and mark the location.
 From PT3 Walk 0.6m on a bearing of 302° and mark the location.
 From PT4 Walk 0.75m on a bearing of 270° and mark the location.
 From PT5 Walk 0.6m on a bearing of 238° and mark the location.
 From PT6 Walk 0.6m on a bearing of 206° and mark the location.
 From PT7 Walk 1.2m on a bearing of 180° and mark the location.
 From PT8 Walk 0.5m on a bearing of 148° and mark the location.
 From PT9 Walk 0.5m on a bearing of 114° and mark the location.
 From PT10 Walk 0.9m on a bearing of 90° and mark the location.
 From PT11 Walk 0.5m on a bearing of 66° and mark the location.
 From PT12 Walk 0.5m on a bearing of 32° and mark the location and finish.

Micro navigation – letter F

From S.O.P _ Walk 2m on a bearing of 0° and mark the location.
 From PT1 Walk 2.3m on a bearing of 90° and mark the location.
 From PT2 Walk 2.3m on a bearing of 270° .
 From PT3 Walk 2m on a bearing of 0° and mark the location.
 From PT4 Walk 3m on a bearing of 90° and mark the location and finish.

Micro navigation – letter f

From S.O.P _ walk 2.5m on a bearing of 0° and mark the location.
 From PT1 Walk 1.5m on a bearing of 90° and mark the location.
 From PT2 Walk 1.5m on a bearing of 270° .
 From PT3 Walk 0.6m on a bearing of 0° and mark the location.
 From PT4 Walk 0.6m on a bearing of 26° and mark the location.
 From PT5 Walk 0.6m on a bearing of 58° and mark the location.
 From PT6 Walk 0.75m on a bearing of 90° and mark the location.
 From PT7 Walk 0.6m on a bearing of 122° and mark the location.
 From PT8 Walk 0.6m on a bearing of 154° and mark the location and finish.

Micro navigation – letter G

Appendix (iv)

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From S.O.P _ walk	1m on a bearing of	90°	and mark the location.
From PT1 Walk	0.6m on a bearing of	180°	and mark the location.
From PT2 Walk	0.75m on a bearing of	215°	and mark the location.
From PT3 Walk	0.75m on a bearing of	247°	and mark the location.
From PT4 Walk	0.75m on a bearing of	270°	and mark the location.
From PT5 Walk	0.75m on a bearing of	293°	and mark the location.
From PT6 Walk	0.75m on a bearing of	325°	and mark the location.
From PT7 Walk	2m on a bearing of	0°	and mark the location.
From PT8 Walk	0.75m on a bearing of	30°	and mark the location.
From PT9 Walk	0.9m on a bearing of	56°	and mark the location.
From PT10 Walk	0.75m on a bearing of	90°	and mark the location.
From PT11 Walk	0.9m on a bearing of	124°	and mark the location.
From PT12 Walk	0.75m on a bearing of	150°	and mark the location and finish.

Micro navigation – letter g

From S.O.P _ walk	0.75m on a bearing of	228°	and mark the location.
From PT1 Walk	1m on a bearing of	270°	and mark the location.
From PT2 Walk	0.75m on a bearing of	312°	and mark the location.
From PT3 Walk	0.9m on a bearing of	348°	and mark the location.
From PT4 Walk	0.9m on a bearing of	12°	and mark the location.
From PT5 Walk	0.75m on a bearing of	48°	and mark the location.
From PT6 Walk	1m on a bearing of	90°	and mark the location.
From PT7 Walk	0.75m on a bearing of	132°	and mark the location.
From PT8 Walk	0.5m on a bearing of	0°	and mark the location.
From PT9 Walk	3.5m on a bearing of	180°	and mark the location.
From PT10 Walk	0.75m on a bearing of	228°	and mark the location.
From PT11 Walk	1m on a bearing of	270°	and mark the location.
From PT12 Walk	0.75m on a bearing of	312°	and mark the location and finish.

Micro navigation – letter H

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	2m on a bearing of	180°	and mark the location.
From PT2 Walk	3m on a bearing of	90°	and mark the location.
From PT3 Walk	2m on a bearing of	0°	and mark the location.
From PT4 Walk	4m on a bearing of	180°	and mark the location and finish.

Micro navigation – letter h

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	2.2m on a bearing of	180°	and mark the location.
From PT2 Walk	0.6m on a bearing of	26°	and mark the location.
From PT3 Walk	0.6m on a bearing of	58°	and mark the location.
From PT4 Walk	0.75m on a bearing of	90°	and mark the location.
From PT5 Walk	0.6m on a bearing of	122°	and mark the location.
From PT6 Walk	0.6m on a bearing of	154°	and mark the location.
From PT7 Walk	1.8m on a bearing of	180°	and mark the location and finish.

Micro navigation – letter I

From S.O.P _ walk	4m on a bearing of	0°	and mark the location and finish.
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Micro navigation – letter i

From S.O.P _ walk	2.7m on a bearing of	0°	and mark the location and finish.
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Micro navigation – letter L

From S.O.P _ walk	3m on a bearing of	270°	and mark the location.
From PT1 Walk	4m on a bearing of	0°	and mark the location and finish.

Micro navigation – letter l

From S.O.P _ walk	4m on a bearing of	180°	and mark the location and finish.
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Micro navigation – letter J

Appendix (v)

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From S.O.P _ walk	1.4m on a bearing of	270°	and mark the location.
From PT1 Walk	0.7m on a bearing of	90°	and mark the location.
From PT2 Walk	3.15m on a bearing of	180°	and mark the location.
From PT3 Walk	0.6m on a bearing of	206°	and mark the location.
From PT4 Walk	0.6m on a bearing of	239°	and mark the location.
From PT5 Walk	0.75m on a bearing of	270°	and mark the location.
From PT6 Walk	0.6m on a bearing of	301°	and mark the location.
From PT7 Walk	0.6m on a bearing of	334°	and mark the location.
From PT8 Walk	0.5m on a bearing of	0°	and mark the location and finish.

Micro navigation – letter j

From S.O.P _ walk	3.5m on a bearing of	180°	and mark the location.
From PT1 Walk	0.75m on a bearing of	228°	and mark the location.
From PT2 Walk	1m on a bearing of	270°	and mark the location.
From PT3 Walk	0.75m on a bearing of	312°	and mark the location and finish.

Micro navigation – letter K

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	2.7m on a bearing of	180°	and mark the location.
From PT2 Walk	1.3m on a bearing of	48°	and mark the location.
From PT3 Walk	3m on a bearing of	137°	and mark the location.
From PT4 Walk	3m on a bearing of	317°	.
From PT5 Walk	2.7m on a bearing of	48°	and mark the location and finish.

Micro navigation – letter k

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	3.1m on a bearing of	180°	and mark the location.
From PT2 Walk	1m on a bearing of	52°	and mark the location.
From PT3 Walk	2.1m on a bearing of	135°	and mark the location.
From PT4 Walk	2.1m on a bearing of	315°	.
From PT5 Walk	1.9m on a bearing of	52°	and mark the location and finish.

Micro navigation – letter M

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	4.3m on a bearing of	201°	and mark the location.
From PT2 Walk	4.3m on a bearing of	339°	and mark the location.
From PT3 Walk	4m on a bearing of	180°	and mark the location and finish.

Micro navigation – letter m

From S.O.P _ walk	2.7m on a bearing of	0°	and mark the location.
From PT1 Walk	0.9m on a bearing of	180°	and mark the location.
From PT2 Walk	0.6m on a bearing of	26°	and mark the location.
From PT3 Walk	0.6m on a bearing of	58°	and mark the location.
From PT4 Walk	0.75m on a bearing of	90°	and mark the location.
From PT5 Walk	0.6m on a bearing of	122°	and mark the location.
From PT6 Walk	0.6m on a bearing of	154°	and mark the location.
From PT7 Walk	1.8m on a bearing of	180°	and mark the location.
From PT8 Walk	1.8m on a bearing of	0°	.
From PT9 Walk	0.6m on a bearing of	26°	and mark the location.
From PT10 Walk	0.6m on a bearing of	58°	and mark the location.
From PT11 Walk	0.75m on a bearing of	90°	and mark the location.
From PT12 Walk	0.6m on a bearing of	122°	and mark the location.
From PT13 Walk	0.6m on a bearing of	154°	and mark the location.
From PT14 Walk	1.8m on a bearing of	180°	and mark the location and finish.

Micro navigation – letter N

From S.O.P _ walk 4m on a bearing of 0° and mark the location.
 From PT1 Walk 4m on a bearing of 180° .
 From PT2 Walk 5m on a bearing of 323° and mark the location.
 From PT3 Walk 4m on a bearing of 180° and mark the location and finish.

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Micro navigation – letter n

From S.O.P _ walk 2.7m on a bearing of 0° and mark the location.
 From PT1 Walk 0.9m on a bearing of 180° and mark the location.
 From PT2 Walk 0.6m on a bearing of 26° and mark the location.
 From PT3 Walk 0.6m on a bearing of 58° and mark the location.
 From PT4 Walk 0.75m on a bearing of 90° and mark the location.
 From PT5 Walk 0.6m on a bearing of 122° and mark the location.
 From PT6 Walk 0.6m on a bearing of 154° and mark the location.
 From PT7 Walk 1.8m on a bearing of 180° and mark the location and finish.

Micro navigation – letter O

From S.O.P _ walk 1.15m on a bearing of 0° and mark the location.
 From PT1 Walk 1.0m on a bearing of 338° and mark the location.
 From PT2 Walk 0.9m on a bearing of 304° and mark the location.
 From PT3 Walk 0.75m on a bearing of 270° and mark the location.
 From PT4 Walk 0.9m on a bearing of 236° and mark the location.
 From PT5 Walk 1.0m on a bearing of 202° and mark the location.
 From PT6 Walk 1.15m on a bearing of 180° and mark the location.
 From PT7 Walk 1.0m on a bearing of 158° and mark the location.
 From PT8 Walk 0.9m on a bearing of 124° and mark the location.
 From PT9 Walk 0.75m on a bearing of 90° and mark the location.
 From PT10 Walk 0.9m on a bearing of 56° and mark the location.
 From PT11 walk 1.0m on a bearing of 22° and finish.

Micro navigation – letter o

From S.O.P _ walk 1.0m on a bearing of 0° and mark the location.
 From PT1 Walk 0.6m on a bearing of 334° and mark the location.
 From PT2 Walk 0.6m on a bearing of 302° and mark the location.
 From PT3 Walk 0.75m on a bearing of 270° and mark the location.
 From PT4 Walk 0.6m on a bearing of 238° and mark the location.
 From PT5 Walk 0.6m on a bearing of 206° and mark the location.
 From PT6 Walk 1.0m on a bearing of 180° and mark the location.
 From PT7 Walk 0.6m on a bearing of 154° and mark the location.
 From PT8 Walk 0.6m on a bearing of 122° and mark the location.
 From PT9 Walk 0.75m on a bearing of 90° and mark the location.
 From PT10 Walk 0.6m on a bearing of 58° and mark the location.
 From PT11 walk 0.6m on a bearing of 26° and finish.

Micro navigation – letter P

From S.O.P _ walk 2m on a bearing of 0° and mark the location.
 From PT1 Walk 2m on a bearing of 90° and mark the location.
 From PT2 Walk 0.75m on a bearing of 116° and mark the location.
 From PT3 Walk 0.75m on a bearing of 154° and mark the location.
 From PT4 Walk 0.75m on a bearing of 206° and mark the location.
 From PT5 Walk 0.75m on a bearing of 244° and mark the location.
 From PT6 Walk 2m on a bearing of 270° .
 From PT7 Walk 2m on a bearing of 180° and mark the location and finish.

Micro navigation – letter p

From S.O.P _ walk 1.8m on a bearing of 180° and mark the location.
 From PT1 Walk 4m on a bearing of 0° and mark the location.
 From PT2 Walk 0.5m on a bearing of 180° and mark the location.
 From PT3 Walk 0.75m on a bearing of 48° and mark the location.
 From PT4 Walk 1m on a bearing of 90° and mark the location.
 From PT5 Walk 0.75m on a bearing of 132° and mark the location.
 From PT6 Walk 0.9m on a bearing of 168° and mark the location.
 From PT7 Walk 0.9m on a bearing of 192° and mark the location.
 From PT8 Walk 0.75m on a bearing of 228° and mark the location.
 From PT9 Walk 1m on a bearing of 270° and mark the location.
 From PT10 Walk 0.75m on a bearing of 312° and finish.

Micro navigation – letter Q

Appendix (vii)

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From S.O.P _ walk 1.0m on a bearing of	22°	and mark the location.
From PT1 Walk 1.15m on a bearing of	0°	and mark the location.
From PT2 Walk 1.0m on a bearing of	338°	and mark the location.
From PT3 Walk 0.9m on a bearing of	304°	and mark the location.
From PT4 Walk 0.75m on a bearing of	270°	and mark the location.
From PT5 Walk 0.9m on a bearing of	236°	and mark the location.
From PT6 Walk 1.0m on a bearing of	202°	and mark the location.
From PT7 Walk 1.15m on a bearing of	180°	and mark the location.
From PT8 Walk 1.0m on a bearing of	158°	and mark the location.
From PT9 Walk 0.9m on a bearing of	124°	and mark the location.
From PT10 Walk 0.75m on a bearing of	90°	and mark the location.
From PT11 Walk 0.9m on a bearing of	56°	
From PT12 Walk 0.6m on a bearing of	323°	and mark the location.
From PT13 Walk 1.2m on a bearing of	143°	and mark the location and finish.

Micro navigation – letter q

From S.O.P _ walk 0.75m on a bearing of	228°	and mark the location.
From PT1 Walk 1m on a bearing of	270°	and mark the location.
From PT2 Walk 0.75m on a bearing of	312°	and mark the location.
From PT3 Walk 0.9m on a bearing of	348°	and mark the location.
From PT4 Walk 0.9m on a bearing of	12°	and mark the location.
From PT5 Walk 0.75m on a bearing of	48°	and mark the location.
From PT6 Walk 1m on a bearing of	90°	and mark the location.
From PT7 Walk 0.75m on a bearing of	132°	and mark the location.
From PT8 Walk 0.5m on a bearing of	0°	and mark the location.
From PT9 Walk 4m on a bearing of	180°	and mark the location and finish.

Micro navigation – letter R

From S.O.P _ walk 4m on a bearing of	0°	and mark the location.
From PT1 Walk 2m on a bearing of	90°	and mark the location.
From PT2 Walk 0.75m on a bearing of	116°	and mark the location.
From PT3 Walk 0.75m on a bearing of	154°	and mark the location.
From PT4 Walk 0.75m on a bearing of	206°	and mark the location.
From PT5 Walk 0.75m on a bearing of	244°	and mark the location.
From PT6 Walk 2.2m on a bearing of	153°	and mark the location.
From PT7 Walk 2.2m on a bearing of	333°	
From PT8 Walk 2m on a bearing of	90°	and mark the location and finish.

Micro navigation – letter r

From S.O.P _ walk 2.7m on a bearing of	0°	and mark the location.
From PT1 Walk 0.9m on a bearing of	180°	and mark the location.
From PT2 Walk 0.6m on a bearing of	26°	and mark the location.
From PT3 Walk 0.6m on a bearing of	58°	and mark the location.
From PT4 Walk 0.75m on a bearing of	90°	and mark the location.
From PT5 Walk 0.6m on a bearing of	122°	and mark the location.
From PT6 Walk 0.6m on a bearing of	154°	and mark the location and finish.

Micro navigation – letter S

From S.O.P _ walk 0.75m on a bearing of	332°	and mark the location.
From PT1 Walk 0.75m on a bearing of	294°	and mark the location.
From PT2 Walk 0.9m on a bearing of	270°	and mark the location.
From PT3 Walk 0.75m on a bearing of	246°	and mark the location.
From PT4 Walk 0.75m on a bearing of	208°	and mark the location.
From PT5 Walk 0.5m on a bearing of	152°	and mark the location.
From PT6 Walk 2.8m on a bearing of	115°	and mark the location.
From PT7 Walk 0.5m on a bearing of	152°	and mark the location.
From PT8 Walk 0.75m on a bearing of	208°	and mark the location.
From PT9 Walk 0.75m on a bearing of	246°	and mark the location.
From PT10 Walk 0.9m on a bearing of	270°	and mark the location.
From PT11 Walk 0.75m on a bearing of	294°	and mark the location.
From PT12 Walk 0.75m on a bearing of	332°	and mark the location and finish.

Micro navigation – letter s

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From S.O.P _ walk	0.5m on a bearing of	328°	and mark the location.
From PT1 Walk	0.5m on a bearing of	288°	and mark the location.
From PT2 Walk	0.8m on a bearing of	270°	and mark the location.
From PT3 Walk	0.5m on a bearing of	252°	and mark the location.
From PT4 Walk	0.5m on a bearing of	212°	and mark the location.
From PT5 Walk	0.5m on a bearing of	137°	and mark the location.
From PT6 Walk	1.8m on a bearing of	115°	and mark the location.
From PT7 Walk	0.5m on a bearing of	143°	and mark the location.
From PT8 Walk	0.5m on a bearing of	212°	and mark the location.
From PT9 Walk	0.5m on a bearing of	252°	and mark the location.
From PT10 Walk	0.8m on a bearing of	270°	and mark the location.
From PT11 Walk	0.5m on a bearing of	288°	and mark the location.
From PT12 Walk	0.5m on a bearing of	328°	and mark the location and finish.

Micro navigation – letter T

From S.O.P _ walk	4m on a bearing of	0°	and mark the location.
From PT1 Walk	1.5m on a bearing of	270°	and mark the location.
From PT2 Walk	3m on a bearing of	90°	and mark the location and finish.

Micro navigation – letter t

From S.O.P _ walk	1.5m on a bearing of	180°	and mark the location.
From PT1 Walk	1.5m on a bearing of	90°	and mark the location.
From PT2 Walk	1.5m on a bearing of	270°	.
From PT3 Walk	1.6m on a bearing of	180°	and mark the location.
From PT4 Walk	0.6m on a bearing of	154°	and mark the location.
From PT5 Walk	0.6m on a bearing of	122°	and mark the location.
From PT6 Walk	0.75m on a bearing of	90°	and mark the location.
From PT7 Walk	0.6m on a bearing of	58°	and mark the location.
From PT8 Walk	0.6m on a bearing of	26°	and mark the location and finish.

Micro navigation – letter U

From S.O.P _ walk	3.1m on a bearing of	180°	and mark the location.
From PT1 Walk	0.75m on a bearing of	215°	and mark the location.
From PT2 Walk	0.75m on a bearing of	247°	and mark the location.
From PT3 Walk	0.75m on a bearing of	270°	and mark the location.
From PT4 Walk	0.75m on a bearing of	293°	and mark the location.
From PT5 Walk	0.75m on a bearing of	325°	and mark the location.
From PT6 Walk	3.1m on a bearing of	0°	and mark the location and finish.

Micro navigation – letter u

From S.O.P _ walk	2.7m on a bearing of	180°	and mark the location.
From PT1 Walk	0.9m on a bearing of	0°	and mark the location.
From PT2 Walk	0.6m on a bearing of	206°	and mark the location.
From PT3 Walk	0.6m on a bearing of	238°	and mark the location.
From PT4 Walk	0.75m on a bearing of	270°	and mark the location.
From PT5 Walk	0.6m on a bearing of	302°	and mark the location.
From PT6 Walk	0.6m on a bearing of	334°	and mark the location.
From PT7 Walk	1.8m on a bearing of	0°	and mark the location and finish.

Micro navigation – letter V

From S.O.P _ walk	4.3m on a bearing of	201°	and mark the location.
From PT1 Walk	4.3m on a bearing of	339°	and mark the location and finish.

Micro navigation – letter v

From S.O.P _ walk	2.9m on a bearing of	203°	and mark the location.
From PT1 Walk	2.9m on a bearing of	337°	and mark the location and finish.

Micro navigation – letter W

From S.O.P _ walk	4.1m on a bearing of	193°	and mark the location.
From PT1 Walk	4.1m on a bearing of	347°	and mark the location.
From PT2 Walk	4.1m on a bearing of	193°	and mark the location.
From PT3 Walk	4.1m on a bearing of	347°	and mark the location and finish.

Micro navigation – letter w

Appendix (ix)

From S.O.P _ walk 2.8m on a bearing of 196° and mark the location.
 From PT1 Walk 2.8m on a bearing of 344° and mark the location.
 From PT2 Walk 2.8m on a bearing of 196° and mark the location.
 From PT3 Walk 2.8m on a bearing of 344° and mark the location and finish.

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Micro navigation – letter X

From S.O.P _ walk 5m on a bearing of 37° and mark the location.
 From PT1 Walk 2.5m on a bearing of 217° and mark the location.
 From PT2 Walk 2.5m on a bearing of 323° and mark the location.
 From PT3 Walk 5m on a bearing of 143° and mark the location and finish.

Micro navigation – letter x

From S.O.P _ walk 3.6m on a bearing of 140° and mark the location.
 From PT1 Walk 1.8m on a bearing of 320° and mark the location.
 From PT2 Walk 1.8m on a bearing of 40° and mark the location.
 From PT3 Walk 3.6m on a bearing of 220° and mark the location and finish.

Micro navigation – letter Y

From S.O.P _ walk 2m on a bearing of 0° and mark the location.
 From PT1 Walk 2.5m on a bearing of 323° and mark the location.
 From PT2 Walk 2.5m on a bearing of 143° .
 From PT3 Walk 2.5m on a bearing of 37° and mark the location and finish.

Micro navigation – letter y

From S.O.P _ walk 2.9m on a bearing of 203° and mark the location.
 From PT1 Walk 2.9m on a bearing of 337° and mark the location.
 From PT2 Walk 2.9m on a bearing of 157° .
 From PT3 Walk 1.4m on a bearing of 203° and mark the location.
 From PT4 Walk 0.6m on a bearing of 270° and mark the location and finish.

Micro navigation – letter Z

From S.O.P _ walk 3m on a bearing of 270° and mark the location.
 From PT1 Walk 5m on a bearing of 37° and mark the location.
 From PT2 Walk 3m on a bearing of 270° and mark the location and finish.

Micro navigation – letter z

From S.O.P _ walk 2.3m on a bearing of 270° and mark the location.
 From PT1 Walk 3.5m on a bearing of 40° and mark the location.
 From PT2 Walk 2.3m on a bearing of 270° and mark the location and finish.

Micro navigation – number 1

From S.O.P _ walk 4m on a bearing of 0° and mark the location.
 From PT1 Walk 1.2m on a bearing of 225° and mark the location and finish.

Micro navigation – number 2

From S.O.P _ walk 0.6m on a bearing of 26° and mark the location.
 From PT1 Walk 0.6m on a bearing of 58° and mark the location.
 From PT2 Walk 0.75m on a bearing of 90° and mark the location.
 From PT3 Walk 0.6m on a bearing of 122° and mark the location.
 From PT4 Walk 0.6m on a bearing of 154° and mark the location.
 From PT5 Walk 0.6m on a bearing of 180° and mark the location.
 From PT6 Walk 3.4m on a bearing of 222° and mark the location.
 From PT7 Walk 2.3m on a bearing of 90° and mark the location and finish.

Micro navigation – number 3

Appendix (x)

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From S.O.P _ walk 0.6m on a bearing of 154° and mark the location.
 From PT1 Walk 0.6m on a bearing of 122° and mark the location.
 From PT2 Walk 0.75m on a bearing of 90° and mark the location.
 From PT3 Walk 0.6m on a bearing of 58° and mark the location.
 From PT4 Walk 0.6m on a bearing of 26° and mark the location.
 From PT5 Walk 0.6m on a bearing of 0° and mark the location.
 From PT6 Walk 0.6m on a bearing of 334° and mark the location.
 From PT7 Walk 0.6m on a bearing of 302° and mark the location.
 From PT8 Walk 0.75m on a bearing of 270° and mark the location.
 From PT9 Walk 2.3m on a bearing of 42° and mark the location.
 From PT10 Walk 2.3m on a bearing of 270° and mark the location and finish.

Micro navigation – number 4

From S.O.P _ walk 2.3m on a bearing of 270° and mark the location.
 From PT1 Walk 3.1m on a bearing of 31° and mark the location.
 From PT2 Walk 4m on a bearing of 180° and mark the location and finish.

Micro navigation – number 5

From S.O.P _ walk 1.6m on a bearing of 270° and mark the location.
 From PT1 Walk 2m on a bearing of 192° and mark the location.
 From PT2 Walk 0.6m on a bearing of 58° and mark the location.
 From PT3 Walk 0.75m on a bearing of 90° and mark the location.
 From PT4 Walk 0.6m on a bearing of 122° and mark the location.
 From PT5 Walk 0.6m on a bearing of 154° and mark the location.
 From PT6 Walk 0.6m on a bearing of 180° and mark the location.
 From PT7 Walk 0.6m on a bearing of 206° and mark the location.
 From PT8 Walk 0.6m on a bearing of 238° and mark the location.
 From PT9 Walk 0.75m on a bearing of 270° and mark the location.
 From PT10 Walk 0.6m on a bearing of 302° and mark the location.
 From PT11 Walk 0.6m on a bearing of 334° and mark the location and finish.

Micro navigation – number 6

From S.O.P _ walk 0.5m on a bearing of 328° and mark the location.
 From PT1 Walk 0.6m on a bearing of 302° and mark the location.
 From PT2 Walk 0.6m on a bearing of 270° and mark the location.
 From PT3 Walk 0.6m on a bearing of 238° and mark the location.
 From PT4 Walk 0.5m on a bearing of 212° and mark the location.
 From PT5 Walk 1.8m on a bearing of 185° and mark the location.
 From PT6 Walk 0.6m on a bearing of 180° and mark the location.
 From PT7 Walk 0.6m on a bearing of 154° and mark the location.
 From PT8 Walk 0.6m on a bearing of 122° and mark the location.
 From PT9 Walk 0.75m on a bearing of 90° and mark the location.
 From PT10 Walk 0.6m on a bearing of 58° and mark the location.
 From PT11 Walk 0.6m on a bearing of 26° and mark the location.
 From PT12 Walk 0.6m on a bearing of 0° and mark the location.
 From PT13 Walk 0.6m on a bearing of 334° and mark the location.
 From PT14 Walk 0.6m on a bearing of 302° and mark the location.
 From PT15 Walk 0.75m on a bearing of 270° and mark the location.
 From PT16 Walk 0.6m on a bearing of 238° and mark the location.
 From PT17 Walk 0.6m on a bearing of 206° and finish.

Micro navigation – number 7

From S.O.P _ walk 2.3m on a bearing of 90° and mark the location.
 From PT1 Walk 4.6m on a bearing of 210° and mark the location and finish.

Once you have formulated what you want to write cut out setting out bearings and write sequential numbers in space

Micro navigation – number 8

Appendix (xi)

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From S.O.P _ walk	0.5m on a bearing of	180°	and mark the location.
From PT1 Walk	0.6m on a bearing of	154°	and mark the location.
From PT2 Walk	0.6m on a bearing of	122°	and mark the location.
From PT3 Walk	0.75m on a bearing of	90°	and mark the location.
From PT4 Walk	0.6m on a bearing of	58°	and mark the location.
From PT5 Walk	0.6m on a bearing of	26°	and mark the location.
From PT6 Walk	0.5m on a bearing of	0°	and mark the location.
From PT7 Walk	0.6m on a bearing of	334°	and mark the location.
From PT8 Walk	0.6m on a bearing of	302°	and mark the location.
From PT9 Walk	0.65m on a bearing of	281°	and mark the location.
From PT10 Walk	0.45m on a bearing of	304°	and mark the location.
From PT11 Walk	0.45m on a bearing of	334°	and mark the location.
From PT12 Walk	0.35m on a bearing of	0°	and mark the location.
From PT13 Walk	0.45m on a bearing of	26°	and mark the location.
From PT14 Walk	0.45m on a bearing of	56°	and mark the location.
From PT15 Walk	0.5m on a bearing of	90°	and mark the location.
From PT16 Walk	0.45m on a bearing of	124°	and mark the location.
From PT17 Walk	0.45m on a bearing of	154°	and mark the location.
From PT18 Walk	0.35m on a bearing of	180°	and mark the location.
From PT19 Walk	0.45m on a bearing of	206°	and mark the location.
From PT20 Walk	0.45m on a bearing of	236°	and mark the location.
From PT21 Walk	0.65m on a bearing of	259°	and mark the location.
From PT22 Walk	0.6m on a bearing of	238°	and mark the location.
From PT23 Walk	0.6m on a bearing of	206°	and finish.

Micro navigation – number 9

From S.O.P _ walk	0.5m on a bearing of	148°	and mark the location.
From PT1 Walk	0.6m on a bearing of	122°	and mark the location.
From PT2 Walk	0.6m on a bearing of	90°	and mark the location.
From PT3 Walk	0.6m on a bearing of	58°	and mark the location.
From PT4 Walk	0.5m on a bearing of	32°	and mark the location.
From PT5 Walk	1.8m on a bearing of	5°	and mark the location.
From PT6 Walk	0.6m on a bearing of	0°	and mark the location.
From PT7 Walk	0.6m on a bearing of	334°	and mark the location.
From PT8 Walk	0.6m on a bearing of	302°	and mark the location.
From PT9 Walk	0.75m on a bearing of	270°	and mark the location.
From PT10 Walk	0.6m on a bearing of	238°	and mark the location.
From PT11 Walk	0.6m on a bearing of	206°	and mark the location.
From PT12 Walk	0.6m on a bearing of	180°	and mark the location.
From PT13 Walk	0.6m on a bearing of	154°	and mark the location.
From PT14 Walk	0.6m on a bearing of	122°	and mark the location.
From PT15 Walk	0.75m on a bearing of	90°	and mark the location.
From PT16 Walk	0.6m on a bearing of	58°	and mark the location.
From PT17 Walk	0.6m on a bearing of	26°	and finish.

Micro navigation – number 0

From S.O.P _ walk	2m on a bearing of	180°	and mark the location.
From PT1 Walk	0.75m on a bearing of	159°	and mark the location.
From PT2 Walk	0.6m on a bearing of	122°	and mark the location.
From PT3 Walk	0.75m on a bearing of	90°	and mark the location.
From PT4 Walk	0.6m on a bearing of	58°	and mark the location.
From PT5 Walk	0.75m on a bearing of	21°	and mark the location.
From PT6 Walk	2m on a bearing of	0°	and mark the location.
From PT7 Walk	0.75m on a bearing of	339°	and mark the location.
From PT8 Walk	0.6m on a bearing of	302°	and mark the location.
From PT9 Walk	0.75m on a bearing of	270°	and mark the location.
From PT10 Walk	0.6m on a bearing of	238°	and mark the location.
From PT11 Walk	0.75m on a bearing of	201°	and finish.

